

LP2956/LP2956A Dual Micropower Low-Dropout Voltage Regulators

General Description

The LP2956 is a micropower voltage regulator with very low quiescent current (170 μ A typical at light loads) and very low dropout voltage (typically 60 mV at 1 mA load current and 470 mV at 250 mA load current on the main output).

The LP2956 retains all the desirable characteristics of the LP2951, but offers increased output current (main output), an auxiliary LDO adjustable regulated output (75 mA), and additional features.

The auxiliary output is always on (regardless of main output status), so it can be used to power memory circuits.

Quiescent current increases only slightly at dropout, which prolongs battery life.

The error flag goes low if the main output voltage drops out of regulation.

An open-collector auxiliary comparator is included, whose inverting input is tied to the 1.23V reference.

Reverse battery protection is provided.

MAIN OUT

ERROR AMP

60

m٧

DROPOUT

AUX OUT

1.23 V_{REF}T

ERROR AMP

AUX

FB

COMP

COMF

The parts are available in plastic DIP and surface mount packages.

LP2956

OUTPUT

SENSE

5V TAP

FRROR

SHUT

DOWN

AUX OUTPUT

COMP

OUTPUT

GROUND

TL/H/11339-1

INPUT

Π

Π

AUXILIAR

COMP

Block Diagram

FEED

BACK



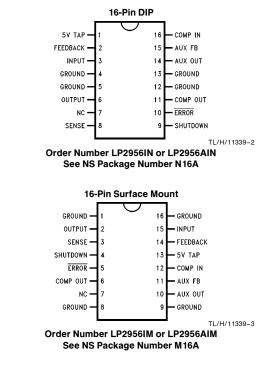
- Output voltage adjusts from 1.23V to 29V
- Guaranteed 250 mA current (main output)
- Auxiliary LDO (75 mA) adjustable output
 Auxiliary comparator with open-collector output
- Auxiliary comparator with open-collect
 Shutdown pin for main output
- Shutdown pin for main output
 Extremely low quiescent current
- Low dropout voltage
- Extremely tight line and load regulation
- Very low temperature coefficient
- Current and thermal limiting
- Reverse battery protection

Applications

- High-efficiency linear regulator
- Low dropout battery-powered regulator

Connection Diagrams

μP system regulator with switchable high-current V_{CC}



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LP2956/LP2956A Dual Micropower Low-Dropout Voltage Regulators

August 1993

Absolute Maximum Ra	atings (Note 1)		
If Military/Aerospace specified	devices are required,	Input Supply Voltage	-20V to $+30V$
please contact the National Semiconductor Sales		Feedback Input Voltage (Note 3)	-0.3V to $+5V$
Office/Distributors for availability	•	Aux. Feedback Input Voltage (Note 3)	-0.3V to $+5V$
Storage Temperature Range	-65°C to +150°C	Shutdown Input Voltage (Note 3)	-0.3V to +30V
Operating Junction Temperature Range	-40°C to +125°C	Comparator Input Voltage (Notes 3, 4)	-0.3V to $+30V$
Lead Temperature		Comparator Output Voltage (Notes 3, 4)	-0.3V to $+30V$
(Soldering, 5 seconds)	260°C	ESD Rating (Note 16)	2 kV
Power Dissipation (Note 2)	Internally Limited		

Electrical Characteristics Limits in standard typeface are for $T_J = 25^{\circ}$ C, and limits in **boldface type** apply over the full operating temperature range. Limits are guaranteed by production testing or correlation techniques using standard Statistical Quality Control (SQC) methods. Unless otherwise specified: $V_{IN} = 6V$, $C_L = 2.2 \ \mu$ F (Main Output) and 10 μ F (Auxiliary Output), Feedback pin is tied to 5V Tap pin, $C_{IN} = 1 \ \mu$ F, $V_{SD} = 0$ V, Main Output pin is tied to Output Sense pin, Auxiliary Output is programmed for 5V. The main regulator output has a 1 mA load, the auxiliary regulator output has a 100 μ A load.

0	Deremeter	Conditions	Turker	LP2956AI		LP2956I		Unite
Symbol	Parameter	Conditions	Typical	Min	Max	Min	Max	Units
	PUT							
V _O	Output Voltage		5.0	4.975 4.940	5.025 5.060	4.950 4.900	5.050 5.100	V
		1 mA \leq I _L \leq 250 mA	5.0	4.930	5.070	4.880	5.120	v
$rac{\Delta V_O}{\Delta T}$	Temperature Coefficient	(Note 5)	20		100		150	ppm/°C
$\frac{\Delta V_{O}}{V_{O}}$	Line Regulation	$V_{IN} = 6V \text{ to } 30V$	0.03		0.1 0.2		0.2 0.4	%
$\frac{\Delta V_{O}}{V_{O}}$	Load Regulation	$I_L = 1 \text{ mA to } 250 \text{ mA}$ $I_L = 0.1 \text{ mA to } 1 \text{ mA}$ (Note 6)	0.04		0.16 0.20		0.20 0.30	%
$v_{IN} - v_O$	Dropout Voltage (Note 7)	$I_L = 1 \text{ mA}$	60		100 150		100 150	- mV
		$I_L = 50 \text{ mA}$	240		300 420		300 420	
		$I_L = 100 \text{ mA}$	310		400 520		400 520	ĨĨĬ
		$I_L = 250 \text{ mA}$	470		600 800		600 800	
ILIMIT	Current Limit	$R_L = 1\Omega$	380		500 530		500 530	mA
$rac{\Delta V_O}{\Delta P_D}$	Thermal Regulation	(Note 8)	0.05		0.2		0.2	%/W
e _n	Output Noise Voltage	$C_L = 2.2 \ \mu F$	400					
	(10 Hz to 100 KHz) I _I = 100 mA	$C_L = 33 \ \mu F$	260					μV RMS
		C _L = 33 μF (Note 9)	80					

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Cumhel	Paramotor	Conditions	Turning	LP2956AI		LP2956I		Unite
Symbol	Parameter	Conditions	Typical	Min	Max	Min	Max	Units
	FPUT (Continued)							
V _{FB}	Feedback Pin Voltage		1.23	1.215	1.245	1.205	1.255	V
I _{FB}	Feedback Pin Bias Current		20		40 60		40 60	nA
I _O (OFF)	Output Leakage In Shutdown	$\label{eq:ISD_IN} \begin{split} I_{(\text{SD IN})} &\geq 1 \; \mu \text{A} \\ V_{\text{IN}} &= 30 \text{V}, V_{\text{OUT}} = 0 \text{V} \end{split}$	3		10 20		10 20	μΑ
AUXILIAF	Υ Ουτρυτ							
V _{FB}	Feedback Pin Voltage		1.23	1.22 1.21	1.25 1.26	1.21 1.20	1.26 1.27	V
$\frac{\Delta V_{FB}}{\Delta T}$	Feedback Voltage Temperature Coefficient		20					ppm/°C
I _{FB}	Feedback Pin Bias Current		10		20 30		20 30	nA
$\frac{\Delta V_O}{V_O}$	Line Regulation	$6V \leq V_{IN} \leq 30V$	0.07		0.3 0.5		0.4 0.6	%
$\frac{\Delta V_O}{V_O}$	Load Regulation	$I_L = 0.1 \text{ mA to } 1 \text{ mA}$ $I_L = 1 \text{ mA to } 75 \text{ mA}$ (Note 10)	0.1		0.3 0.6		0.4 1.0	%
V _{IN} -V _O	Dropout Voltage	$I_L = 1 \text{ mA}$	100		200 300		200 300	mV
		$I_L = 50 \text{ mA}$	400		600 700		600 700	mV
		$I_L = 75 \text{ mA}$	500		700 850		700 850	mV
e _n	Output Noise	$C_L = 10 \mu F$	300					
	(10 Hz–100 KHz) I _L = 10 mA	$C_L = 33 \ \mu F$ (Note 9)	100					μV RMS
I _{LIM}	Current Limit	V _{OUT} = 0V (Note 13)	80		200 250		200 250	mA
$\frac{\Delta V_O}{\Delta P_D}$	Thermal Regulation	(Note 8)	0.2		0.5		0.5	%/W
DROPOUT	DETECTION COMPARATO	R						
I _{OH}	Output "HIGH" Leakage	$V_{OH} = 30V$	0.01		1 2		1 2	μΑ
V _{OL}	Output "LOW" Voltage	$V_{IN} = 4V$ I _O (COMP) = 400 µA	150		250 400		250 400	mV
V _{THR}	Upper Threshold Voltage	(Note 11)	-240	-320 - 380	150 100	-320 - 380	150 100	mV

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Symbol	Parameter	Conditions	Conditions Typical LP2956AI LP2		P2956AI LP2956I		9561	Units
Symbol	Farameter	Conditions	i ypicai	Min	Max	Min	Max	Units
DROPOUT	DETECTION COMPARATOR (Co	ntinued)						
V _{THR} (min)	Lower Threshold Voltage	(Note 11)	-350	-450 - 640	-230 - 160	-450 - 640	-230 - 160	mV
HYST	Hysteresis	(Note 11)	110					mV
SHUTDOW	IN INPUT							-
I _{IN}	Input Current to Disable Output	(Note 12)	0.03		0.5		0.5	μΑ
V_{IH}	Shutdown Input High Threshold	$I_{(SD N)} \ge 1 \ \mu A$		900 1200		900 1200		mV
V _{IL}	Shutdown Input Low Threshold	$V_{O} \ge 4.5V$			400 200		400 200	mV
	Y COMPARATOR							
V _T (high)	Upper Trip Point	(Note 14)	1.236	1.20 1.19	1.28 1.29	1.20 1.19	1.28 1.29	v
V _T (low)	Lower Trip Point	(Note 14)	1.230	1.19 1.18	1.27 1.28	1.19 1.18	1.27 1.28	v
HYST	Hysteresis		6					mV
I _{OH}	Output "HIGH" Leakage	$V_{OH} = 30V$ V_{IN} (COMP) = 1.3V	0.01		1 2		1 2	μΑ
V _{OL}	Output "LOW" Voltage	V_{IN} (COMP) = 1.1V I_O (COMP) = 400 μ A	150		250 400		250 400	mV
Ι _Β	Input Bias Current	$0 \le V_{IN}$ (COMP) $\le 5V$	10	-30 - 50	30 50	-30 - 50	30 50	nA
GROUND F	PIN CURRENT							
I _{GND}	Ground Pin Current (Note 15)	I_L (Main Out) = 1 mA I_L (Aux. Out) = 0.1 mA	170		250 280		250 280	μΑ
		I_L (Main Out) = 50 mA I_L (Aux. Out) = 1 mA	1.1		2 2.5		2 2.5	
		I_L (Main Out) = 100 mA I_L (Aux. Out) = 1 mA	3		6 8		6 8	
		I_L (Main Out) = 250 mA I_L (Aux. Out) = 1 mA	16		28 33		28 33	mA
		I_L (Main Out) = 1 mA I_L (Aux. Out) = 50 mA	3		6 8		6 8	
		I_L (Main Out) = 1 mA I_L (Aux. Out) = 75 mA	6		8 10		8 10	

Electrical Characteristics

Limits in standard typeface are for $T_J = 25^{\circ}$ C, and limits in **boldface type** apply over the full operating temperature range. Limits are guaranteed by production testing or correlation techniques using standard Statistical Quality Control (SQC) methods. Unless otherwise specified: $V_{IN} = 6V$, $C_L = 2.2 \ \mu$ F (Main Output) and 10 μ F (Auxiliary Output), Feedback pin is tied to 5V Tap pin, $C_{IN} = 1 \ \mu$ F, $V_{SD} = 0V$, Main Output pin is tied to Output Sense pin, Auxiliary Output is programmed for 5V. The main regulator output has a 1 mA load, the auxiliary regulator output has a 100 μ A load. (Continued)

Cumhal	Devementer	Conditions	Turningal	LP2	956AI	LP2956I		Units
Symbol	Parameter Conditions		Typical	Min	Max	Min	Max	Units
GROUND PI	N CURRENT (Continued)							
I _{GND}	Ground Pin Current at Dropout (Note 15)	$\label{eq:VIN} \begin{array}{l} V_{\text{IN}} = 4.5 V \\ I_{\text{L}} \left(\text{Main Out} \right) = 0.1 \text{ mA} \\ I_{\text{L}} \left(\text{Aux. Out} \right) = 0.1 \text{ mA} \end{array}$	270		325 350		325 350	μΑ
I _{GND}	Ground Pin Current at Shutdown (Note 15)	No Load on Either Output $I_{(SD N)} \ge 1 \ \mu A$	120		180 200		180 200	

Note 1: Absolute maximum ratings indicate limits beyond which damage to the component may occur. Electrical specifications do not apply when operating the device outside of its rated operating conditions.

Note 2: The maximum allowable power dissipation is a function of the maximum junction temperature, $T_J(max)$, the junction-to-ambient thermal resistance, θ_{J-A} , and the ambient temperature, T_A . The maximum allowable power dissipation at any ambient temperature is calculated using: $P(max) = \frac{T_J(max) - T_A}{2}$.

Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. See Application Hints for additional information on heat sinking and thermal resistance.

Note 3: When used in dual-supply systems where the regulator load is returned to a negative supply, the output voltage must be diode-clamped to ground. Note 4: May exceed the input supply voltage.

Note 5: Output or reference voltage temperature coefficient is defined as the worst case voltage change divided by the total temperature range.

Note 6: Load regulation is measured at constant junction temperature using low duty cycle pulse testing. Two separate tests are performed, one for the range of 100 µA to 1 mA and one for the 1 mA to 250 mA range. Changes in output voltage due to heating effects are covered by the thermal regulation specification. Note 7: Dropout voltage is defined as the input to output differential at which the output voltage drops 100 mV below the value measured with a 1V differential. At very low values of programmed output voltage, the input voltage minimum of 2V (2.3V over temperature) must be observed.

Note 8: Thermal regulation is the change in output voltage at a time T after a change in power dissipation, excluding load or line regulation effects. Specifications are for a 200 mA load pulse at $V_{IN} = 20V$ (3W pulse) for T = 10 ms on the Main regulator output. For the Auxiliary regulator output, specifications are for a 66 mA load pulse at $V_{IN} = 20V$ (1W pulse) for T = 10 ms.

Note 9: Connect a 0.1 μ F capacitor from the output to the feedback pin.

Note 10: Load regulation is measured at constant junction temperature using low duty cycle pulse testing. Two separate tests are performed, one for the range of 100 μ A to 1 mA and one for the 1 mA to 75 mA range. Changes in output voltage due to heating effects are covered by the thermal regulation specification. Note 11: Dropout dectection comparator thresholds are expressed as changes in a 5V output. To express the threshold voltages in terms of a differential at the Feedback terminal, divide by the error amplifier gain = V_{OLT}/V_{DFF} .

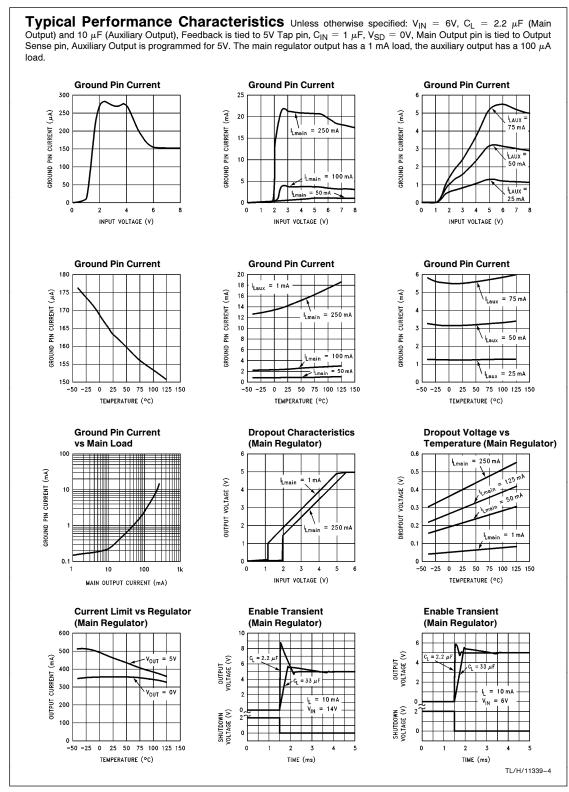
Note 12: The shutdown input equivalent circuit is the base of a grounded-emitter NPN transistor in series with a current-limiting resistor. Pulling the shutdown input high turns off the main regulator. For more details, see Application Hints.

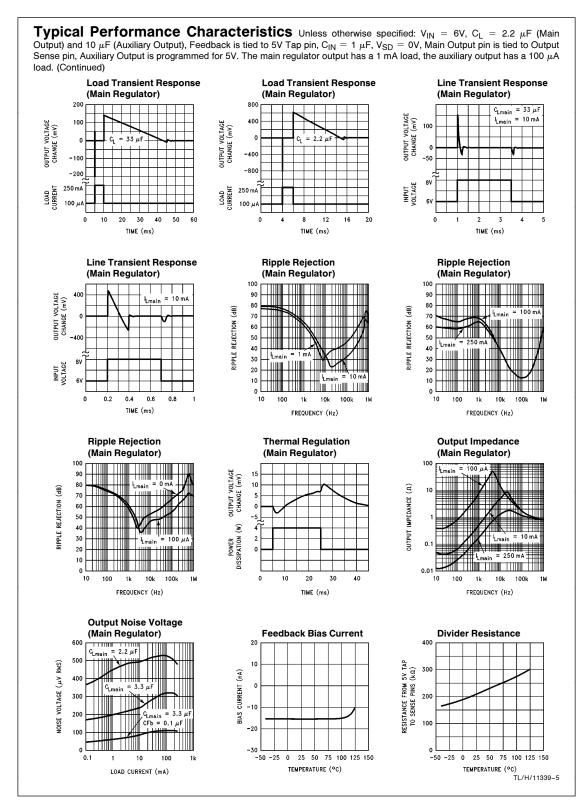
Note 13: The auxiliary regulator output has foldback limiting, which means the output current reduces with output voltage. The tested limit is for V_{OUT} = 0V, so the output current will be higher at higher output voltages.

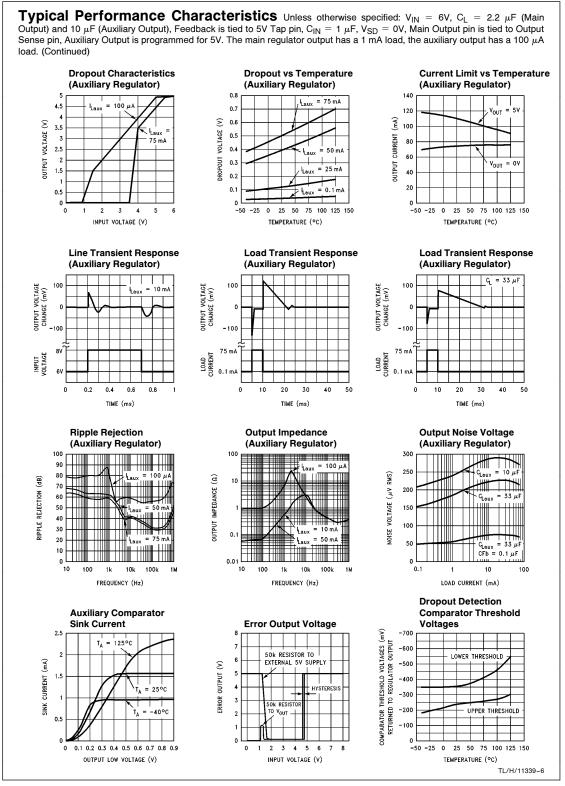
Note 14: This test is performed with the auxiliary comparator output sinking 400 μ A of current. At the upper trip point, the comparator output must be \geq 2.4V. At the low trip point, the comparator output must be \leq 0.4V.

Note 15: Ground pin current is the regulator quiescent current. The total current drawn from the source is the sum of the ground pin current, output load current, and current through the external resistive dividers (if used).

Note 16: All pins are rated for 2 kV, except for the auxiliary feedback pin which is rated for 1.2 kV (human body model, 100 pF discharged through 1.5 kΩ).









Application Hints

HEATSINK REQUIREMENTS

A heatsink may be required with the LP2956 depending on the maximum power dissipation and maximum ambient temperature of the application. Under all expected operating conditions, the junction temperature must be within the range specified under Absolute Maximum Ratings.

To determine if a heatsink is required, the maximum power dissipated by the regulator, P(max), must be calculated. It is important to remember that if the regulator is powered from a transformer connected to the AC line, the **maximum specified AC input voltage** must be used (since this produces the maximum DC input voltage to the regulator). *Figure 1* shows the voltages and currents which are present in the circuit. The formula for calculating the power dissipated in the regulator is also shown in *Figure 1* (the currents and power due to external resistive dividers are not included, and are typically negligible).

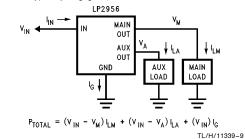


FIGURE 1. Current/Voltage Diagram

The next parameter which must be calculated is the maximum allowable temperature rise, $T_{R}(max)$. This is calculated by using the formula:

 $T_R(max) = T_J(max) - T_R(max)$

where: $T_{\rm J}({\rm max})$ is the maximum allowable junction temperature

T_A(max) is the maximum ambient temperature

Using the calculated values for $T_R(max)$ and P(max), the required value for junction-to-ambient thermal resistance, $\theta_{(J-A)}$, can now be found:

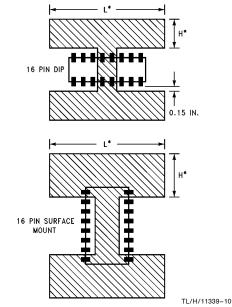
$\theta_{(J-A)} = T_{R}(max)/P(max)$

The heatsink for the LP2956 is made using the PC board copper. The heat is conducted from the die, through the lead frame (inside the part), and out the pins which are soldered to the PC board. The pins used for heat conduction are shown in Table I.

T/	٩BI	-E I
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Part	Package	Pins
LP2956IN	16-Pin DIP	4, 5, 12, 13
LP2956AIN	16-Pin DIP	4, 5, 12, 13
LP2956IM	16-Pin Surface Mt.	1, 8, 9, 16
LP2956AIM	16-Pin Surface Mt.	1, 8, 9, 16

Figure 2 shows copper patterns which may be used to dissipate heat from the LP2956:



*For best results, use L = 2H

FIGURE 2. Copper Heatsink Patterns

Table II shows some typical values of junction-to-ambient thermal resistance $(\theta_{J\text{-}A})$ for values of L and W (1 oz. copper).

TABLE II								
Package	L (ln.)	H (In.)	θ _{J-A} (°C/W)					
16-Pin	1	0.5	70					
DIP	2	1	60					
	3	1.5	58					
	4	0.19	66					
	6	0.19	66					
16-Pin	1	0.5	83					
Surface Mount	2	1	70					
	3	1.5	67					
	6	0.19	69					
	4	0.19	71					
	2	0.19	73					

Application Hints (Continued)

EXTERNAL CAPACITORS

A 2.2 μF (or greater) capacitor is required between the main output pin and ground to assure stability. The auxiliary output requires 10 μF to ground. Without these capacitors, the part may oscillate. Most types of tantalum or aluminum electrolytics will work here. Film types will work, but are more expensive. Many aluminum electrolytics contain electrolytes which freeze at -30°C , which requires the use of solid tantalums below -25°C . The important characteristic of the capacitors is an ESR of 5 Ω (or less) on the main regulator output (the ESR may increase by a factor of 20 or 30 as the temperature is reduced from $+25^\circ\text{C}$ to -30°C). The value of these capacitors may be increased without limit.

The main output requires less capacitance at lighter load currents. This capacitor can be reduced to 0.68 μ F for currents below 10 mA or 0.22 μ F for currents below 1 mA.

Programming the main output for voltages below 5V requires *more* output capacitance for stability. For the worstcase condition of 1.23V output and 250 mA of load current, a 6.8 μ F (or larger) capacitor should be used.

A 1 μ F capacitor should be placed from the input pin to ground if there is more than 10 inches of wire between the input and the AC filter capacitor or if a battery input is used. Stray capacitance to the Feedback terminal can cause instability. This problem is most likely to appear when using high value external resistors to set the output voltage. Adding a 100 pF capacitor between the Output and Feedback pins and increasing the output capacitance to 6.8 μ F (or greater) will cure the problem.

MINIMUM LOAD ON MAIN OUTPUT

When setting the main output voltage using an external resistive divider, a minimum current of 10 μ A is recommended through the resistors to provide a minimum load.

It should be noted that a minimum load current is specified in several of the electrical characteristic test conditions, so the specified value must be used to obtain test limit correlation.

PROGRAMMING THE MAIN OUTPUT VOLTAGE

The main output may be pin-strapped for 5V operation using its internal resistive divider by tying the Output and Sense pins together and also tying the Feedback and 5V Tap pins together.

Alternatively, it may be programmed for any voltage between the 1.23V reference and the 29V maximum rating using an external pair of resistors (see *Figure 3*). The complete equation for the output voltage is:

$$V_{\text{MAIN OUT}} = V_{\text{REF}} \times \left(1 + \frac{\text{R1}}{\text{R2}}\right) + (I_{\text{FB}} \times \text{R1})$$

where V_{REF} is the 1.23V reference and I_{FB} is the Feedback pin bias current (-20 nA typical). The minimum recommended load current of 1 μ A sets an upper limit of 1.2 M Ω on the value of R2 in cases where the regulator must work with no load (see **MINIMUM LOAD**).

If I_{FB} is ignored in the calculation of the output voltage, it will produce a small error in V_{MAIN OUT}. Choosing R2 = 100 kΩ will reduce this error to 0.16% (typical) while increasing the resistor program current to 12 μ A. Since the typical quiescent current is 130 μ A, this added current is negligible.

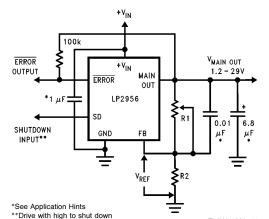


FIGURE 3. Adjustable Regulator TL/H/11339-11

DROPOUT VOLTAGE

The dropout voltage of the regulator is defined as the minimum input-to-output voltage differential required for the output voltage to stay within 100 mV of the output voltage measured with a 1V differential. The dropout voltage is independent of the programmed output voltage.

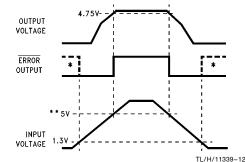
DROPOUT DETECTION COMPARATOR

This comparator produces a logic "LOW" whenever the main output falls out of regulation by more than about 5%. This figure results from the comparator's built-in offset of 60 mV divided by the 1.23V reference (refer to block diagram). The 5% low trip level remains constant regardless of the programmed output voltage. An out-of-regulation condition can result from low input voltage, current limiting, or thermal limiting.

Figure 4 gives a timing diagram showing the relationship between the main output voltage, the ERROR output, and input voltage as the input voltage is ramped up and down to a regulator whose main output is programmed for 5V. The ERROR signal becomes low at about 1.3V input. It goes high at about 5V input, where the main output equals 4.75V. Since the dropout voltage is load dependent, the **input** voltage trip points will vary with load current. The **main output** voltage trip point does not vary.

The comparator has an open-collector output which requires an external pull-up resistor. This resistor may be connected to the regulator main output or some other supply voltage. Using the main output prevents an invalid "HIGH" on the comparator output which occurs if it is pulled up to an external voltage while the regulator input voltage is reduced below 1.3V. In selecting a value for the pull-up resistor, note that while the output can sink 400 μ A, this current adds to battery drain. Suggested values range from 100 k Ω to 1 M Ω . The resistor is not required if the output is unused.

Application Hints (Continued)



*In shutdown mode, ERROR will go high if it has been pulled up to an external supply. To avoid this invalid response, pull up to regulator output. **Exact value depends on dropout voltage. (See Application Hints)

FIGURE 4. ERROR Output Timing

If a single pull-up resistor is used to the regulator output, the error flag may briefly rise up to about 1.3V as the input voltage ramps up or down through the 0V to 1.3V region.

In some cases, this 1.3V signal may be mis-interpreted as a false high by a μP which is still "alive" with 1.3V applied to it.

To prevent this, the user may elect to use **two** resistors which are equal in value on the error output (one connected to ground and the other connected to the regulator output). If this two-resistor divider is used, the error output will only be pulled up to about 0.6V (not 1.3V) during power-up or power-down, so it can not be interpreted as a high signal. When the regulator output is at 5V, the error output will be 2.5V, which is still clearly a high signal.

OUTPUT ISOLATION

The regulator outputs can be left connected to an active voltage source (such as a battery) with the regulator input power shut off, as long as the regulator ground pin is connected to ground. If the ground pin is left floating, damage to the regulator can occur if the output is pulled up by an external voltage source.

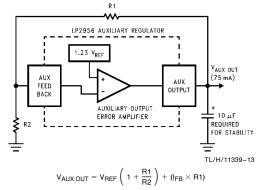
REDUCING MAIN OUTPUT NOISE

In reference applications it may be advantageous to reduce the AC noise present on the main output. One method is to reduce regulator bandwidth by increasing output capacitance. This is relatively inefficient, since large increases in capacitance are required to get significant improvement.

Noise can be reduced more effectively by a bypass capacitor placed across R1 (refer to *Figure 3*). The formula for selecting the capacitor to be used is:

$$CB = \frac{1}{2\pi R1 \times 20 Hz}$$

This gives a value of about 0.1μ F. When this is used, the output capacitor must be 6.8 μ F (or greater) to maintain stability. The 0.1 μ F capacitor reduces the high frequency noise gain of the circuit to unity, lowering the output noise from 260 μ V to 80 μ V using a 10 Hz to 100 kHz bandwidth. Also, noise is no longer proportional to the output voltage, so improvements are more pronounced at higher output voltages.



where: $V_{\mbox{\scriptsize REF}}$ = 1.23V and $I_{\mbox{\scriptsize FB}}$ = -10 nA (typical)

FIGURE 5. Auxiliary Adjustable Regulator

AUXILIARY LDO OUTPUT

The LP2956 has an auxiliary LDO regulator output (which can source up to 75 mA) that is adjustable for voltages from 1.23V to 29V.

The output voltage is set by an external resistive divider, as shown in *Figure 5*. The maximum output current is 75 mA, and the output requires 10 μ F from the output to ground for stability, regardless of load current.

SHUTDOWN INPUT

The shutdown input equivalent circuit is shown in *Figure 6*. The main regulator output is shut down when the NPN transitor is turned ON.

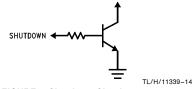
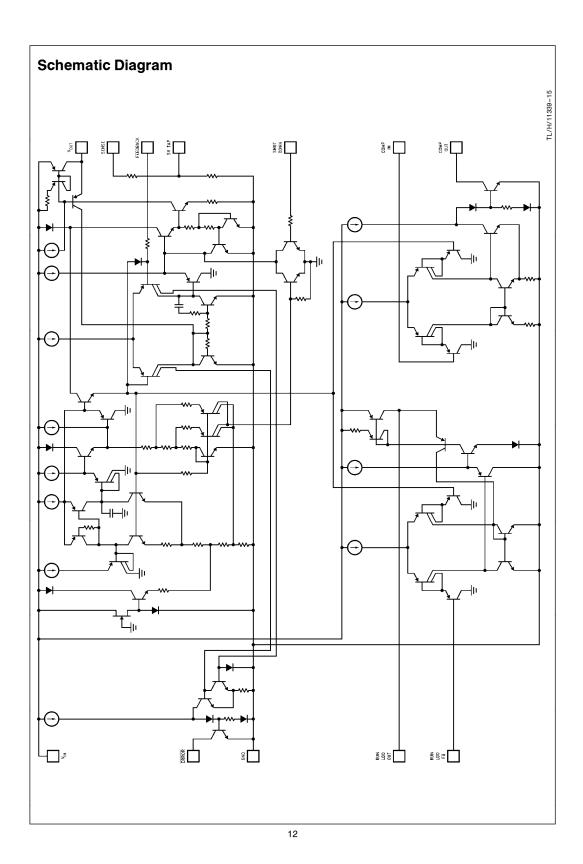


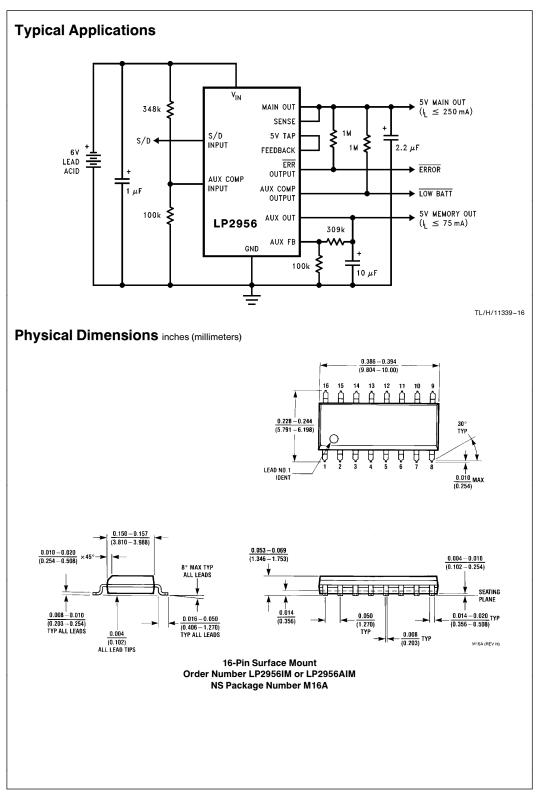
FIGURE 6. Shutdown Circuitry

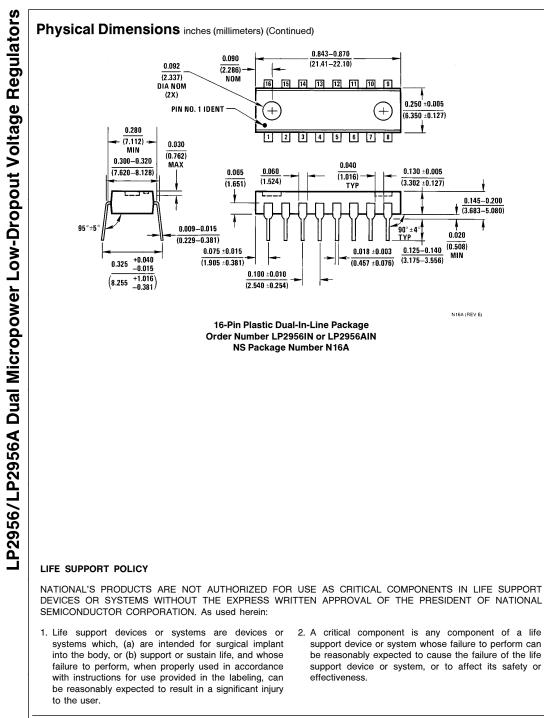
The current into the input should be at least 0.5 μA to assure the output shutdown function. A resistor may be placed in series with the input to minimize current draw in shutdown mode, provided this minimum input current requirement is met.

IMPORTANT:

The shutdown input must not be left floating: a pull-down resistor (10 k Ω to 50 k Ω recommended) must be connected between the shutdown input and ground in cases where the input is not actively pulled low.







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	the user.	ed to result in a s	significant injury			
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0.250 ±0.005

(6.350 ±0.127)

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 0.130 ± 0.005

(3.302 ±0.127)

0.125-0.140 (0.508)

(3.175-3.556)

90°±4

0.145-0.200 (3.683-5.080)

0.020

N16A (REV E)

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