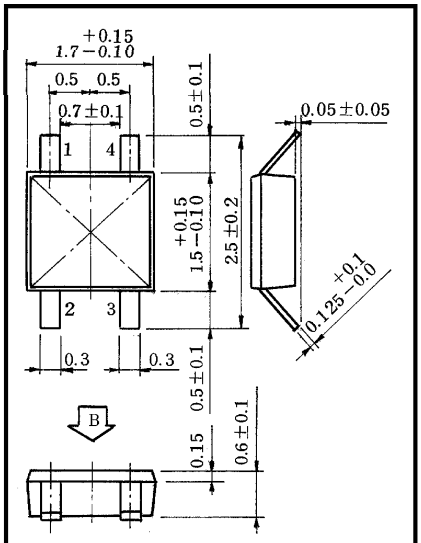
TOSHIBA HALL SENSOR GaAs ION IMPLANTED PLANAR TYPE

THS129

HIGH STABILITY MOTOR CONTROL.
DIGITAL TACHOMETER.

- High Internal Resistance. : R_d = 2kΩ (Typ.)
- Super Small Package.
- Wide Operating Temperature Range. (; −55~125°C)
- Excellent Output Voltage Linearity.

Unit in mm



1 (+) −3 (−) (INPUT)
2 (+) −4 (−) (OUTPUT)

JEDEC	—
EIAJ	—
TOSHIBA	10-2A1A

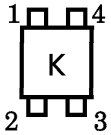
Weight : 0.0047g

MAXIMUM RATINGS (Ta = 25°C)

CHARACTERISTIC	SYMBOL	RAITING	UNIT
Control Voltage	V_C	6**	V
Power Dissipation	P_D	150**	mW
Operating Temperature Range	T_{opr}	−55~125	°C
Storage Temperature Range	T_{stg}	−55~150	°C

** Mounted on a printed circuit board.

Marking



ELECTRICAL CHARACTERISTICS (Ta = 25°C)

CHARACTERISTIC	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Internal Resistance (Input)	R_d	I_C = 1mA	1.6	2.0	2.4	kΩ
Residual Voltage Ratio	V_{HO}/V_H	V_C = 5V, B = 0 / B = 0.1T	—	—	±10	%
Hall Voltage (Note 1)	V_H	V_C = 5V, B = 0.1T	130	150	170	mV
Temperature Coefficient (Note 2)	V_{HT}	I_C = 1mA, B = 0.1T, T1 = 25°C T2 = 125°C	—	—	−0.06	%/°C
Linearity (Note 3)	ΔK_H	V_C = 5V, B1 = 0.05T, B2 = 0.1T	—	—	2	%
Specific Sensitivity (Note 4)	K*	V_C = 5V, B = 0.1T	—	30	—	$\times 10^{-2}$/T
Internal Resistance (Output)	R_{OUT}	I_C = 0.5mA	4.2	6.0	7.8	kΩ

Note 1 : $V_H = V_{HM} - V_{HO}$ (V_{HM} is meter indication)

Note 2 : $V_{HT} = \frac{1}{V_{H(T1)}} \cdot \frac{V_{H(T2)} - V_{H(T1)}}{T2 - T1} \times 100\ (\%/°C)$

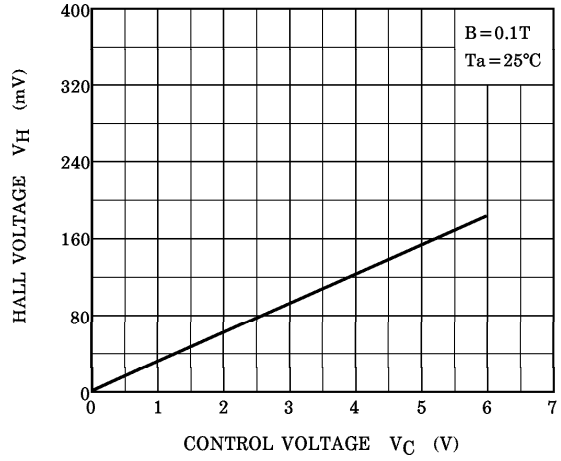
Note 3 : $\Delta K_H = \frac{K_{H(B2)} - K_{H(B1)}}{1/2\{K_{H(B1)} + K_{H(B2)}\}} \times 100\ (\%)$, $K_H = \frac{V_H}{I_C \cdot B}$

Note 4 : $K^* = V_H / (R_d \times I_C \times B) = K_H / R_d$

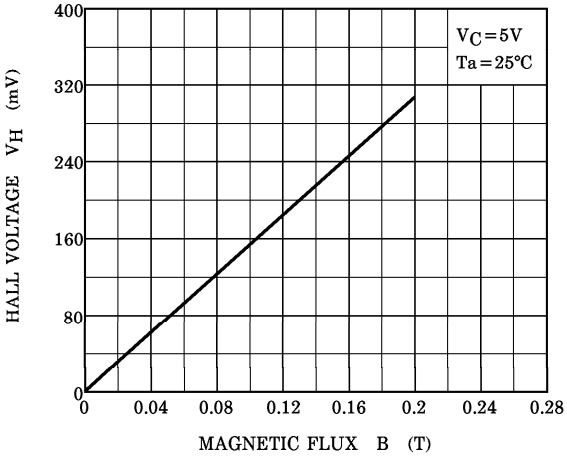
V_{HO} : Residual Voltage

K_H : Product Sensitivity

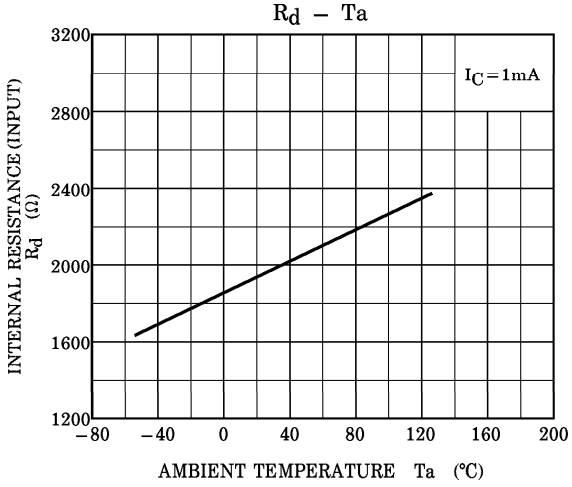
V_H – V_C



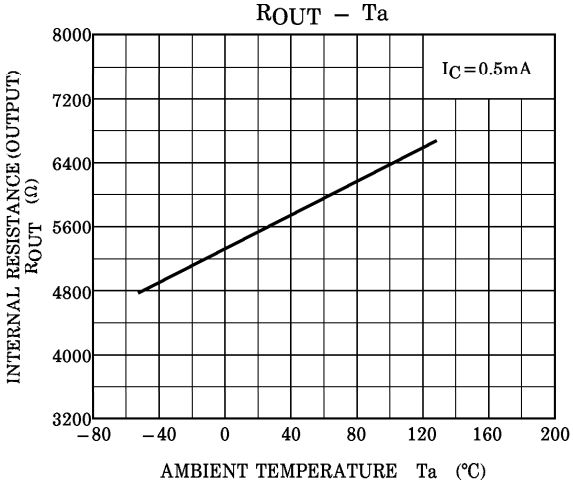
V_H – B



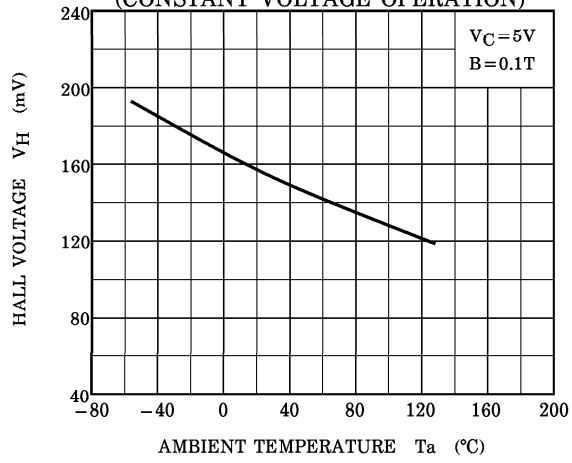
R_d – Ta



R_{OUT} – Ta



V_H – Ta
(CONSTANT VOLTAGE OPERATION)



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