

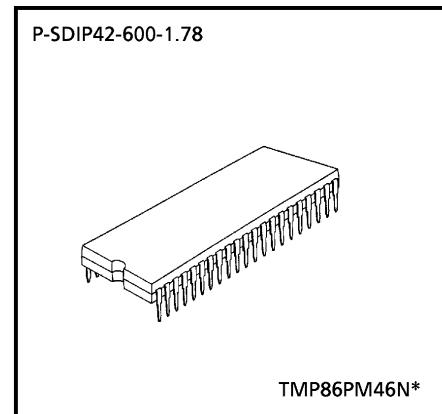
CMOS 8-Bit Microcontroller

TMP86PM46N

The TMP86PM46 is a OTP type MCU which includes 32 Kbyte One-time PROM. It is a pin compatible with a mask ROM product of the TMP86C846/H46/M46. Writing the program to built-in PROM, the TMP86PM46 operates as the same way as the TMP86C846/H46/M46. Using the Adapter socket, you can write and verify the data for the TMP86PM46 with a general-purpose PROM programmer same as TC57100D/AD.

Product No.	OTP	RAM	Package	Adapter Socket
TMP86PM46N*	32 K × 8 bits	1 K × 8 bits	P-SDIP42-600-1.78	BM11188

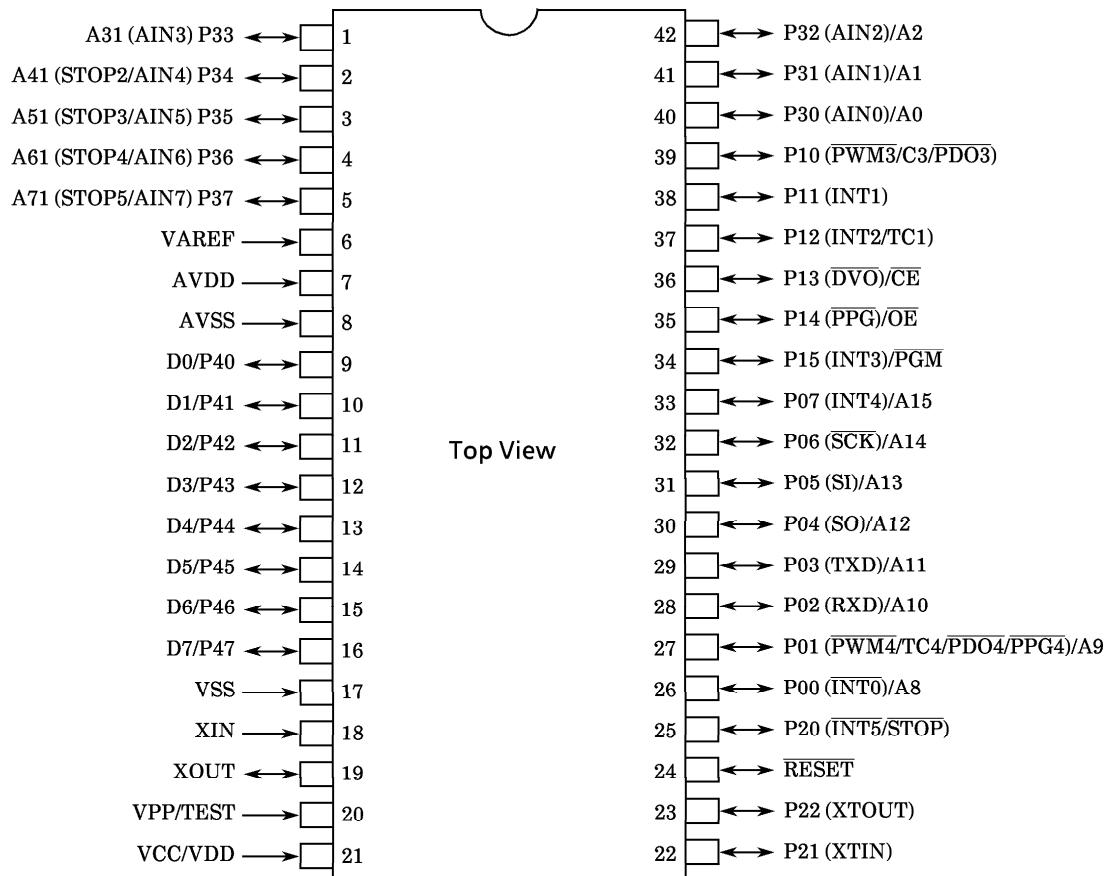
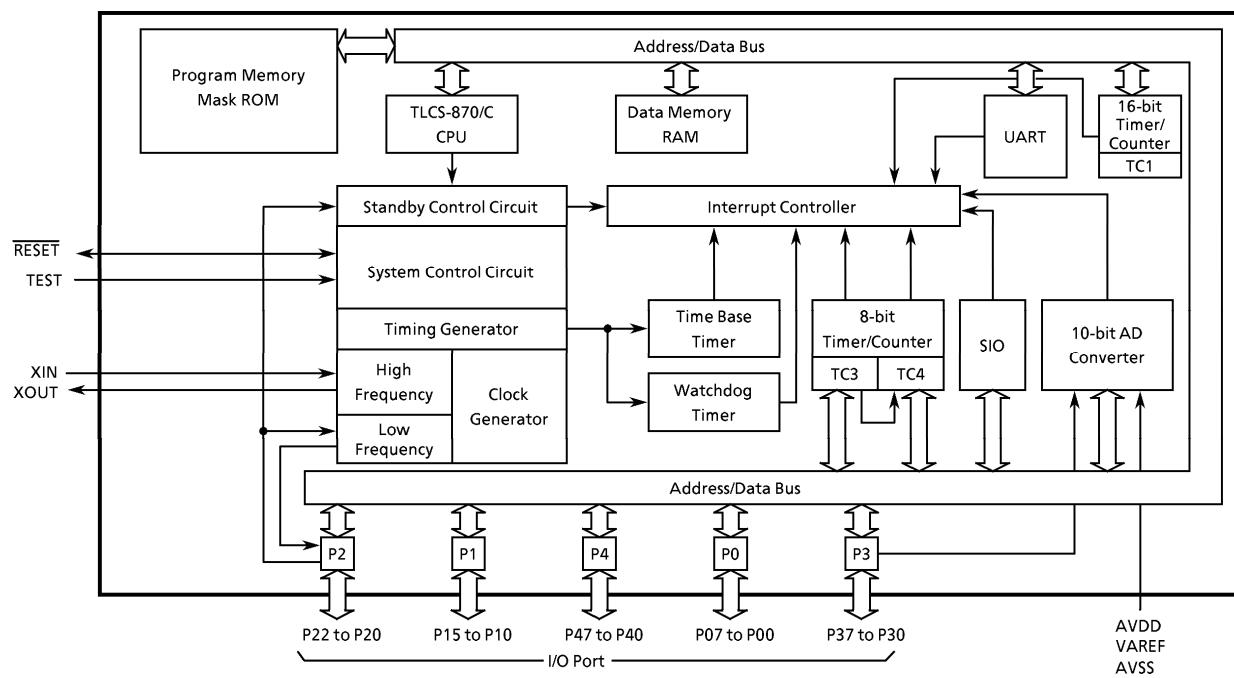
* Under development



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P-SDIP42-600-1.78

**Block Diagram**

Pin Function

The TMP86PM46 has MCU mode and PROM mode.

(1) MCU mode

In the MCU mode, the TMP86PM46 is a pin compatible with the TMP86C846/H46/M46 (Make sure to fix the TEST pin to low level).

(2) PROM mode

Pin Name	Input/Output	Functions	Pin Name (MCU mode)
A15 to A8 A7 to A0	Input	Input of Memory address for program	P07 to P00 P37 to P30
D7 to D0	I/O	Input/Output of Memory data for program	P47 to P40
CE	Input	Chip enable	P13
OE		Output enable	P14
PGM		Program control	P15
VPP	Power supply	+ 12.75 V/5 V (Power supply of program)	TEST
VCC, AVDD		+ 6.25 V/5 V	VDD, AVDD
GND, VAREF, AVSS		0 V	VSS, VAREF, AVSS
P11, P21	I/O	PROM mode setting pin. Fix to high.	
P10, P12, P22, P20 RESET		PROM mode setting pin. Fix to low.	
XIN XOUT	Input Output	Self oscillation with resonator (8 MHz).	

Note: No pin is applied to A16 input.

Operation

This section describes the functions and basic operational blocks of TMP86PM46.

The TMP86PM46 has PROM in place of the mask ROM which is included in the TMP86C846/H46/M46.

The configuration and function are the same as the TMP86C846/H46/M46. For the functions of TMP86PM47 in details, see the section of TMP86C846/H46/M46.

1. Operating Mode

The TMP86PM46 has MCU mode and PROM mode.

1.1 MCU Mode

The MCU mode is set by fixing the TEST/VPP pin to the low level.

In the MCU mode, the operation is the same as the TMP86C846/H46/M46 (TEST/VPP pin cannot be used open because it has no built-in pull-down resister).

1.1.1 Program memory

The TMP86PM46 has a 32-Kbyte built-in one time PROM (addresses 8000 to FFFF_H in the MCU mode, addresses 0000 to 7FFF_H in the PROM mode).

When using TMP86PM46 for evaluation of TMP86C846/H46/M46, the program is written in the program storing area shown in Figure 1-1.

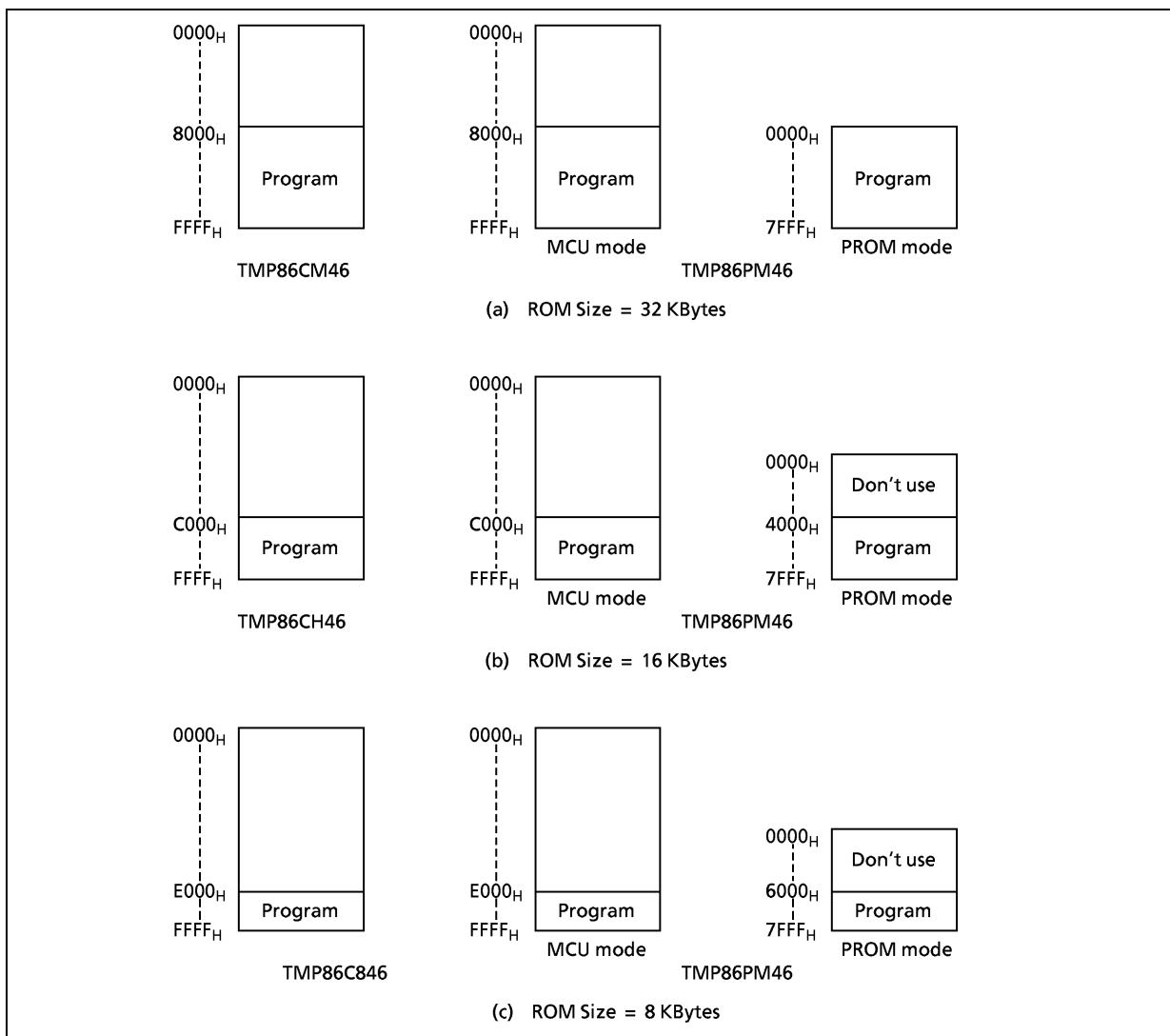


Figure 1-1. Program Memory Area

Note: The area that is not in use should be set data to FFH, or a general-purpose PROM programmer should be set only in the program memory area to access.

Electrical Characteristics

Absolute Maximum Ratings	($V_{SS} = 0$ V)
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Parameter	Symbol	Pins	Rating	Unit
Supply Voltage	V_{DD}		- 0.3 to 6.5	
Program Voltage	V_{PP}	TEST/ V_{PP}	- 0.3 to 13.0	
Input Voltage	V_{IN}		- 0.3 to $V_{DD} + 0.3$	
Output Voltage	V_{OUT1}	P21, P22, RESET, Tri-state Port	- 0.3 to $V_{DD} + 0.3$	
	I_{OUT1}	P1, P3, P4 Port	- 1.8	
Output Current (Per 1 pin)	I_{OUT2}	P1, P3 Port	3.2	
	I_{OUT3}	P0, P2, P4 Port	30	
	ΣI_{OUT1}	P1, P3 Port	60	
Output Current (Total)	ΣI_{OUT2}	P0, P2, P4 Port	80	
	PD		250	mW
Soldering Temperature (time)	Tsld		260 (10 s)	
Storage Temperature	Tstg		- 55 to 125	°C
Operating Temperature	Topr		- 40 to 85	

Note: The absolute maximum ratings are rated values which must not be exceeded during operation, even for an instant. Any one of the ratings must not be exceeded. If any absolute maximum rating is exceeded, a device may break down or its performance may be degraded, causing it to catch fire or explode resulting in injury to the user. Thus, when designing products which include this device, ensure that no absolute maximum rating value will ever be exceeded.

Recommended Operating Condition
($V_{SS} = 0 \text{ V}$, $T_{opr} = -40 \text{ to } 85^\circ\text{C}$)

Parameter	Symbol	Pins	Condition	Min	Max	Unit	
Supply Voltage	V_{DD}		$f_c = 16 \text{ MHz}$	NORMAL1, 2 mode	4.5	V	
				IDLE0, 1, 2 mode			
			$f_c = 8 \text{ MHz}$	NORMAL1, 2 mode	2.7		
				IDLE0, 1, 2 mode			
			$f_c = 4.2 \text{ MHz}$	NORMAL1, 2 mode	1.8		
				IDLE0, 1, 2 mode			
Input high Level	V_{IH1}	Except Hysteresis input	$V_{DD} \geq 4.5 \text{ V}$	$V_{DD} \times 0.70$	V_{DD}		
				$V_{DD} \times 0.75$			
			$V_{DD} < 4.5 \text{ V}$	$V_{DD} \times 0.90$			
Input low Level	V_{IL1}	Except Hysteresis input	$V_{DD} \geq 4.5 \text{ V}$	0	$V_{DD} \times 0.30$		
			$V_{DD} < 4.5 \text{ V}$				
Clock Frequency	f_c	XIN, XOUT	$V_{DD} = 1.8 \text{ to } 5.5 \text{ V}$	1.0	4.2	MHz	
			$V_{DD} = 2.7 \text{ to } 5.5 \text{ V}$				
			$V_{DD} = 4.5 \text{ to } 5.5 \text{ V}$				
	f_s	XTIN, XTOUT		30.0	34.0	kHz	

Note: The recommended operating conditions for a device are operating conditions under which it can be guaranteed that the device will operate as specified. If the device is used under operating conditions other than the recommended operating conditions (supply voltage, operating temperature range, specified AC/DC values etc.), malfunction may occur. Thus, when designing products which include this device, ensure that the recommended operating conditions for the device are always adhered to.

DC Characteristics

(V_{SS} = 0 V, Topr = -40 to 85°C)

Parameter	Symbol	Pins	Condition	Min	Typ.	Max	Unit
Hysteresis Voltage	V _{HS}	Hysteresis input		-	0.9	-	V
Input Current	I _{IN1}	TEST	V _{DD} = 5.5 V, V _{IN} = 5.5 V/0 V	-	-	± 2	μA
	I _{IN2}	Sink Open-drain, Tri-state					
	I _{IN3}	RESET, STOP					
Input Resistance	R _{IN2}	RESET Pull-Up		100	220	450	kΩ
Output Leakage Current	I _{LO1}	Sink Open-drain	V _{DD} = 5.5 V, V _{OUT} = 5.5 V	-	-	2	μA
	I _{LO2}	Tri-state	V _{DD} = 5.5 V, V _{OUT} = 5.5 V/0 V	-	-	± 2	
Output High Voltage	V _{OH1}	Tri-state Port	V _{DD} = 4.5 V, I _{OH} = -0.7 mA	4.1	-	-	V
Output Low Voltage	V _{OL}	Except XOUT and P0, P2, P4 Port	V _{DD} = 4.5 V, I _{OL} = 1.6mA	-	-	0.4	
Output Low Current	I _{OL}	High Current Port (P0, P2, P4 Port)	V _{DD} = 4.5 V, V _{OL} = 1.0 V	-	20	-	
Supply Current in NORMAL 1, 2 mode	V _{DD}		V _{DD} = 5.5 V V _{IN} = 5.3/0.2 V f _C = 16 MHz f _S = 32.768 kHz	-	7.5	9	mA
Supply Current in IDLE 0, 1, 2 mode				-	5.5	6.5	
Supply Current in SLOW 1 mode			V _{DD} = 3.0 V V _{IN} = 2.8 V/0.2 V f _S = 32.768 kHz	-	18	42	
Supply Current in SLEEP 1 mode				-	16	25	
Supply Current in SLEEP 0 mode				-	12	20	μA
Supply Current in STOP mode			V _{DD} = 5.5 V V _{IN} = 5.3 V/0.2 V	-	0.5	10	

Note 1: Typical values show those at Topr = 25°C, V_{DD} = 5 VNote 2: Input current (I_{IN1}, I_{IN2}); The current through pull-up or pull-down resistor is not included.Note 3: I_{DD} does not include I_{REF} current.

Note 4: The supply currents of SLOW 2 and SLEEP 2 modes are equivalent to IDLE 0, 1, 2.

AD Conversion Characteristics

(V_{SS} = 0.0 V, 4.5 V ≤ V_{DD} ≤ 5.5 V, Topr = -40 to 85°C)

Parameter	Symbol	Condition	Min	Typ.	Max	Unit
Analog Reference Voltage	V _{AREF}		A _{VDD} - 1.0	-	A _{VDD}	V
Power Supply Voltage of Analog Control Circuit	A _{VDD}			V _{DD}		
Analog Reference Voltage Range (Note 4)	△V _{AREF}		3.5	-	-	
Analog Input Voltage	V _{AIN}		V _{SS}	-	V _{AREF}	
Power Supply Current of Analog Reference Voltage	I _{REF}	V _{DD} = A _{VDD} = V _{AREF} = 5.5 V V _{SS} = AVSS = 0.0 V	-	0.6	1.0	mA
Non linearity Error		V _{DD} = A _{VDD} = 5.0 V, V _{SS} = AVSS = 0.0 V V _{AREF} = 5.0 V	-	-	± 2	LSB
Zero Point Error			-	-	± 2	
Full Scale Error			-	-	± 2	
Total Error			-	-	± 2	

(V_{SS} = 0.0 V, 2.7 V ≤ V_{DD} < 4.5 V, Topr = -40 to 85°C)

Parameter	Symbol	Condition	Min	Typ.	Max	Unit
Analog Reference Voltage	V _{AREF}		A _{VDD} - 1.0	-	A _{VDD}	V
Power Supply Voltage of Analog Control Circuit	A _{VDD}			V _{DD}		
Analog Reference Voltage Range (Note 4)	△V _{AREF}		2.5	-	-	
Analog Input Voltage	V _{AIN}		V _{SS}	-	V _{AREF}	
Power Supply Current of Analog Reference Voltage	I _{REF}	V _{DD} = A _{VDD} = V _{AREF} = 4.5 V V _{SS} = AVSS = 0.0 V	-	0.5	0.8	mA
Non linearity Error		V _{DD} = A _{VDD} = 2.7 V, V _{SS} = AVSS = 0.0 V V _{AREF} = 2.7 V	-	-	± 2	LSB
Zero Point Error			-	-	± 2	
Full Scale Error			-	-	± 2	
Total Error			-	-	± 2	

(V_{SS} = 0.0 V, 2.0 V ≤ V_{DD} < 2.7 V, Topr = -40 to 85°C) Note 5(V_{SS} = 0.0 V, 1.8 V ≤ V_{DD} < 2.0 V, Topr = -10 to 85°C) Note 5

Parameter	Symbol	Condition	Min	Typ.	Max	Unit
Analog Reference Voltage	V _{AREF}		A _{VDD} - 0.9	-	A _{VDD}	V
Power Supply Voltage of Analog Control Circuit	A _{VDD}			V _{DD}		
Analog Reference Voltage Range (Note 4)	△V _{AREF}	1.8 V ≤ V _{DD} < 2.0 V	1.8	-	-	LSB
		2.0 V ≤ V _{DD} < 2.7 V	2.0	-	-	
Analog Input Voltage	V _{AIN}		V _{SS}	-	V _{AREF}	
Power Supply Current of Analog Reference Voltage	I _{REF}	V _{DD} = A _{VDD} = V _{AREF} = 2.7 V V _{SS} = AVSS = 0.0 V	-	0.3	0.5	
Non linearity Error		V _{DD} = A _{VDD} = 1.8 V, V _{SS} = AVSS = 0.0 V V _{AREF} = 1.8 V	-	-	± 4	
Zero Point Error			-	-	± 4	
Full Scale Error			-	-	± 4	
Total Error			-	-	± 4	

Note 1: The total error includes all errors except a quantization error, and is defined as a maximum deviation from the ideal conversion line.

Note 2: Conversion time is different in recommended value by power supply voltage.

Note 3: Please use input voltage to AIN input Pin in limit of V_{AREF} - V_{SS}.

When voltage of range outside is input, conversion value becomes unsettled and gives affect to other channel conversion value.

Note 4: Analog Reference Voltage Range: △V_{AREF} = V_{AREF} - V_{SS}Note 5: When AD is used with V_{DD} < 2.7 V, the guaranteed temperature range varies with the operating voltage.

AC Characteristics

(V_{SS} = 0 V, V_{DD} = 4.5 to 5.5 V, Topr = -40 to 85°C)

Parameter	Symbol	Condition	Min	Typ.	Max	Unit	
Machine Cycle Time	tcy	NORMAL 1, 2 mode	0.25	–	4	μs	
		IDLE 0, 1, 2 mode					
		SLOW 1, 2 mode	117.6	–	133.3		
		SLEEP 0, 1, 2 mode					
High Level Clock Pulse Width	t _{wcH}	For external clock operation (XIN input) fc = 16 MHz	–	31.25	–	ns	
Low Level Clock Pulse Width	t _{wcL}						
High Level Clock Pulse Width	t _{wcH}	For external clock operation (XTIN input) fc = 32.768 kHz	–	15.26	–	μs	
Low Level Clock Pulse Width	t _{wcL}						

(V_{SS} = 0 V, V_{DD} = 2.7 to 4.5 V, Topr = -40 to 85°C)

Parameter	Symbol	Condition	Min	Typ.	Max	Unit	
Machine Cycle Time	tcy	NORMAL 1, 2 mode	0.5	–	4	μs	
		IDLE 0, 1, 2 mode					
		SLOW 1, 2 mode	117.6	–	133.3		
		SLEEP 0, 1, 2 mode					
High Level Clock Pulse Width	t _{wcH}	For external clock operation (XIN input) fc = 8 MHz	–	62.5	–	ns	
Low Level Clock Pulse Width	t _{wcL}						
High Level Clock Pulse Width	t _{wcH}	For external clock operation (XTIN input) fc = 32.768 kHz	–	15.26	–	μs	
Low Level Clock Pulse Width	t _{wcL}						

(V_{SS} = 0 V, V_{DD} = 1.8 to 2.7 V, Topr = -40 to 85°C)

Parameter	Symbol	Condition	Min	Typ.	Max	Unit	
Machine Cycle Time	tcy	NORMAL 1, 2 mode	0.95	–	4	μs	
		IDLE 0, 1, 2 mode					
		SLOW 1, 2 mode	117.6	–	133.3		
		SLEEP 0, 1, 2 mode					
High Level Clock Pulse Width	t _{wcH}	For external clock operation (XIN input) fc = 4.2 MHz	–	119.05	–	ns	
Low Level Clock Pulse Width	t _{wcL}						
High Level Clock Pulse Width	t _{wcH}	For external clock operation (XTIN input) fc = 32.768 kHz	–	15.26	–	μs	
Low Level Clock Pulse Width	t _{wcL}						

Recommended Oscillating Conditions - 1

(V_{SS} = 0 V, V_{DD} = 4.5 to 5.5 V, Topr = -40 to 85°C)

PARAMETER	Oscillator	Oscillation Frequency	Recommended Oscillator	Recommended Constant	
				C ₁	C ₂
High-frequency Oscillation	Ceramic Resonator	16 MHz	MURATA CSA16.00MXZ040	10 pF	10 pF
		8 MHz	MURATA CSA8.00MTZ CST8.00MTW	30 pF 30 pF (built-in)	30 pF 30 pF (built-in)
		4.19 MHz	MURATA CSA4.19MG CST4.19MGW	30 pF 30 pF (built-in)	30 pF 30 pF (built-in)
Low-frequency Oscillation	Crystal Oscillator	32.768 kHz	SII VT-200	6 pF	6 pF

Recommended Oscillating Conditions - 2

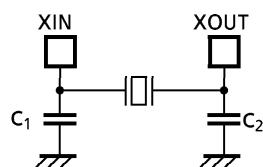
(V_{SS} = 0 V, V_{DD} = 2.7 to 5.5 V, Topr = -40 to 85°C)

PARAMETER	Oscillator	Oscillation Frequency	Recommended Oscillator	Recommended Constant	
				C ₁	C ₂
High-frequency Oscillation	Ceramic Resonator	8 MHz	MURATA CSA8.00MTZ CST8.00MTW	30 pF 30 pF (built-in)	30 pF 30 pF (built-in)
		4.19 MHz	MURATA CSA4.19MG CST4.19MGW	30 pF 30 pF (built-in)	30 pF 30 pF (built-in)

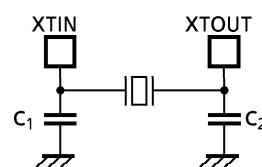
Recommended Oscillating Conditions - 3

(V_{SS} = 0 V, V_{DD} = 1.8 to 5.5 V, Topr = -40 to 85°C)

PARAMETER	Oscillator	Oscillation Frequency	Recommended Oscillator	Recommended Constant	
				C ₁	C ₂
High-frequency Oscillation	Ceramic Resonator	4.19 MHz	MURATA CSA4.19MG CST4.19MGW	30 pF 30 pF (built-in)	30 pF 30 pF (built-in)



(1) High-frequency Oscillation



(2) Low-frequency Oscillation

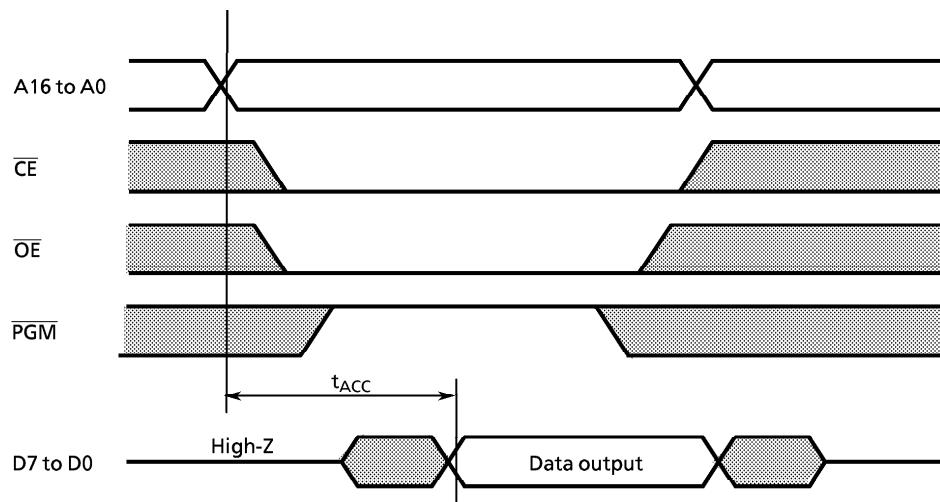
- Note 1: An electrical shield by metal shield plate on the surface of IC package is recommended in order to protect the device from the high electric field stress applied from CRT (Cathodic Ray Tube) for continuous reliable operation.
- Note 2: The product numbers and specifications of the resonators by Murata Manufacturing Co., Ltd. are subject to change. For up-to-date information, please refer to the following URL;
<http://www.murata.co.jp/search/index.html>

DC Characteristics, AC Characteristics (PROM Mode) ($V_{SS} = 0 \text{ V}$, $T_{opr} = -40 \text{ to } 85^\circ\text{C}$)

(1) Read operation in PROM mode

Note: $t_{cyc} = 500 \text{ ns}$ at 8 MHz

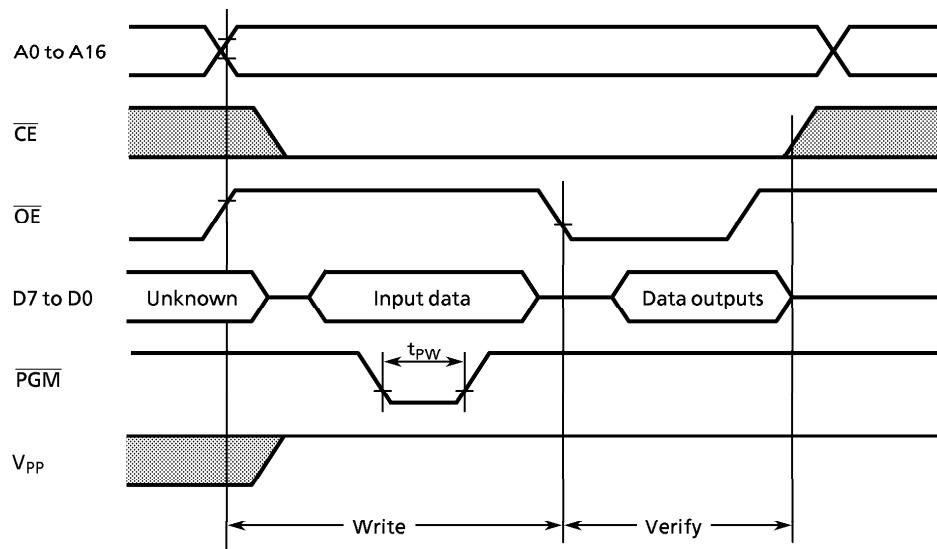
Parameter	Symbol	Conditions	Min	Typ.	Max	Unit
High level input voltage (TTL)	V_{IH4}	$V_{CC} = 5.0 \pm 0.25 \text{ V}$	2.2	-	V_{CC}	V
Low level input voltage (TTL)	V_{IL4}		0	-	0.8	
Power supply	V_{CC}		4.75	5.0	5.25	
Power supply of program	V_{PP}		-	1.5t _{cyc} + 300	-	ns
Address access time	t_{ACC}		-	-	-	-



(2) Program operation (High-speed) (Topr = 25 ± 5°C)

Parameter	Symbol	Conditions	Min	Typ.	Max	Unit
High level input voltage (TTL)	V _{IH4}		2.2	-	V _{CC}	V
Low level input voltage (TTL)	V _{IL4}		0	-	0.8	
Power supply	V _{CC}		6.0	6.25	6.5	
Power supply of program	V _{PP}		12.5	12.75	13.0	
Pulse width of initializing program	t _{PW}	V _{CC} = 6.0 V	0.095	0.1	0.105	ms

High-speed program writing



Note 1: The power supply of V_{PP} (12.75 V) must be set power-on at the same time or the later time for a power supply of V_{CC} and must be clear power-on at the same time or early time for a power supply of V_{CC}.

Note2 : The pulling up/down device on the condition of V_{PP} = 12.75 V ± 0.25 V causes a damage for the device. Do not pull up/down at programming.

Note3 : Use the recommended adapter (see 1.2.2 (1)) and mode (see 1.2.2 (3) i). Using other than the above condition may cause the trouble of the writing.