

Nonvolatile Memory 8-Kbit E²PROM with I²C Bus Interface

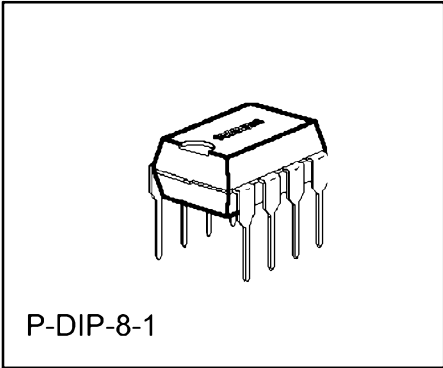
SDA 2586-5

Preliminary Data

MOS IC

Features

- Word-organized, reprogrammable nonvolatile memory in n-channel floating-gate technology (E²PROM)
- 1024 × 8-bit organization
- Supply voltage 5 V
- Serial 2-line bus for data input and output (I²C Bus)
- Reprogramming mode, 10 ms erase / write cycle
- Reprogramming by means of on-chip control (without external control)
- The end of the programming cycle can be checked
- Data retention in excess of 10 years
- More than 10⁴ reprogramming cycles per address



| Type | Ordering Code | Package |
|------------|---------------|-----------|
| SDA 2586-5 | Q67100-H5101 | P-DIP-8-1 |

Circuit Description

I²C Bus Interface

The I²C Bus is a bidirectional 2-line bus for the transfer of data between various integrated circuits. It consists of a data line SDA and a clock line SCL. The data line requires an external pull-up resistor to V_{CC} (open drain output stages).

The possible operational states of the I²C Bus are shown in **figure 1**. In the quiescent state, both lines SDA and SCL are high, i.e. the output stages are disabled. As long as SCL remains "1", information changes on the data bus indicate the start or the end of a data transfer between two components. The transition on SDA from "1" to "0" is a start condition, the transition from "0" to "1" a stop condition. During a data transfer, the information on the data bus will only change when the clock line SCL is "0". The information on SDA is valid as long as SCL is "1".

In conjunction with an I²C Bus system, the device can operate as a receiver, and as a transmitter (slave receiver/listener, or slave transmitter/talker). Between a start and a stop condition, the information is always transmitted in byte-organized form. Between the falling edge of the eighth transmission pulse and a ninth acknowledge clock pulse, the device sets the SDA-line to low as a reception confirmation, if the chip select conditions have been met. During the output of data, the data output of the memory becomes high in impedance during the ninth clock pulse (acknowledge master).

The signal timing required for the operation of the I²C Bus is summarized in **figure 2**.

Control Functions of the I²C Bus

The device is controlled by the controller (master) via the I²C Bus in two operating modes: read cycle, and reprogramming cycle, including erase and write to a memory address. In both operating modes, the controller, as transmitter, has to provide 3 bytes to the bus after the start condition. Each byte has to be followed by an acknowledge bit. During a memory read, at least eight additional clock pulses are required to accept the data from the memory, before the stop condition may follow. In the programming instance, the active programming process is only started by the stop condition after data input, **see figure 3**.

The chip select word includes the chip select bit CS. Thus it is possible to parallel two memory devices. Chip select is obtained when the control bits logically correspond to the condition selected at the select input CS. The two most significant bits A8 and A9 are inputs with the chip select words CS/E.

Checking the End of the Programming Cycle and Breaking off the Programming Cycle

Addressing the chip by the input of CS/E during active reprogramming terminates the programming cycle. If the chip is addressed by entering CS/A, this will be ignored. Only when the programming cycle has terminated will the chip react on CS/A. With this procedure the end of the programming cycle can be checked, **see figure 3**.

Memory Read

After the input of the two control words CS/E and WA, the resetting of the start condition and the input of a third control word CS/A, the memory is set ready to read. During acknowledge clock No. 9, the memory information is transferred in parallel to the internal data register. Subsequent to the falling edge of the acknowledge clock the data output is low-impedance and the first data bit can be sampled, **see figure 4**. With each shift clock, an additional bit reaches the output. After reading a byte, the internal address counter is automatically incremented through the master receiver acknowledge, so that any number of memory locations can be read one after the other. At address 1024, an overflow to address 0 is initiated. With the stop condition, the data output returns to high-impedance mode. The internal sequence control of the memory component is reset from the read to the quiescent state with the stop condition.

Memory Reprogramming

The reprogramming cycle of a memory word comprises an erase and a subsequent write process. During erase, all eight bits of the selected word are set into "1" state. During the write process, "0" states are generated according to the information in the internal data register, i.e. according to the third input control word.

After the 27th and the last clock of the control word input, the active programming process is started by the stop condition. The active programming process is executed under on-chip control and can be terminated by addressing the device via SCL and SDA.

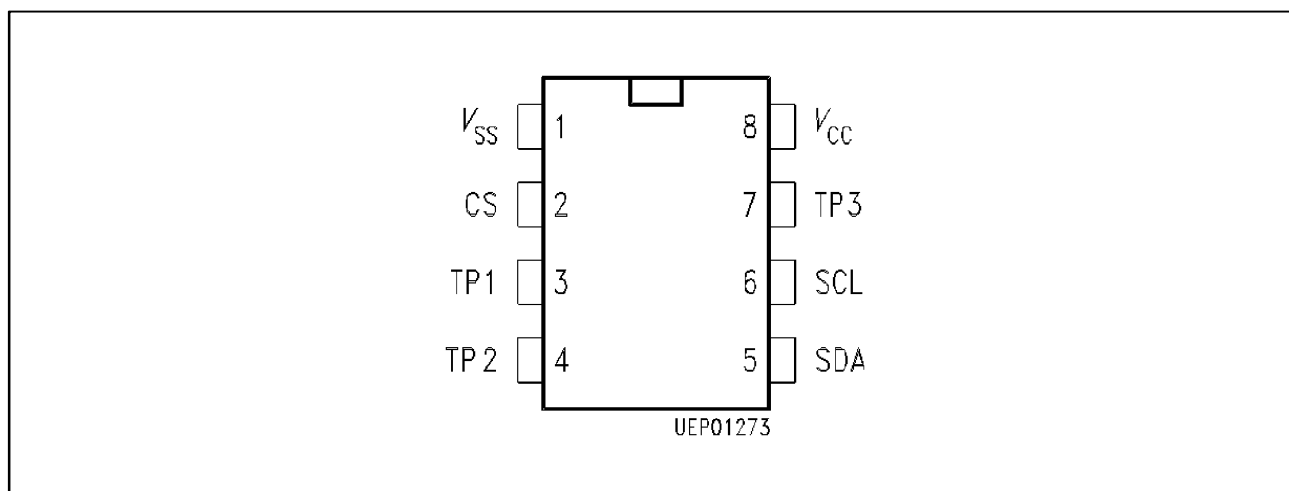
The time required for reprogramming depends on component deviation and data patterns. Therefore, with rated supply voltage the erase/write process is max. 20 ms, or typically, 10 ms. For the input of a data word without write request (write request is defined as data bit in the data register set to "0"), the write process is suppressed and the programming time is shortened. During a subsequent programming of an already erased memory address, the erase process is suppressed again, so that the reprogramming time is also shortened.

Switch-On and Chip Reset

After the supply voltage V_{CC} has been connected, the data output will be in the high impedance mode. As a rule, the first operating mode to be entered should be the read process of a word address. Subsequent to the data output and to the stop condition, the internal control logic is reset. In the case of a subsequent active programming operation, however, the stop condition will not reset the control logic.

Chip Erase

To erase the entire memory the control word CS/E is entered, the address register is loaded with address 0 and the data register with FF (hex), respectively. Immediately prior to generating the stop condition, the input TP2 is connected from 0 to 5 V. The subsequent stop condition initiates the chip erase. As soon as the erase procedure has terminated, TP2 is again connected to 0 V.

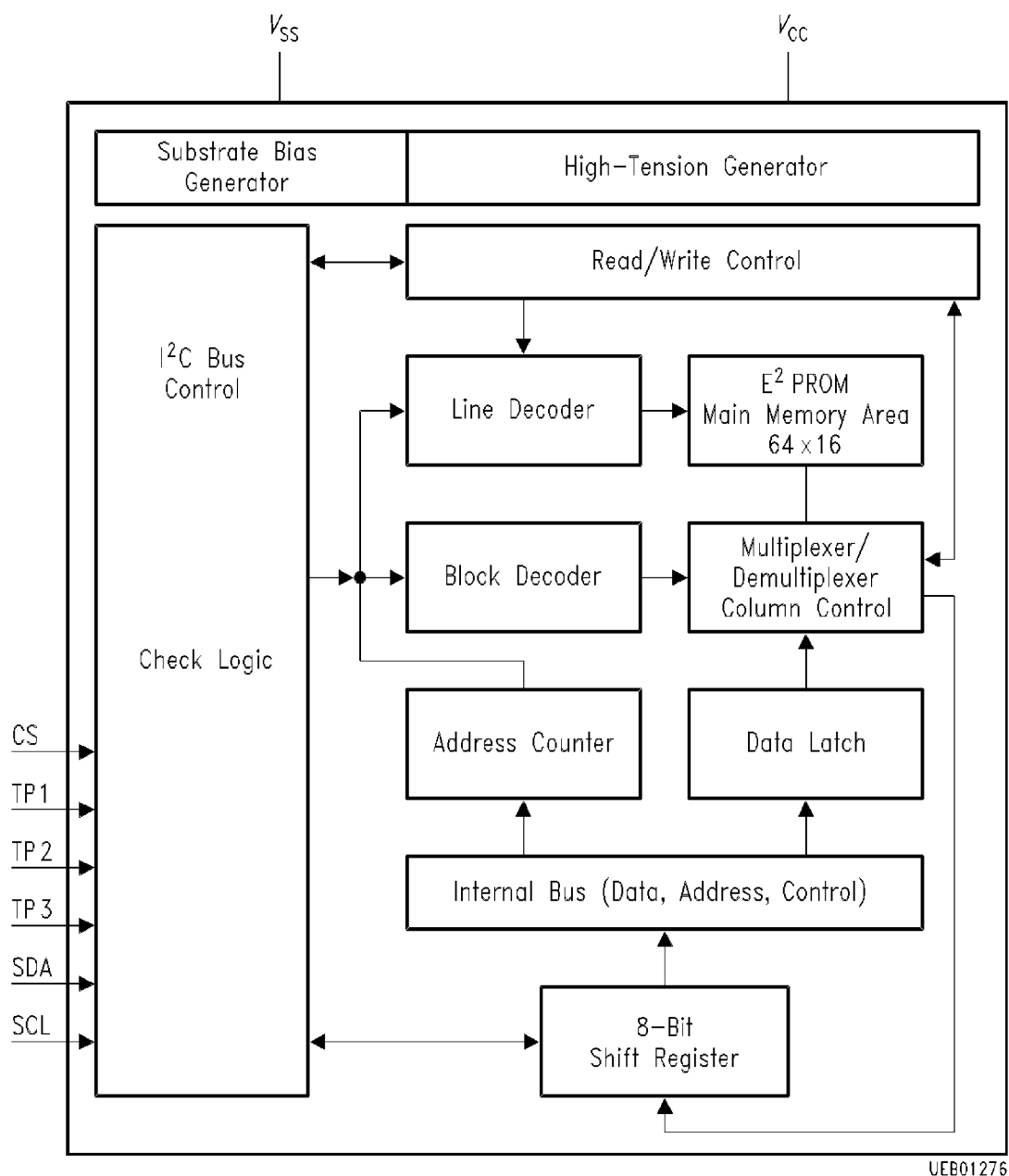


Pin Configuration

(top view)

Pin Definitions and Functions

| Pin No. | Symbol | Function |
|---------|----------|--|
| 1 | V_{SS} | Ground |
| 2 | CS | Chip select |
| 3 | TP1 | to V_{SS} |
| 4 | TP2 | 0 V normal function, TP2 = 5 V condition to erase of the entire memory |
| 5 | SDA | Data line |
| 6 | SCL | Clock line |
| 7 | TP3 | open |
| 8 | V_{CC} | Supply voltage |



Block Diagram

Absolute Maximum Ratings

| Parameter | Symbol | Limit Values | | Unit |
|------------------------------------|-------------|--------------|------|------|
| | | min. | max. | |
| Supply voltage | V_{CC} | - 0.3 | 6 | V |
| Input voltage | V_I | - 0.3 | 6 | V |
| Power dissipation | P_D | | 130 | mW |
| Storage temperature | T_{stg} | - 40 | 125 | °C |
| Thermal resistance (system-air) | $R_{th SA}$ | | 100 | K/W |
| Junction temperature | T_j | | 85 | °C |

Operating Range

| | | | | |
|---------------------|----------|------|------|----|
| Supply voltage | V_{CC} | 4.75 | 5.25 | V |
| Ambient temperature | T_A | 0 | 70 | °C |

Characteristics

$T_A = 25\text{ °C}$

| Parameter | Symbol | Limit Values | | | Unit | Test Condition |
|----------------|----------|--------------|------|------|------|--------------------------|
| | | min. | typ. | max. | | |
| Supply voltage | V_{CC} | 4.75 | 5.0 | 5.25 | V | |
| Supply current | I_{CC} | | | 20 | mA | $V_{CC} = 5.25\text{ V}$ |

Inputs

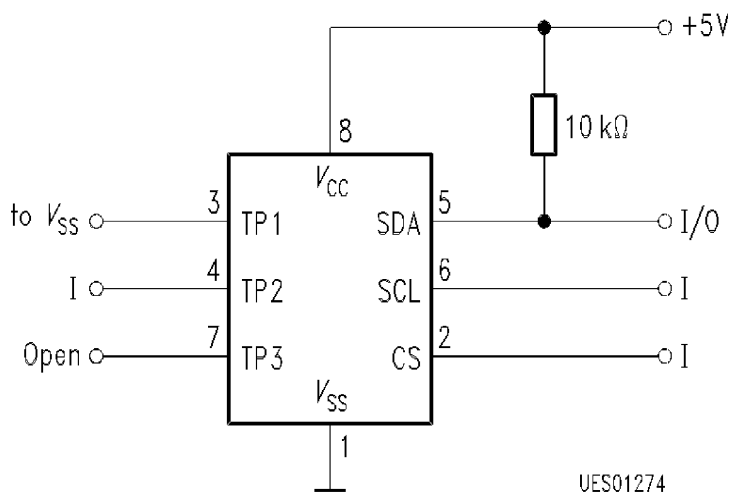
| | | | | | | |
|-----------------------|----------|-----|--|----------|----|-------------------|
| Input voltage SDA/SCL | V_{IL} | | | 1.5 | V | |
| Input voltage SDA/SCL | V_{IH} | 3.0 | | V_{CC} | V | |
| Input current SDA/SCL | I_{IH} | | | 10 | μA | $V_{IH} = V_{CC}$ |

Outputs

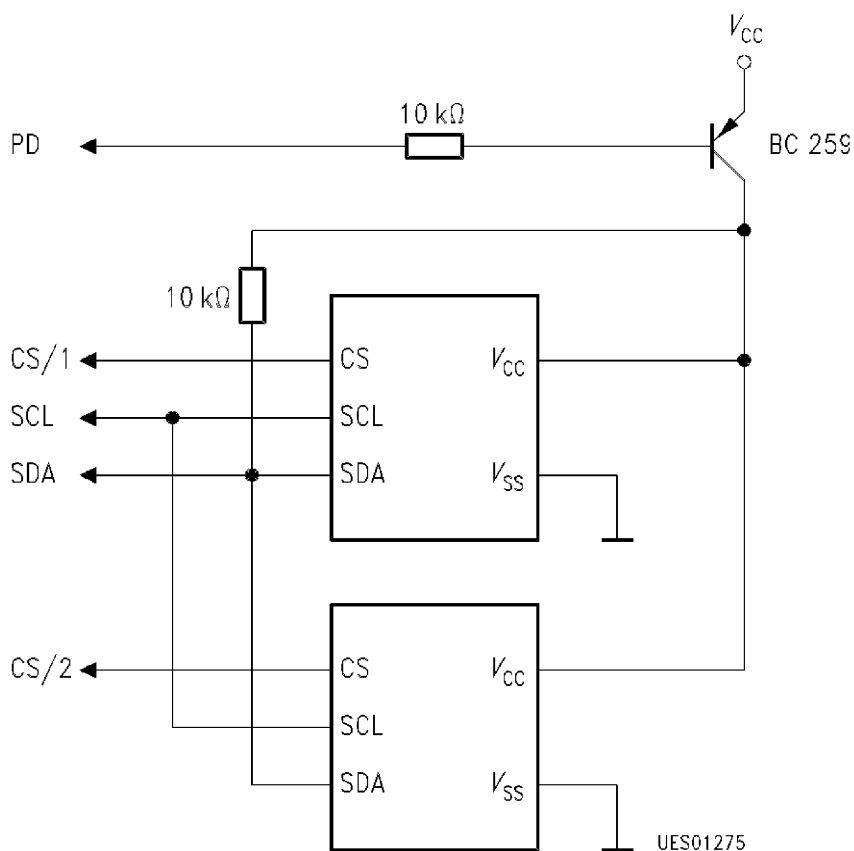
| | | | | | | |
|---------------------|----------|--|--|-----|----|------------------------------|
| Output current SDA | I_{QL} | | | 3.0 | mA | $V_{QL} = 0.4\text{ V}$ |
| Leakage current SDA | I_{QH} | | | 10 | μA | $V_{QH} = V_{CC\text{ max}}$ |

Inputs

| | | | | | | |
|---------------------------|------------|-----|----|----------|-----|--------------------------|
| Input voltages CS/TP1/TP2 | V_{IL} | | | 0.2 | V | |
| Input voltages CS/TP1/TP2 | V_{IH} | 4.5 | | V_{CC} | V | |
| Input currents CS/TP1/TP2 | I_{IH} | | | 100 | μA | $V_{CC} = 5.25\text{ V}$ |
| Clock frequency | f_{SCL} | | | 100 | kHz | |
| Reprogramming duration | t_{PROG} | | 10 | 20 | ms | erase and write |
| Input capacity | C_1 | | | 10 | pF | |
| Total erase | t_{GL} | | | 20 | ms | TP2 = 5 V |



Test Circuit



Application Circuit

The diagram shows the SDA and SCL signals over time. The SDA signal is high during the Start and Stop conditions. During the Data Transmission with Acknowledge Bit phase, the SDA signal is low for the first 8 bits (labeled 'Input') and high for the 9th bit (labeled 'Output'). The SCL signal is high during the Start and Stop conditions and low during the Data Transmission phase. The SCL signal has a pulse width of 1-8 for the first two data bytes and 9 for the third data byte. The diagram is labeled 'UED00349'.

The diagram illustrates the timing relationships for the I2C protocol. It shows three signals: SDA (Serial Data), SCL (Serial Clock), and SDA (Serial Data). The timing parameters are defined as follows:

- t_{BUF} : Buffer time between SDA and SCL signals.
- t_R : Rise time of SCL signal.
- t_F : Fall time of SCL signal.
- t_{LOW} : Low pulse width of SCL signal.
- t_{HIGH} : High pulse width of SCL signal.
- $t_{HD; STA}$: Hold time of SDA signal after SCL signal goes high.
- $t_{HD; DAT}$: Hold time of SDA signal after SCL signal goes high during data transfer.
- $t_{SU; DAT}$: Setup time of SDA signal before SCL signal goes high during data transfer.
- $t_{SU; STA}$: Setup time of SDA signal before SCL signal goes high for start of transmission.
- $t_{SU; STO}$: Setup time of SDA signal before SCL signal goes high for stop of transmission.

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Timing Conditions

| Parameter | Symbol | Limit Values | | Unit |
|---|---------------------|--------------|------|---------------|
| | | min. | max. | |
| Minimum time the bus must be free before a new transmission can start | t_{BUF} | 4.7 | | μs |
| Start condition hold time | $t_{\text{HD;STA}}$ | 4.0 | | μs |
| Clock low period | t_{LOW} | 4.7 | | μs |
| Clock high period | t_{HIGH} | 4.0 | | μs |
| Start condition set-up time, only valid for repeated start code | $t_{\text{SU;STA}}$ | 4.7 | | μs |
| Data set-up time | $t_{\text{SU;DAT}}$ | 250 | | ns |
| Rise time of both the SDA and SCL line | t_{R} | | 1 | μs |
| Fall time of both the SDA and SCL line | t_{F} | | 300 | μs |
| Stop condition set-up time | $t_{\text{SU;SPO}}$ | 4.7 | | μs |

Note that a transmitter must internally provide at least a hold time to bridge the undefined region (max. 300 ns) of the falling edge of SCL. All values refer to V_{IH} and V_{IL} level.

Control Word Table

| Clock No. | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | (Acknowledge) |
|------------------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------------------|
| CS/E | 1 | 0 | 1 | 0 | A9 | A8 | CS | 0 | 0 | through memory |
| CS/A | 1 | 0 | 1 | 0 | – | – | CS | 1 | 0 | through memory |
| WA | A7 | A6 | A5 | A4 | A3 | A2 | A1 | A0 | 0 | through memory |
| DE | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | 0 | through memory |
| DA | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | 0/1 | through master |

Control Word Input Key

| | |
|----------|--|
| CS/E | Chip select for data input into memory (with word-address bit A8 and A9) |
| CS/A | Chip select for data output out of memory |
| WA | Memory word address |
| DE | Data word for memory |
| DA | Data word read out for memory |
| D0 to D7 | Data bits |
| ST | Start condition |
| SP | Stop condition |
| As | Acknowledge bit from memory |
| Am | Acknowledge bit from master |
| CS | Chip select bits |
| A0 to A9 | Memory word address bits |