Monolithic Digital IC

LB1889, 1889M, 1889D

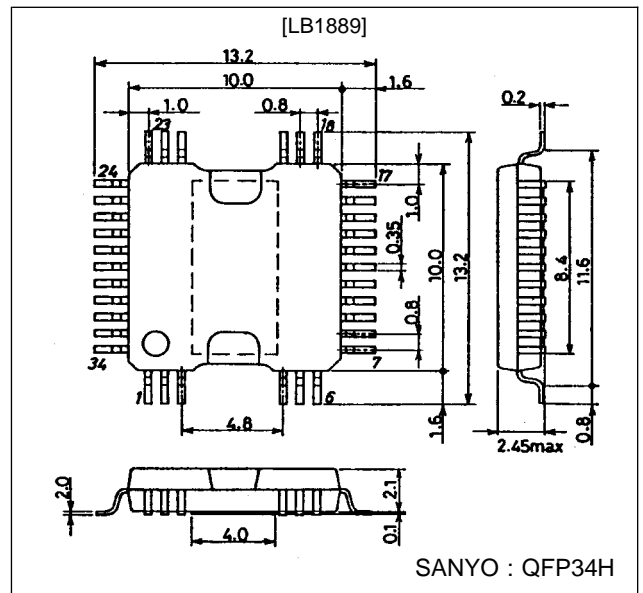## 3-phase Brushless Motor Driver for VTR Capstans

Functions

- 3-phase full-wave current linear drive system
- Torque ripple correction circuit built in (variable compensation ratio)
- Current limiting circuit built in/with control characteristic gain switch
- Output stage upper/lower oversaturation prevention circuit built in (no external capacitor required)
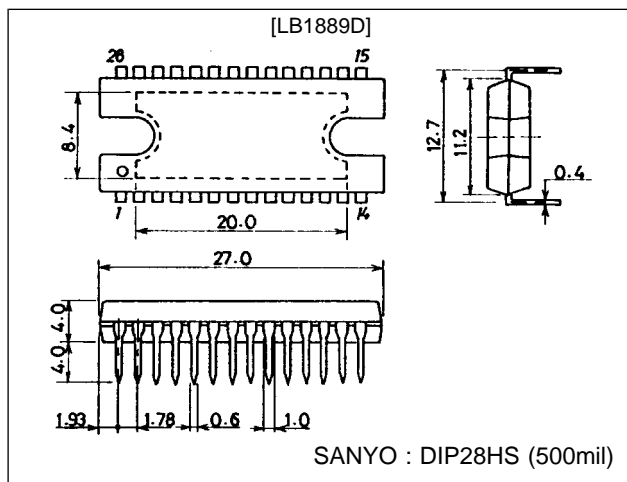- FG amplifier built in
- Thermal shutdown circuit built in
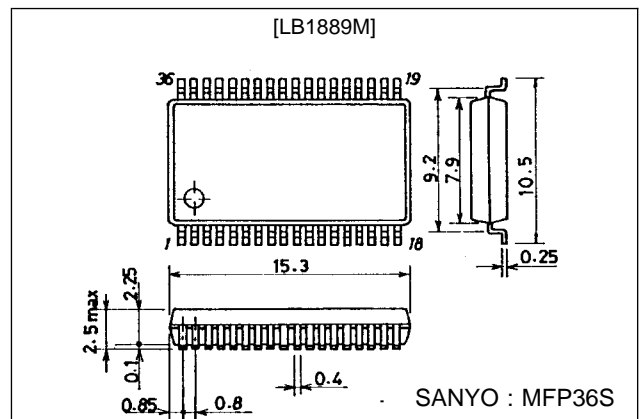
Package Dimensions

unit : mm

3206-QFP34H

[LB1889]

SANYO : QFP34H

3147A-DIP28HS

[LB1889D]

SANYO : DIP28HS (500mil)

3129-MFP36S

[LB1889M]

SANYO : MFP36S

Specifications

Absolute Maximum Ratings at Ta = 25 °C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V_{CC} max		7	V
	V_S max		24	V
Maximum output current	I_O max		1.3	A
Allowable power dissipation	Pd max	Arbitrarily large heat sink LB1889	12.5	W
		Arbitrarily large heat sink LB1889D	15.0	W
		Independent IC LB1889	0.77	W
		Independent IC LB1889M	0.95	W
		Independent IC LB1889D	3.0	W
Operating temperature	Topr		−20 to +75	°C
Storage temperature	Tstg		−55 to +150	°C

Allowable Operating Ranges at Ta = 25 °C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V_S		5 to 22	V
	V_{CC}		4.5 to 5.5	V
Hall input amplitude	V_{HALL}	Between Hall inputs	±30 to ±80	mV_{0-P}
GSENSE input range	V_{GSENSE}	Relative to control system GND	−0.20 to +0.20	V

Electrical Characteristics at Ta = 25 °C, V_{CC} = 5 V, V_S = 15 V

Parameter	Symbol	Conditions	min	typ	max	Unit
V_{CC} supply current	I_{CC}	$R_L = \infty$ (when stopped), V_{CTL} = 0 V, V_{LIM} = 0 V		12	18	mA
[Output]						
Output saturation voltage	$V_{Osat}1$	I_O = 500 mA, Rf = 0.5 Ω, Sink + Source $V_{CTL} = V_{LIM}$ = 5 V (with saturation prevention)		2.1	2.6	V
	$V_{Osat}2$	I_O = 1.0 A, Rf = 0.5 Ω, Sink + Source $V_{CTL} = V_{LIM}$ = 5 V (with saturation prevention)		2.6	3.5	V
Output leakage current	Ioleak				1.0	mA
[FR]						
FR pin input threshold voltage	V_{FSR}		2.25	2.50	2.75	V
FR pin input bias current	Ib (FSR)		−5.0			µA
[Control]						
CTLREF pin voltage	V_{CREF}		2.37	2.50	2.63	V
CTLREF pin input range	$V_{CREF}IN$		1.70		3.50	V
CTL pin input bias current	Ib (CTL)	V_{CTL} = 5 V, CTLREF : Open			8.0	µA
CTL pin control start voltage	V_{CTL} (ST)	With Rf = 0.5 Ω, V_{LIM} = 5 V, $I_O \geqq$ 10 mA, Hall input logic fixed, (u, v, w = H, H, L)	2.20	2.35	2.50	V
CTL pin control switch voltage	V_{CTL} (ST2)	Rf = 0.5 Ω, V_{LIM} = 5 V	3.00	3.15	3.30	V
CTL pin control Gm1	Gm1 (CTL)	With Rf = 0.5 Ω, ΔI_O = 200 mA, Hall input logic fixed, (u, v, w = H, H, L)	0.52	0.65	0.78	A/V
CTL pin control Gm2	Gm2 (CTL)	With Rf = 0.5 Ω, ΔV_{CTL} = 200 mV, Hall input logic fixed, (u, v, w = H, H, L)	1.20	1.50	1.80	A/V
[Current Limit]						
LIM current limit offset voltage	Voff (LIM)	With Rf = 0.5 Ω, V_{CTL} = 5 V, $I_O \geqq$ 10 mA, Hall input logic fixed, (u, v, w = H, H, L)	140	200	260	mV
LIM pin input bias current	Ib (LIM)	With V_{CTL} = 5 V, CTLREF : Open, V_{LIM} = 0 V	−2.5			µA
LIM pin current limit level	I lim	With Rf = 0.5 Ω, V_{CTL} = 5 V, V_{LIM} = 2.06 V, Hall input logic fixed, (u, v, w = H, H, L)	830	900	970	mA
[Hall Amplifier]						
Hall amplifier input offset voltage	Voff (HALL)		−6		+6	mV
Hall amplifier input bias current	Ib (HALL)			1.0	3.0	µA
Hall amplifier common-mode input voltage	Vcm (HALL)		1.3		3.3	V

LB1889, 1889M, 1889D

Continued from preceding page.

Parameter	Symbol	Conditions	min	typ	max	Unit
[TRC]						
Torque ripple correction factor	T_{RC}	At bottom and peak in Rf waveform at I_O = 200 mA (RF = 0.5 Ω, ADJ-OPEN) Note 2		9		%
ADJ pin voltage	Vadj		2.37	2.50	2.63	V
[FG Amplifier]						
FG amplifier input offset voltage	Voff (FG)		−8		+8	mV
FG amplifier input bias current	Ib (FG)		−100			nA
FG amplifier output saturation voltage	V_{Osat} (FG)	At internal pull-up resistor load on sink side			0.5	V
FG amplifier common-mode input voltage	V_{CM} (FG)		0.5		4.0	V
[Saturation]						
Saturation prevention circuit lower set voltage	V_{Osat} (DET)	Voltage between each OUT and Rf at I_O = 10 mA, Rf = 0.5 Ω, V_{CTL} = V_{LIM} = 5 V	0.175	0.25	0.325	V
[TSD]						
TSD operation temperature	T-TSD	(Design target) Note 1		180		°C
TSD temperature hysteresis width	ΔTSD	(Design target) Note 1		20		°C

Note 1: No measurements are performed for any values listed in the conditions column as design targets.
Note 2: The torque ripple correction factor is calculated using the Rf voltage waveform as follows.

Hall input logic settings
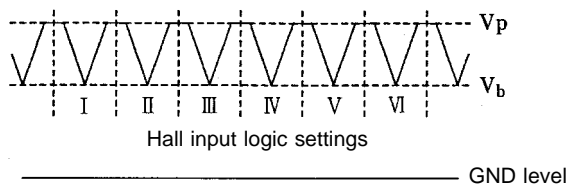
$$\text{Correction factor} = \frac{2 \times (Vp - Vb)}{Vp + Vb} \times 100 \ (\%)$$

Truth Table & Control Function

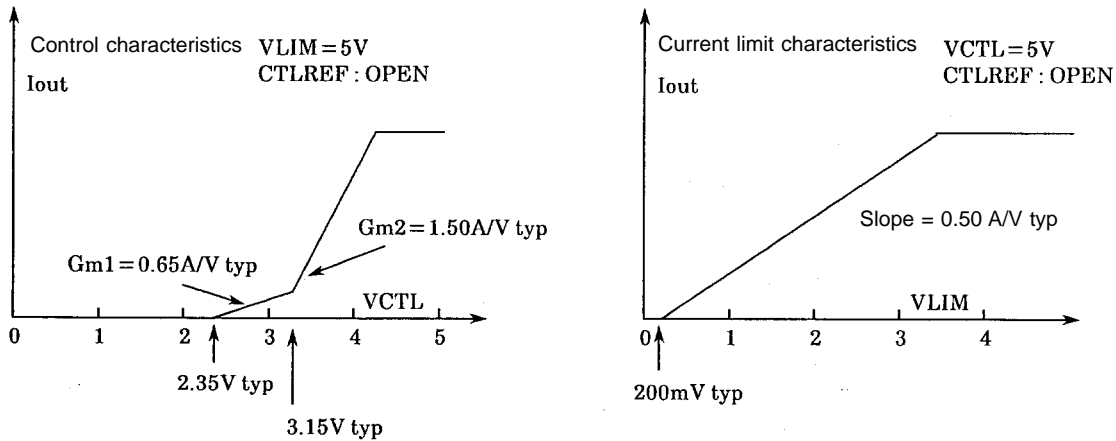|	Source → Sink	Hall input U	V	W	FR
1	V → W	H	H	L	H
	W → V				L
2	U → W	H	L	L	H
	W → U				L
3	U → V	H	L	H	H
	V → U				L
4	W → V	L	L	H	H
	V → W				L
5	W → U	L	H	H	H
	U → W				L
6	V → U	L	H	L	H
	U → V				L

Note: "H" in the FR column represents a voltage of 2.75 V or more; "L" represents a voltage of 2.25 V or less. (At V_{CC} = 5 V)
Note: "H" in the Hall input columns represents a state in which "+" has a potential which is higher by 0.01 V or more than that of the "−" phase inputs. Conversely, "L" represents a state in which "+" has a potential which is lower by 0.01 V or more than that of the "−" phase input.

Note: Since 180° energized system is used as the drive system, other phases than the sink and source phases are turned off.

Control Function & Current Limit Function

Control characteristics VLIM＝5V CTLREF : OPEN

Iout

Gm2＝1.50A/V typ

Gm1＝0.65A/V typ

VCTL

0   1   2   3   4   5

2.35V typ

3.15V typ

Current limit characteristics VCTL＝5V CTLREF : OPEN

Iout

Slope = 0.50 A/V typ

VLIM

0   1   2   3   4

200mV typ

Pin Functions

The pin number in ( ) is for MFP, that in < > is for DIP, and other than these is for QFP.

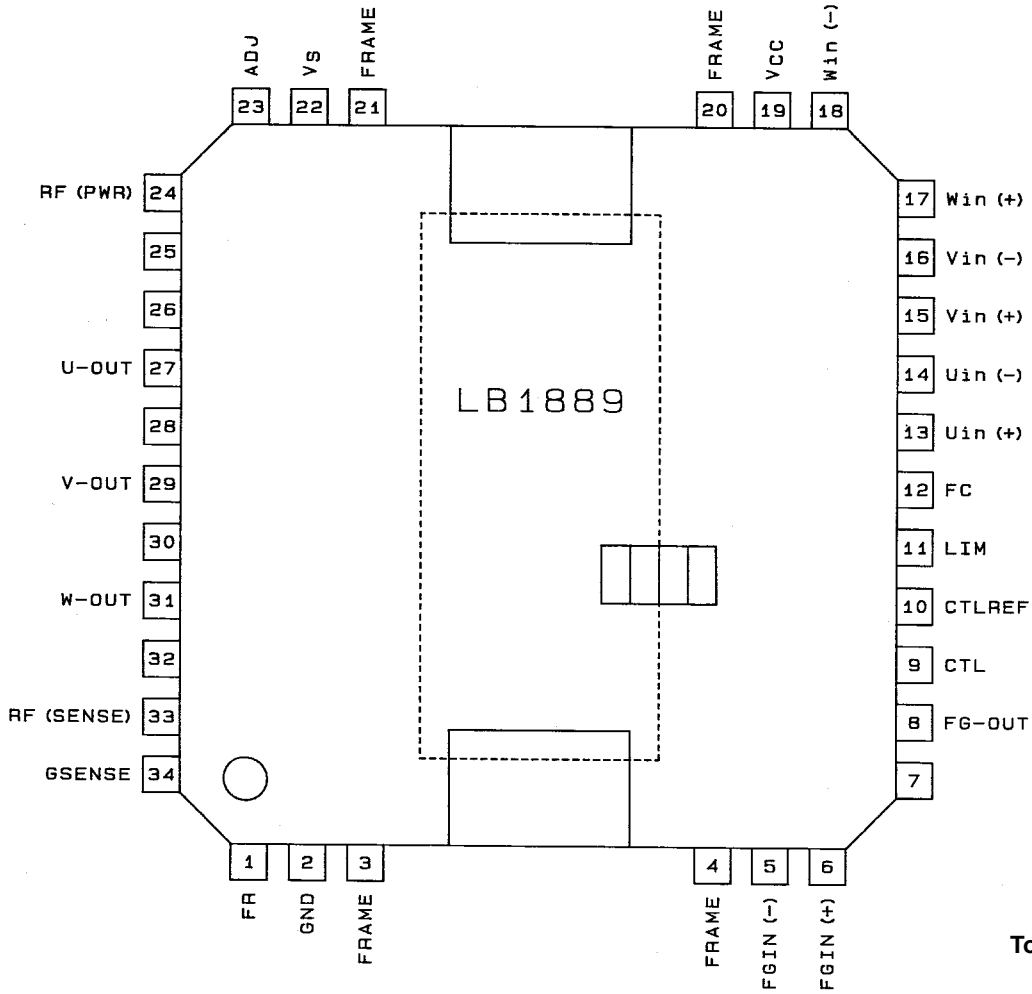| Pin name	Pin No.	Function
FR	1 (33) <26>	Forward/reverse select pin. The pin voltage selects forward/reverse. (Vth = 2.5 V typ at V_{CC} = 5 V)
GND	2 (34) <27>	GND for other than output transistor. Minimum potential of output transistor is at Rf pin.
FGin (−)	5 (3) <28>	Input pin when FG amplifier is used with inverted input. Feedback resistor is connected between this pin and FG-OUT.
FGin (+)	6 (4) <1>	Noninverting input pin when FG amplifier is used with differential input. Internal bias is not applied.
FG-OUT	8 (5) <3>	FG amplifier output pin. Resistive load provided internally.
CTL	9 (6) <4>	Speed control pin. Control is exercised by constant-current drive with current feedback applied from Rf. Gm = 0.65 A/V & 1.50 A/V typ at Rf = 0.5 Ω
CTLREF	10 (7) <5>	Control reference voltage pin. The voltage is set internally to approx. V_{CC}/2 but this can be varied by applying voltage through a low impedance (input impedance = approx. 2.5 kΩ).
LIM	11 (8) <6>	Current limiting function control pin. The output current is varied linearly by this pin voltage; slope = 0.5 A/V typ at Rf = 0.5 Ω.
FC	12 (9) <7>	Speed control loop frequency characteristic correction pin
Uin$^+$, Uin$^-$ Vin$^+$, Vin$^-$ Win$^+$, Win$^-$	13, 14 (10, 11) <8, 9> 15, 16 (12, 13) <10, 11> 17, 18 (14, 15) <12, 13>	U-phase Hall device input pin; logic "H" represents IN+ > IN−. V-phase Hall device input pin; logic "H" represents IN+ > IN−. W-phase Hall device input pin; logic "H" represents IN+ > IN−.
V_{CC}	19 (16) <14>	Power supply pin for supplying power to all circuits except output section in IC; this voltage must be stabilized so as to eliminate ripple and noise.
V_S	22 (21) <15>	Output selection power supply pin
ADJ	23 (22) <16>	Pin for external adjustment of torque ripple correction factor. When this factor is to be adjusted, a voltage is externally applied to the ADJ pin through a low impedance. If the voltage applied is increased, the factor drops; conversely, if it is reduced, the factor rises. The factor varies between 0 and 2 times that of the open state. (The voltage is set inside to approx. V_{CC}/2 internally, and the input impedance is approx. 5 kΩ.)
Rf (PWR) Rf (SNS)	24 (23) <17> 33 (31) <24>	Output current detection pin. Current feedback is applied to the control section by connecting Rf between this pin and GND. The lower oversaturation prevention circuit and torque ripple correction circuit are activated in accordance with this pin voltage. Since the oversaturation prevention level is set with this voltage, the lower oversaturation prevention effect may deteriorate in the high current range if the Rf value is reduced to an extremely low level. The PWR and SENSE pins must always be connected.
Uout Vout Wout	27 (26) <21> 29 (27) <22> 31 (28) <23>	U-phase output pin V-phase output pin (Built-in spark killer diode) W-phase output pin
GSENSE	34 (32) <25>	GND sensing pin. By connecting this pin to the neighboring GND on the Rf resistor side of the motor GND wire which contains Rf, the effect that GND common impedance exerts on Rf can be eliminated. (This pin must not be left open.)

Block Diagram
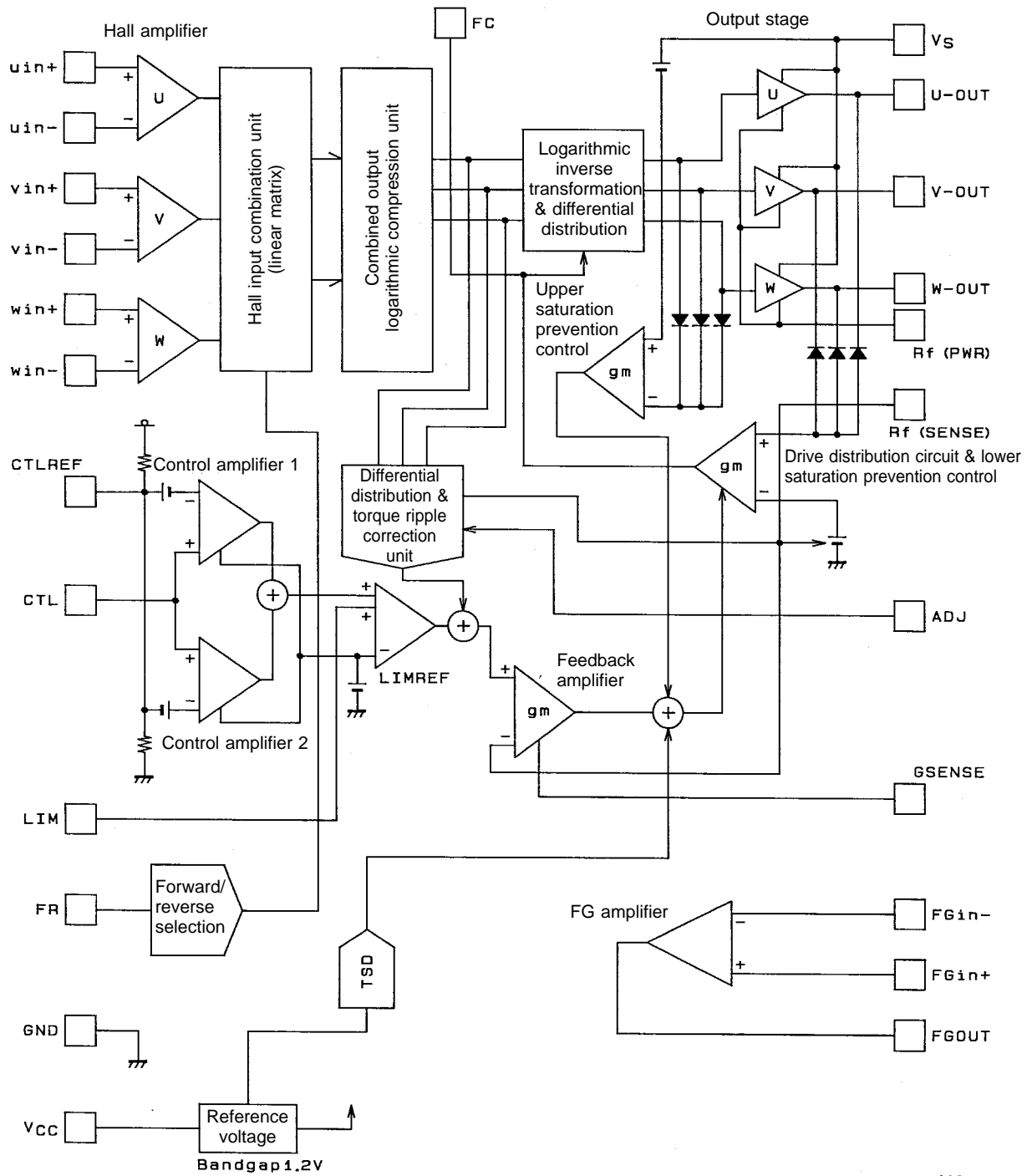
Pin Assignment [LB1889]

(PACKAGE : QFP-34H-A)
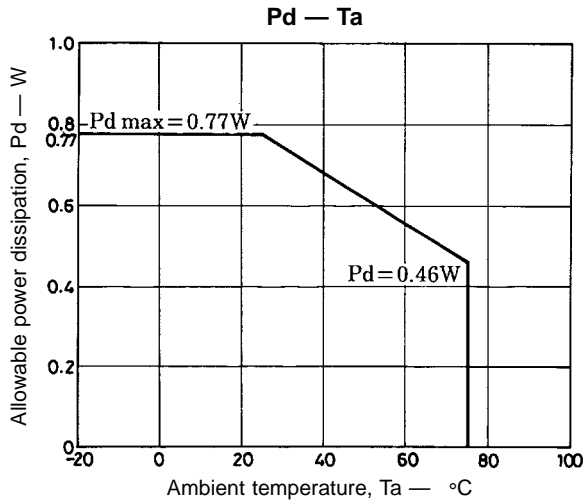

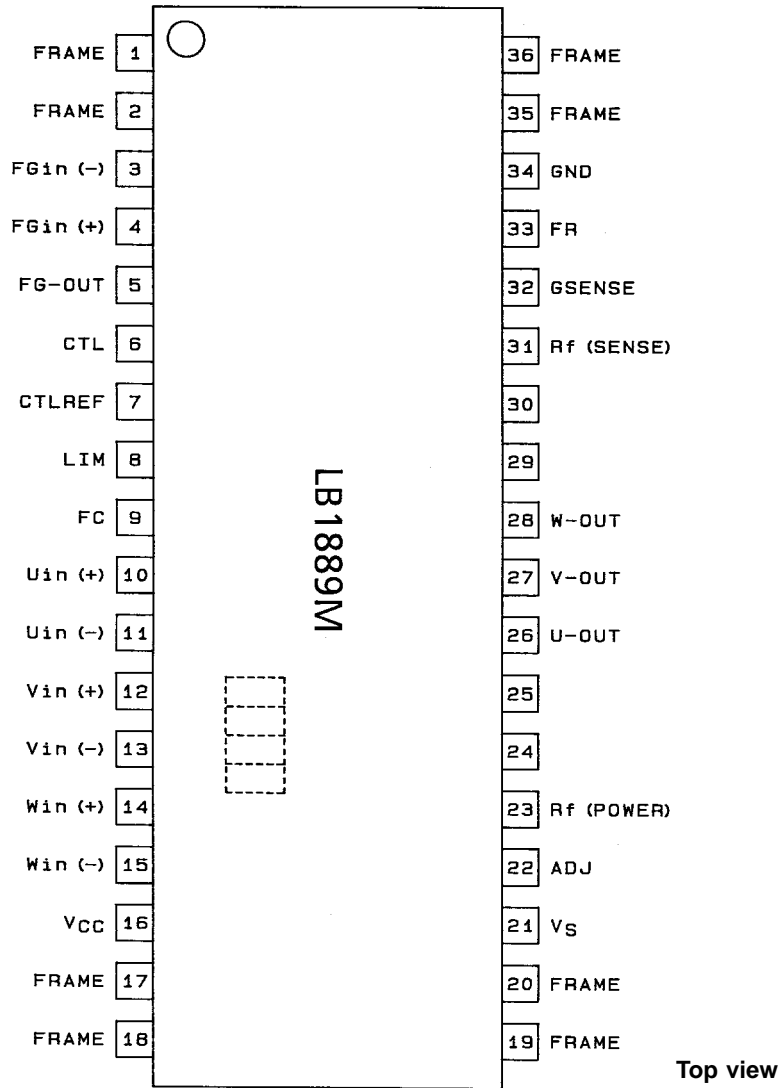Note: FRAME must be connected to GND for GND
potential stablization.

Top view

A03960

Pd — Ta
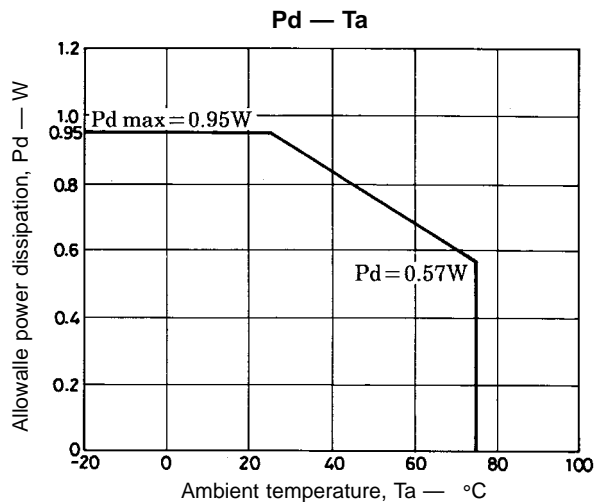

Pd max = 0.77W

Pd = 0.46W

Allowable power dissipation, Pd — W

Ambient temperature, Ta — °C

Pin Assignment [LB1889M]

(PACKAGE : MFP-36S-LF)

FRAME	1		36	FRAME
FRAME	2		35	FRAME
FGin (−)	3		34	GND
FGin (+)	4		33	FR
FG−OUT	5		32	GSENSE
CTL	6		31	Rf (SENSE)
CTLREF	7		30	
LIM	8		29	
FC	9	LB1889M	28	W−OUT
Uin (+)	10		27	V−OUT
Uin (−)	11		26	U−OUT
Vin (+)	12		25	
Vin (−)	13		24	
Win (+)	14		23	Rf (POWER)
Win (−)	15		22	ADJ
Vcc	16		21	Vs
FRAME	17		20	FRAME
FRAME	18		19	FRAME

Top view

A03961

Note: Although there is no internal connection between the FRAME pin and GND, FRAME must be connected to GND externally for GND potential stabilization.

Pd — Ta

Ambient temperature, Ta — °C

Allowalle power dissipation, Pd — W

Pd max = 0.95W

Pd = 0.57W

Pin Assignment [LB1889D]

DIP-28HS bent opposite
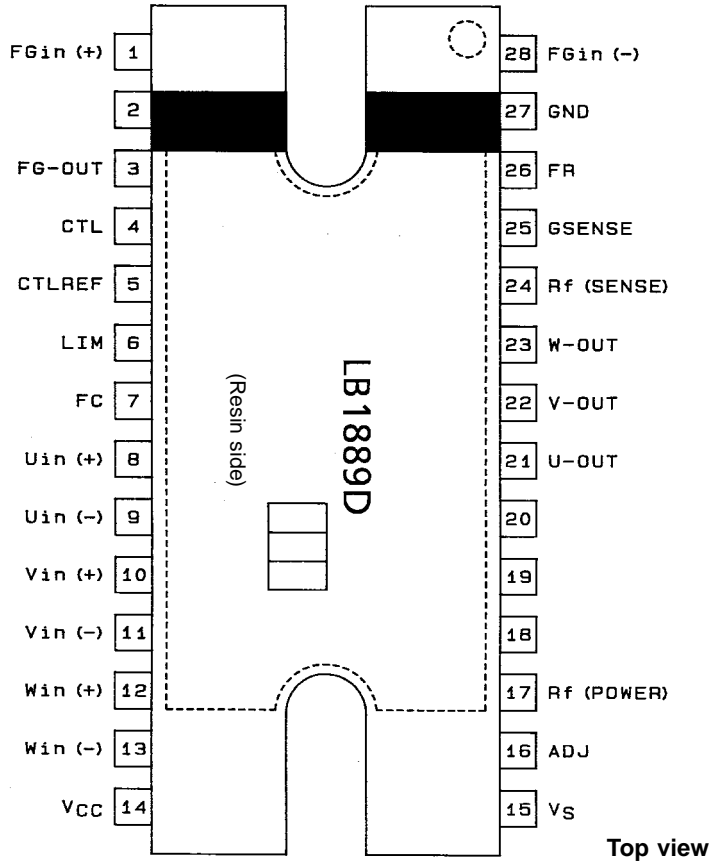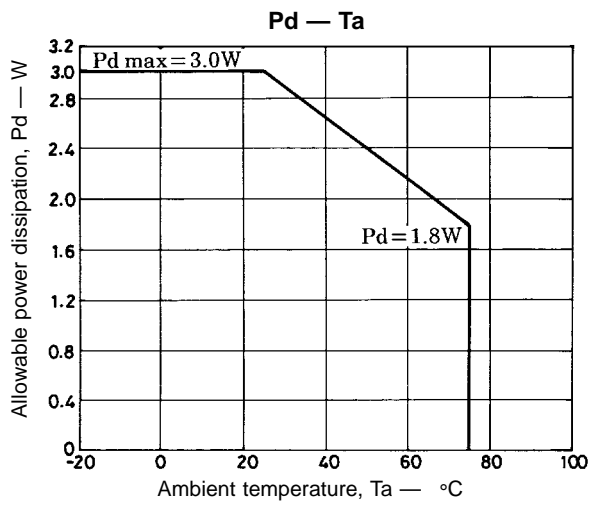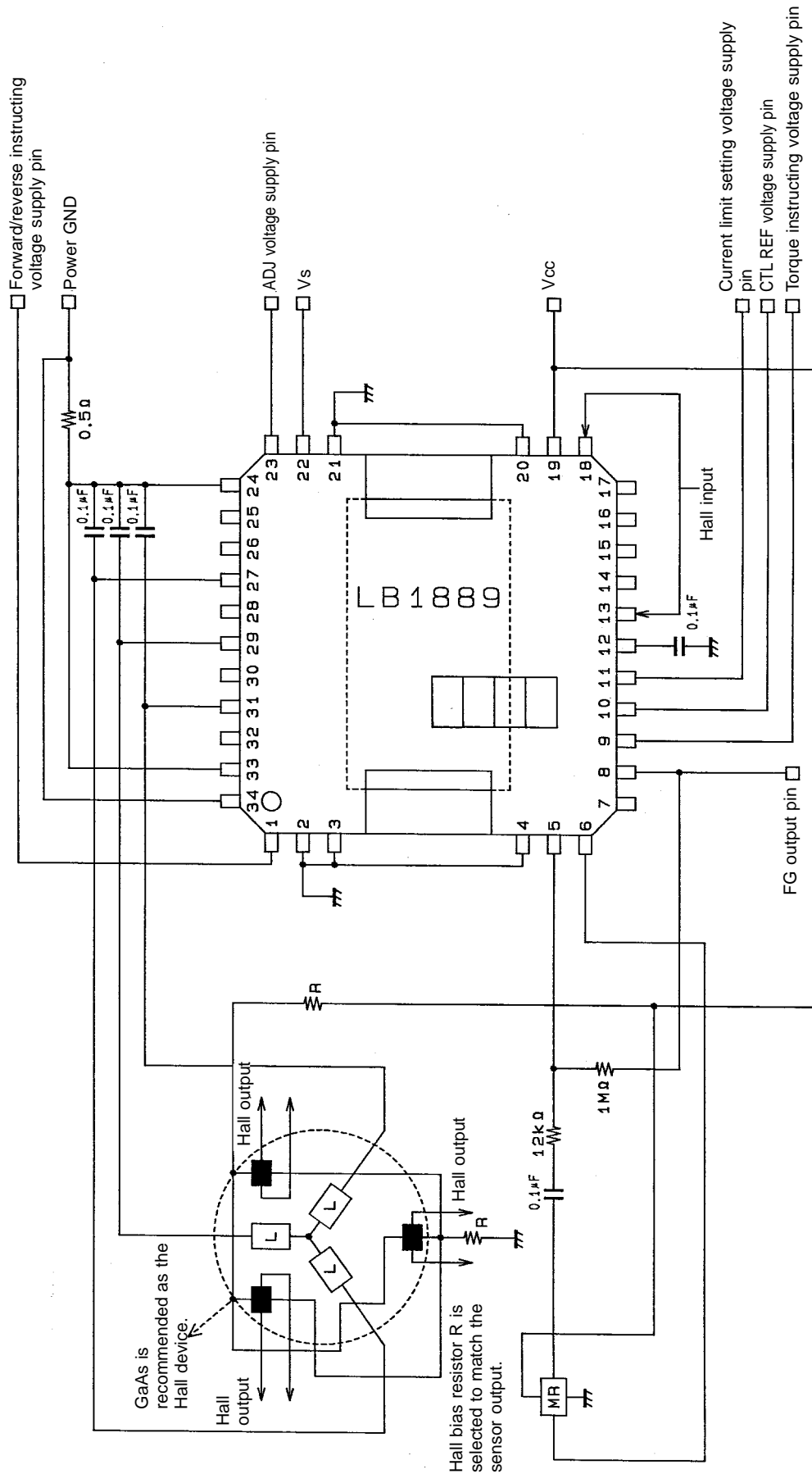
Pin	Name		Pin	Name
1	FGin (+)		28	FGin (−)
2			27	GND
3	FG-OUT		26	FR
4	CTL		25	GSENSE
5	CTLREF		24	Rf (SENSE)
6	LIM		23	W-OUT
7	FC		22	V-OUT
8	Uin (+)		21	U-OUT
9	Uin (−)		20	
10	Vin (+)		19	
11	Vin (−)		18	
12	Win (+)		17	Rf (POWER)
13	Win (−)		16	ADJ
14	Vcc		15	Vs

(Resin side)

LB1889D

Top view

A03962

Pd — Ta

Pd max = 3.0W

Pd = 1.8W

Allowable power dissipation, Pd — W

Ambient temperature, Ta — °C

Sample Application Circuit [LB1889]

Note: The constants provided in this sample application circuit are provided by way of example and are not intended to guarantee the characteristics.

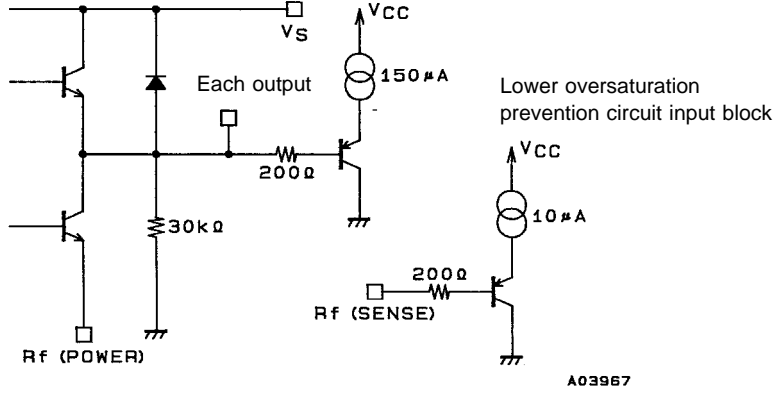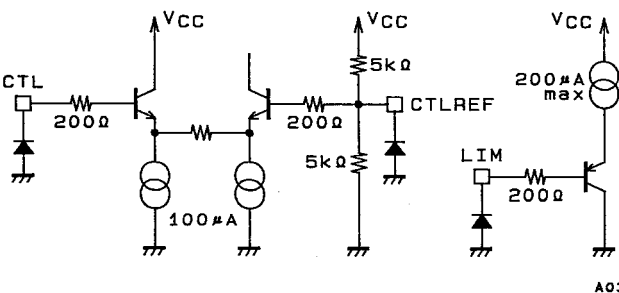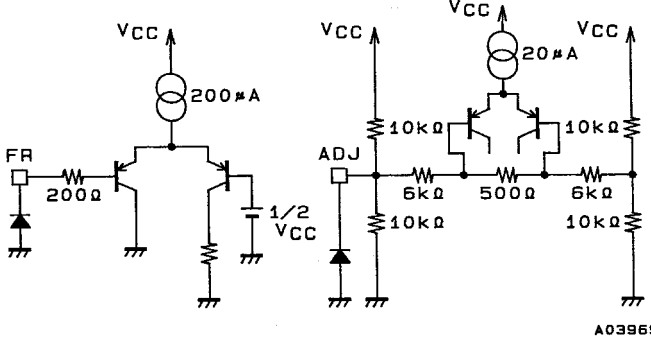## Sample Application Circuit [LB1889M]

A03964

Forward/reverse instructing voltage supply pin

Power GND

ADJ voltage supply pin

Vs

Vcc

Current limit setting voltage supply pin

CTL REF voltage supply pin

Torque instructing voltage supply pin

0.5 Ω

0.1 µF
0.1 µF
0.1 µF

LB1889M
TOP VIEW

19

18

Hall input

0.1 µF

36

1

FG output pin

1 MΩ

R

Hall output

Hall output

GaAs is recommended as the Hall device.

Hall output

R

Hall bias resistor R is selected to match the sensor output.

12 kΩ

MR

0.1 µF
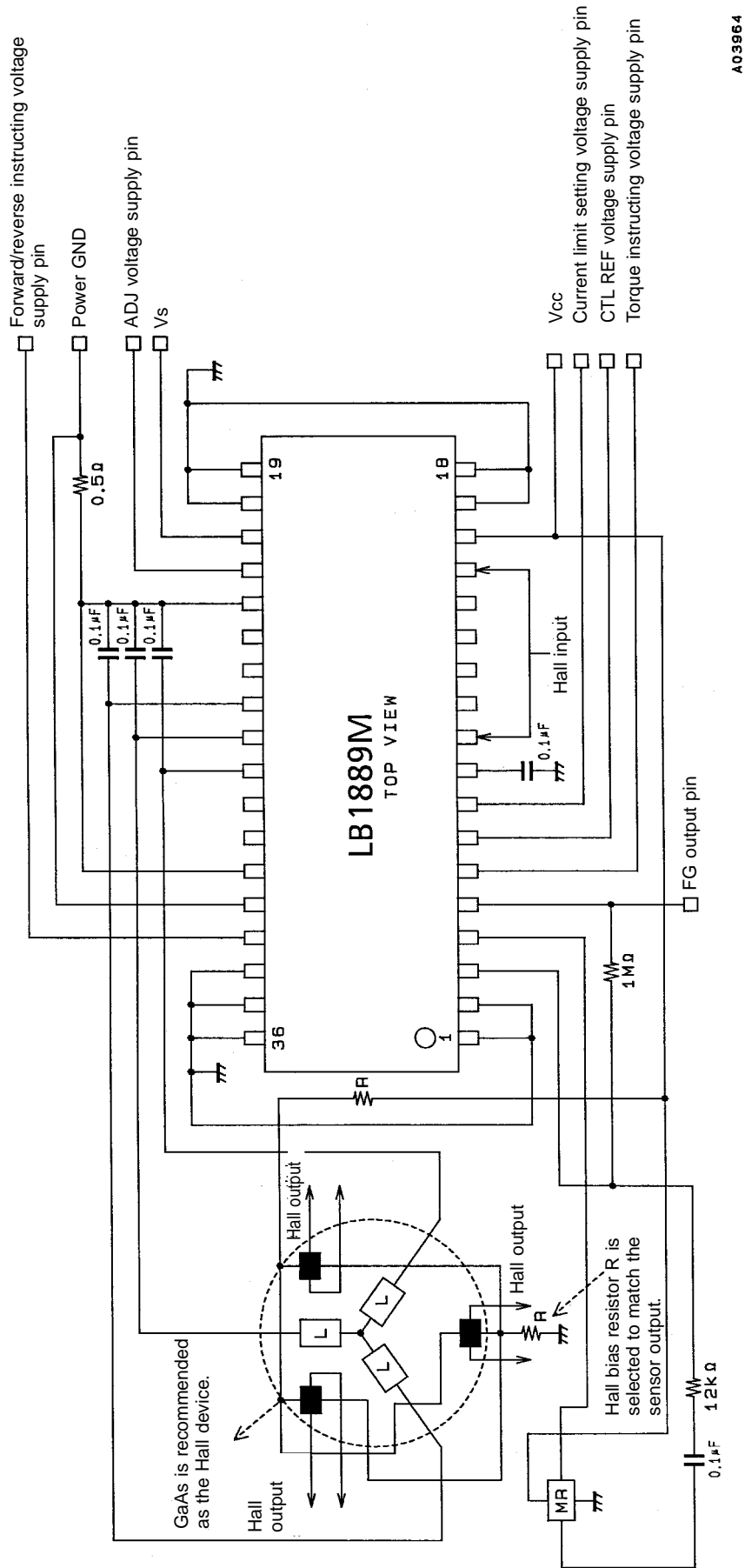
Note: The constants provided in this sample application circuit are provided by way of example and are not intended to guarantee the characteristics.

Sample Application Circuit [LB1889D]

A03965

LB1889D
(Resign side)

Forward/reverse instructing voltage supply pin

Power GND

ADJ voltage supply pin

Vs

Vcc

Current limit setting voltage supply pin

CTL REF voltage supply pin

Torque instructing voltage supply pin

Hall input

0.1μF

0.5Ω

0.1μF 0.1μF 0.1μF

FG output pin

R

1MΩ

Hall output

Hall output

Hall output

GaAs is recommended as the Hall device.

Hall bias resistor R is selected to match the sensor output.

12kΩ

0.1μF

MR

R

Note: The constants provided in this sample application circuit are provided by way of example and are not intended to guarantee the characteristics.

Pin Input/Output Equivalent Circuit

Pin name	Input/Output Equivalent Circuit
Uin (+) Uin (−) Vin (+) Vin (−) Win (+) Win (−)	
U-OUT V-OUT W-OUT V_S Rf (POWER) Rf (SENSE)	
CTL LIM CTLREF	
FR ADJ	

Continued from preceding page.

Pin name	Input/Output Equivalent Circuit
FGin (–) FGin (+)	
FGOUT FC	