

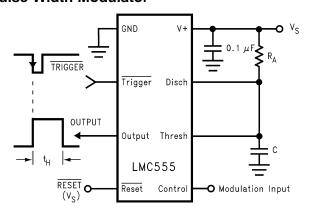
LMC555 CMOS Timer

Check for Samples: LMC555

FEATURES

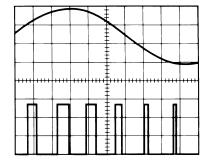
- Less than 1 mW Typical Power Dissipation at **5V Supply**
- 3 MHz Astable Frequency Capability
- 1.5V Supply Operating Voltage Ensured
- **Output Fully Compatible with TTL and CMOS** Logic at 5V Supply
- Tested to −10 mA, +50 mA Output Current Levels
- **Reduced Supply Current Spikes During Output Transitions**
- Extremely Low Reset, Trigger, and Threshold Currents
- **Excellent Temperature Stability**
- Pin-for-Pin Compatible with 555 Series of Timers
- Available in 8-pin VSSOP Package and 8-Bump **DSBGA** package

Pulse Width Modulator



DESCRIPTION

The LMC555 is a CMOS version of the industry standard 555 series general purpose timers. In addition to the standard package (SOIC, VSSSOP, and PDIP) the LMC555 is also available in a chip sized package (8 Bump DSBGA) using TI's DSBGA package technology. The LMC555 offers the same capability of generating accurate time delays and frequencies as the LM555 but with much lower power dissipation and supply current spikes. When operated as a one-shot, the time delay is precisely controlled by a single external resistor and capacitor. In the stable mode the oscillation frequency and duty cycle are accurately set by two external resistors and one capacitor. The use of Texas Instruments' LMCMOS process extends both the frequency range and low supply capability.



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Connection Diagram

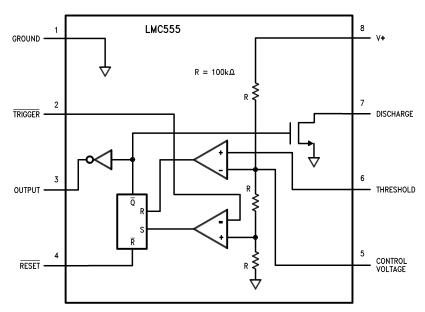


Figure 1. 8-Pin SOIC, VSSOP, PDIP Top View

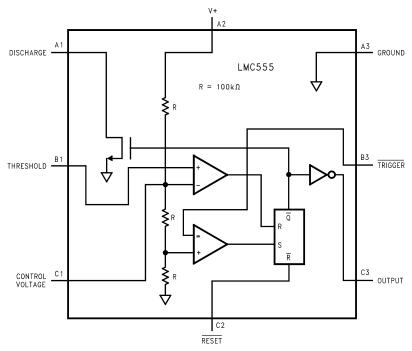


Figure 2. 8-Bump DSBGA Top View (Bump Side Down)



Table 1. Pin Descriptions

Dia Nama	Package Pin Numbers			
Pin Name	8-Pin SOIC, VSSOP, and PDIP	8-Bump DSBGA		
GND	1	A3		
Trigger	2	B3		
Output	3	C3		
Reset	4	C2		
Control Voltage	5	C1		
Threshold	6	B1		
Discharge	7	A1		
V+	8	A2		



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

Absolute Maximum Ratings (1)(2)(3)

- 1.5 C C 1.5 1.1 1.5 1.1 1.1 1.1 1.1 1.1 1.1 1.1	
Supply Voltage, V ⁺	15V
Input Voltages, V _{TRIG} , V _{RES} , V _{CTRL} , V _{THRESH}	-0.3V to V _S + 0.3 V
Output Voltages, V _O , V _{DIS}	15V
Output Current I _O , I _{DIS}	100 mA
Storage Temperature Range	−65°C to +150°C
Soldering specification for PDIP package:	
Soldering (10 seconds)	260°C
Soldering specification for all other packages:	
see product folder at www.ti.com and http://www.ti.com/lit/SNOA549	

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not ensure specific performance limits. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which ensure specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not ensured for parameters where no limit is given, however, the typical value is a good indication of device performance.
- (2) See AN-1112 (SNVA009) for DSBGA considerations.
- 3) If Military/Aerospace specified devices are required, please contact the TI Sales Office/Distributors for availability and specifications.

Operating Ratings⁽¹⁾⁽²⁾

Temperature Range	
LMC555IM	-40°C to +125°C
LMC555CM/MM/N/TP	-40°C to +85°C
Thermal Resistance $(\theta_{JA})^{-(1)}$	
SOIC, 8-Pin	169°C/W
VSSOP, 8-Pin	225°C/W
PDIP, 8-Pin	111°C/W
8-Bump DSBGA	220°C/W
Maximum Allowable Power Dissipation @25°C	
PDIP-8	1126 mW
SOIC-8	740 mW
VSSOP-8	555 mW
8-Bump DSBGA	568 mW

⁽¹⁾ Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not ensure specific performance limits. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which ensure specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not ensured for parameters where no limit is given, however, the typical value is a good indication of device performance.

(2) See AN-1112 (SNVA009) for DSBGA considerations.



Electrical Characteristics (1) (2)

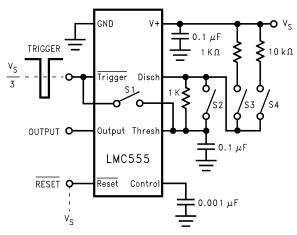
Test Circuit, T = 25°C, all switches open, \overline{RESET} to V_S unless otherwise noted

	Parameter	Test Conditions	Min	Тур	Max	Units (Limits)
I _S	Supply Current	$V_S = 1.5V$ $V_S = 5V$ $V_S = 12V$		50 100 150	150 250 400	μА
V _{CTRL}	Control Voltage	$V_S = 1.5V$ $V_S = 5V$ $V_S = 12V$	0.8 2.9 7.4	1.0 3.3 8.0	1.2 3.8 8.6	V
V _{DIS}	Discharge Saturation Voltage	$V_S = 1.5V$, $I_{DIS} = 1$ mA $V_S = 5V$, $I_{DIS} = 10$ mA		75 150	150 300	mV
V _{OL}	Output Voltage (Low)	$V_S = 1.5V, I_O = 1 \text{ mA}$ $V_S = 5V, I_O = 8 \text{ mA}$ $V_S = 12V, I_O = 50 \text{ mA}$		0.2 0.3 1.0	0.4 0.6 2.0	V
V _{OH}	Output Voltage (High)	$V_S = 1.5V$, $I_O = -0.25$ mA $V_S = 5V$, $I_O = -2$ mA $V_S = 12V$, $I_O = -10$ mA	1.0 4.4 10.5	1.25 4.7 11.3		V
V_{TRIG}	Trigger Voltage	V _S = 1.5V V _S = 12V	0.4 3.7	0.5 4.0	0.6 4.3	V
I _{TRIG}	Trigger Current	$V_S = 5V$		10		pA
V _{RES}	Reset Voltage	V _S = 1.5V ⁽³⁾ V _S = 12V	0.4 0.4	0.7 0.75	1.0 1.1	V
I _{RES}	Reset Current	V _S = 5V		10		pA
I _{THRESH}	Threshold Current	V _S = 5V		10		pA
I _{DIS}	Discharge Leakage	V _S = 12V		1.0	100	nA
t	Timing Accuracy	$ \begin{array}{l} \text{SW 2, 4 Closed} \\ \text{V}_{\text{S}} = \text{1.5V} \\ \text{V}_{\text{S}} = \text{5V} \\ \text{V}_{\text{S}} = \text{12V} \end{array} $	0.9 1.0 1.0	1.1 1.1 1.1	1.25 1.20 1.25	ms
Δt/ΔV _S	Timing Shift with Supply	V _S = 5V ± 1V		0.3		%/V
Δt/ΔΤ	Timing Shift with Temperature	V _S = 5V		75		ppm/°C
f_A	Astable Frequency	SW 1, 3 Closed, V _S = 12V	4.0	4.8	5.6	kHz
f _{MAX}	Maximum Frequency	Max. Freq. Test Circuit, V _S = 5V		3.0		MHz
t _R , t _F	Output Rise and Fall Times	Max. Freq. Test Circuit V _S = 5V, C _L = 10 pF		15		ns
t _{PD}	Trigger Propagation Delay	V _S = 5V, Measure Delay from Trigger to Output		100		ns

If the $\overline{\text{RESET}}$ pin is to be used at temperatures of -20°C and below V_S is required to be 2.0V or greater.

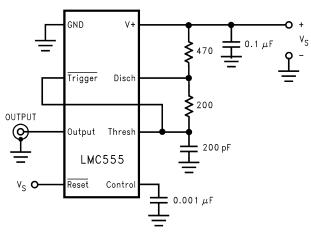
 ⁽¹⁾ All voltages are measured with respect to the ground pin, unless otherwise specified.
(2) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not ensure specific performance limits. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which ensure specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not ensured for parameters where no limit is given, however, the typical value is a good indication of device performance.





For device pinout, please see Table 1.

Figure 3. Test Circuit



For device pinout, please see Table 1.

Figure 4. Maximum Frequency Test Circuit



APPLICATION INFORMATION

MONOSTABLE OPERATION

In this mode of operation, the timer functions as a one-shot (Figure 5). The external capacitor is initially held discharged by internal circuitry. Upon application of a negative trigger pulse of less than $1/3 \text{ V}_S$ to the Trigger terminal, the flip-flop is set which both releases the short circuit across the capacitor and drives the output high.

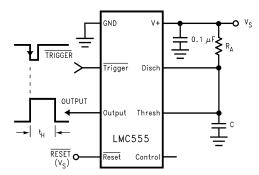
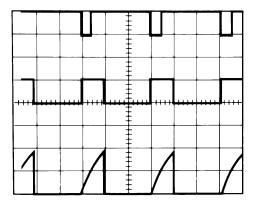


Figure 5. Monostable (One-Shot)

The voltage across the capacitor then increases exponentially for a period of $t_H = 1.1~R_AC$, which is also the time that the output stays high, at the end of which time the voltage equals $2/3~V_S$. The comparator then resets the flip-flop which in turn discharges the capacitor and drives the output to its low state. Figure 6 shows the waveforms generated in this mode of operation. Since the charge and the threshold level of the comparator are both directly proportional to supply voltage, the timing internal is independent of supply.



 V_{CC} = 5V TIME = 0.1 ms/Div. R_A = 9.1 k Ω C = 0.01 µF

V_{CC} = 5V Top Trace: Input 5 V/Div. TIME = 0.1 ms/Div. Middle Trace: Output 5 V/Div.

Bottom Trace: Capacitor Voltage 2 V/Div.

Figure 6. Monostable Waveforms

Reset overrides Trigger, which can override threshold. Therefore the trigger pulse must be shorter than the desired $t_{\rm H}$. The minimum pulse width for the Trigger is 20ns, and it is 400ns for the Reset. During the timing cycle when the output is high, the further application of a trigger pulse will not effect the circuit so long as the trigger input is returned high at least 10 μ s before the end of the timing interval. However the circuit can be reset during this time by the application of a negative pulse to the reset terminal. The output will then remain in the low state until a trigger pulse is again applied.

When the reset function is not use, it is recommended that it be connected to V_+ to avoid any possibility of false triggering. Figure 7 is a nomograph for easy determination of RC values for various time delays.

NOTE

In monstable operation, the trigger should be driven high before the end of timing cycle.



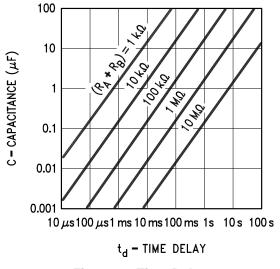


Figure 7. Time Delay

ASTABLE OPERATION

If the circuit is connected as shown in Figure 8 ($\overline{\text{Trigger}}$ and Threshold terminals connected together) it will trigger itself and free run as a multivibrator. The external capacitor charges through $R_A + R_B$ and discharges through R_B . Thus the duty cycle may be precisely set by the ratio of these two resistors.

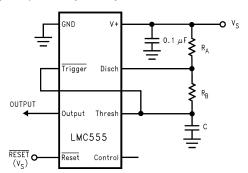
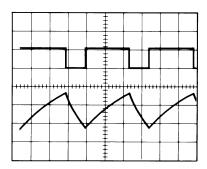


Figure 8. Astable (Variable Duty Cycle Oscillator)

In this mode of operation, the capacitor charges and discharges between $1/3 \text{ V}_S$ and $2/3 \text{ V}_S$. As in the triggered mode, the charge and discharge times, and therefore the frequency are independent of the supply voltage.

Figure 9 shows the waveform generated in this mode of operation.





 $V_{CC} = 5V$ TIME = 20 µs/Div. Top Trace: Output 5 V/Div.

Bottom Trace: Capacitor Voltage 1 V/Div.

 $R_A = 3.9 \text{ k}\Omega$ $R_B = 9 \text{ k}\Omega$ $C = 0.01 \mu\text{F}$

Figure 9. Astable Waveforms

The charge time (output high) is given by

$$t_1 = 0.693 (R_A + R_B)C$$
 (1)

And the discharge time (output low) by:

$$t_2 = 0.693 (R_B)C$$
 (2)

Thus the total period is:

$$T = t_1 + t_2 = 0.693 (R_A + 2R_B)C$$
 (3)

The frequency of oscillation is:

$$f = \frac{1}{T} = \frac{1.44}{(R_A + 2R_B)C}$$
 (4)

Figure 10 may be used for quick determination of these RC Values. The duty cycle, as a fraction of total period that the output is low, is:

$$D = \frac{R_B}{R_A + 2R_B} \tag{5}$$

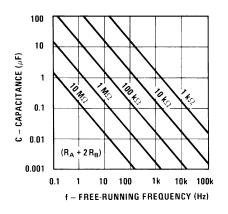
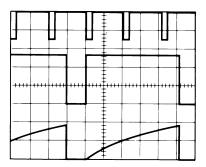


Figure 10. Free Running Frequency



FREQUENCY DIVIDER

The monostable circuit of Figure 5 can be used as a frequency divider by adjusting the length of the timing cycle. Figure 11 shows the waveforms generated in a divide by three circuit.



 $V_{CC} = 5V$ $R_A = 9.1 \text{ k}\Omega$ $C = 0.01 \mu F$

Top Trace: Input 4 V/Div. TIME = 20 μ s/Div. Middle Trace: Output 2 V/Div. Bottom Trace: Capacitor 2 V/Div.

Figure 11. Frequency Divider Waveforms

PULSE WIDTH MODULATOR

When the timer is connected in the monostable mode and triggered with a continuous pulse train, the output pulse width can be modulated by a signal applied to the Control Voltage Terminal. Figure 12 shows the circuit, and in Figure 13 are some waveform examples.

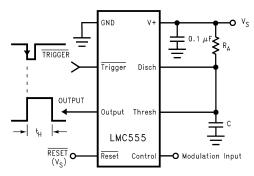
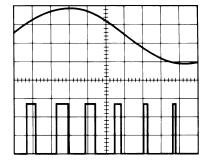


Figure 12. Pulse Width Modulator



 $V_{CC} = 5V$ $R_A = 9.1 \text{ k}\Omega$ $C = 0.01 \mu F$

Top Trace: Modulation 1 V/Div. TIME = 0.2 ms/Div. Bottom Trace: Output Voltage 2 V/Div.

Figure 13. Pulse Width Modulator Waveforms



PULSE POSITION MODULATOR

This application uses the timer connected for a stable operation, as in Figure 14, with a modulating signal again applied to the control voltage terminal. The pulse position varies with the modulating signal, since the threshold voltage and hence the time delay is varied. Figure 15 shows the waveforms generated for a triangle wave modulation signal.

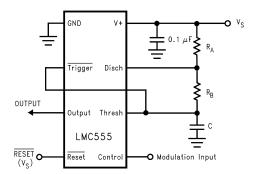
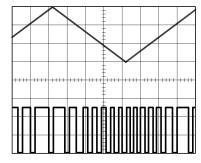


Figure 14. Pulse Position Modulator



 V_{CC} = 5V TIME = 0.1 ms/Div. R_A = 3.9 k Ω

 $R_A = 3.9 \text{ k}\Omega$ $R_B = 3 \text{ k}\Omega$ $C = 0.01 \mu\text{F}$

Top Trace: Modulation Input 1 V/Div. Bottom Trace: Output Voltage 2 V/Div.

Figure 15. Pulse Position Modulator Waveforms

50% DUTY CYCLE OSCILLATOR

The frequency of oscillation is

$$f = 1/(1.4 R_CC)$$

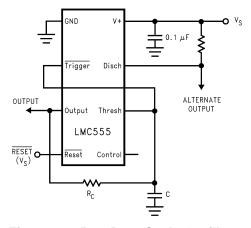


Figure 16. 50% Duty Cycle Oscillator



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REVISION HISTORY

Changes from Revision I (March 2013) to Revision J		age
•	Changed layout of National Data Sheet to TI format	. 10

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