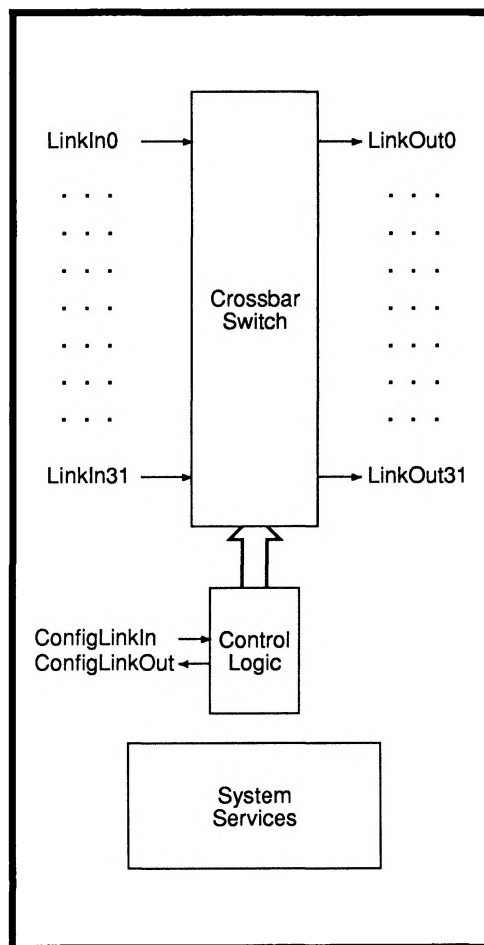# IMS C004
programmable link switch

Engineering Data

FEATURES

Standard INMOS serial links
32 way crossbar switch
Regenerates input signal
Cascadable to any depth
No loss of signal integrity
10 or 20 Mbits/sec operating speed
Separate INMOS configuration link
Single +5V ±5% power supply
TTL and CMOS compatibility
1W power dissipation
Standard 84 pin ceramic PGA
MIL-STD-883C device is available

APPLICATIONS

Programmable crossbar switch
Component of larger switch
Reconfigurable supercomputers
Message routing system
High speed multiprocessor systems
Telecommunications
Robotics
Fault tolerant systems
Additional links for transputers

1   Introduction

The INMOS communication link is a high speed system interconnect which provides full duplex communication between members of the INMOS transputer family, according to the INMOS serial link protocol. The IMS C004, a member of this family, is a transparent programmable link switch designed to provide a full crossbar switch between 32 link inputs and 32 link outputs.

The IMS C004 will switch links running at either the standard speed of 10 Mbits/sec or at the higher speed of 20 Mbits/sec. It introduces, on average, only a 1.75 bit time delay on the signal. Link switches can be cascaded to any depth without loss of signal integrity and can be used to construct reconfigurable networks of arbitrary size. The switch is programmed via a separate serial link called the *configuration link*.

All INMOS products which use communication links, regardless of device type, support a standard communications frequency of 10 Mbits/sec; most products also support 20 Mbits/sec. Products of different type or performance can, therefore, be interconnected directly and future systems will be able to communicate directly with those of today.
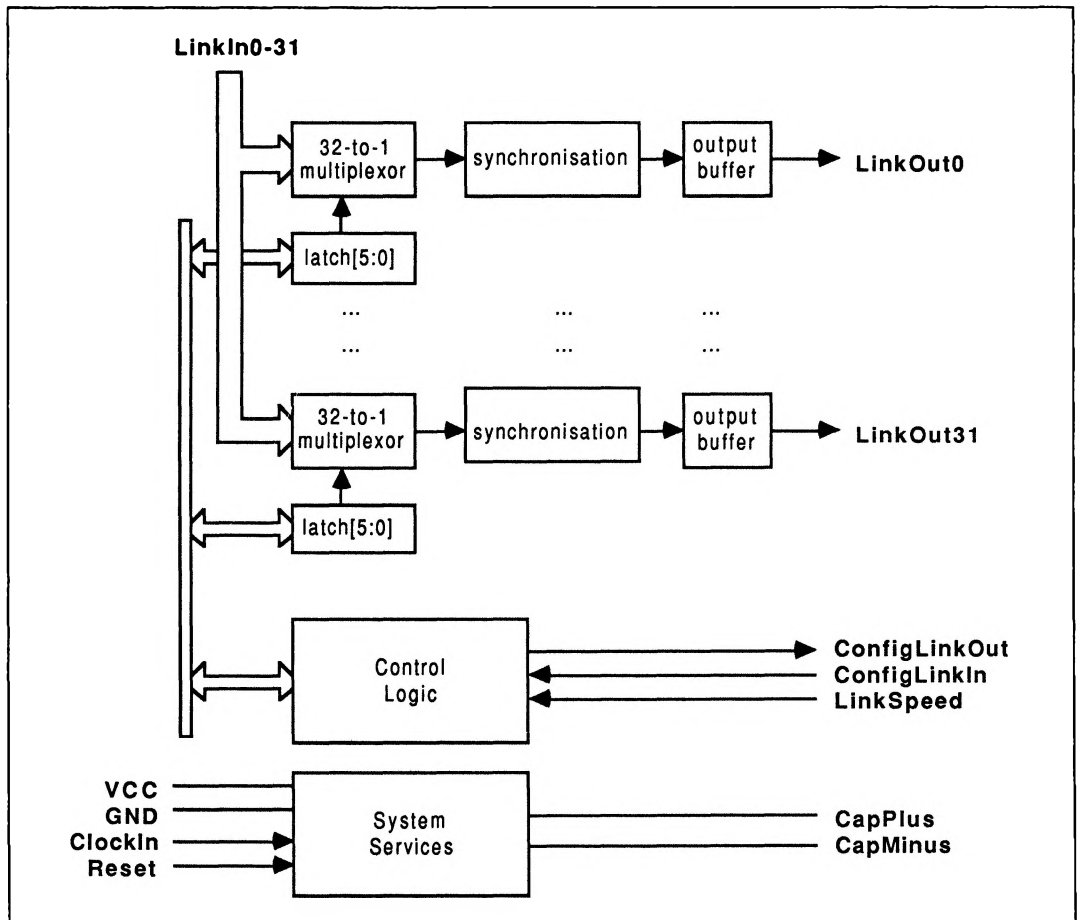

Figure 1.1 IMS C004 block diagram

2   Pin designations

Table 2.1 IMS C004 system services

Pin	In/Out	Function
VCC, GND		Power supply and return
CapPlus, CapMinus		External capacitor for internal clock power supply
ClockIn	in	Input clock
Reset	in	System reset
DoNotWire		Must not be wired

Table 2.2 IMS C004 configuration

Pin	In/Out	Function
ConfigLinkIn	in	INMOS configuration link input
ConfigLinkOut	out	INMOS configuration link output

Table 2.3 IMS C004 link

Pin	In/Out	Function
LinkIn0-31	in	INMOS link inputs to the switch
LinkOut0-31	out	INMOS link outputs from the switch
LinkSpeed	in	Link speed selection

Signal names are prefixed by **not** if they are active low, otherwise they are active high.
Pinout details for various packages are given on page 498.

3 System services

System services include all the necessary logic to start up and maintain the IMS C004.

3.1 Power

Power is supplied to the device via the **VCC** and **GND** pins. Several of each are provided to minimise inductance within the package. All supply pins must be connected. The supply must be decoupled close to the chip by at least one 100 nF low inductance (e.g. ceramic) capacitor between **VCC** and **GND**. Four layer boards are recommended; if two layer boards are used, extra care should be taken in decoupling.

Input voltages must not exceed specification with respect to **VCC** and **GND**, even during power-up and power-down ramping, otherwise *latchup* can occur. CMOS devices can be permanently damaged by excessive periods of latchup.

3.2 CapPlus, CapMinus

The internally derived power supply for internal clocks requires an external low leakage, low inductance $1\,\mu F$ capacitor to be connected between **CapPlus** and **CapMinus**. A ceramic capacitor is preferred, with an impedance less than 3 Ohms between 100 KHz and 10 MHz. If a polarised capacitor is used the negative terminal should be connected to **CapMinus**. Total PCB track length should be less than 50 mm. The connections must not touch power supplies or other noise sources.
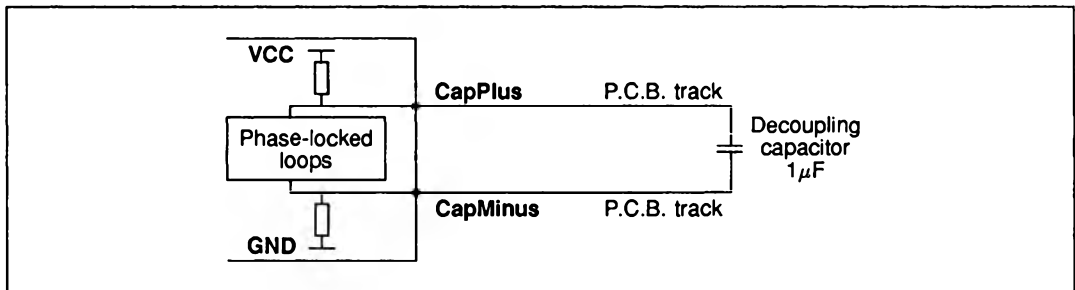

Figure 3.1 Recommended PLL decoupling

3.3 ClockIn

Transputer family components use a standard clock frequency, supplied by the user on the **ClockIn** input. The nominal frequency of this clock for all transputer family components is 5 MHz, regardless of device type, transputer word length or processor cycle time. High frequency internal clocks are derived from **ClockIn**, simplifying system design and avoiding problems of distributing high speed clocks externally.

A number of transputer family devices may be connected to a common clock, or may have individual clocks providing each one meets the specified stability criteria. In a multi-clock system the relative phasing of **ClockIn** clocks is not important, due to the asynchronous nature of the links. Mark/space ratio is unimportant provided the specified limits of **ClockIn** pulse widths are met.

Oscillator stability is important. **ClockIn** must be derived from a crystal oscillator; RC oscillators are not sufficiently stable. **ClockIn** must not be distributed through a long chain of buffers. Clock edges must be monotonic and remain within the specified voltage and time limits.

Table 3.1 Input clock

SYMBOL	PARAMETER	MIN	NOM	MAX	UNITS	NOTE
TDCLDCH	ClockIn pulse width low	40			ns	1
TDCHDCL	ClockIn pulse width high	40			ns	1
TDCLDCL	ClockIn period		200		ns	1,2,4
TDCerror	ClockIn timing error			±0.5	ns	1,3
TDC1DC2	Difference in ClockIn for 2 linked devices			400	ppm	1,4
TDCr	ClockIn rise time			10	ns	1,5
TDCf	ClockIn fall time			8	ns	1,5

Notes

1 These paramters are not tested.

2 Measured between corresponding points on consecutive falling edges.

3 Variation of individual falling edges from their nominal times.

4 This value allows the use of 200ppm crystal oscillators for two devices connected together by a link.

5 Clock transitions must be monotonic within the range **VIH** to **VIL** (table 7.3).
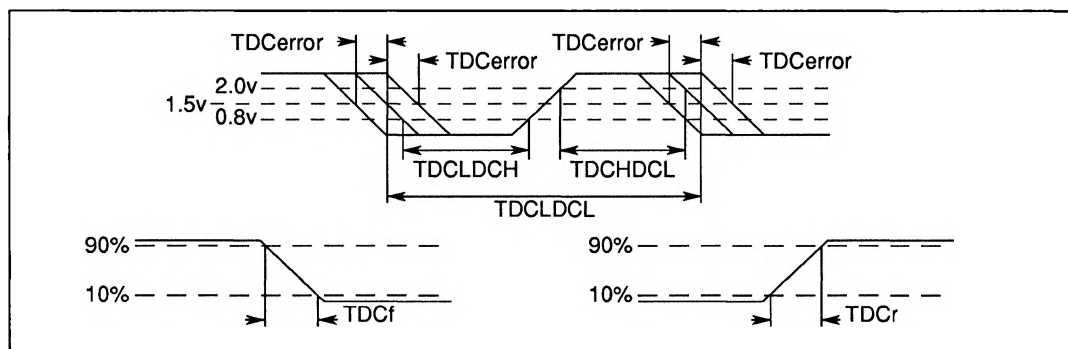

Figure 3.2 ClockIn timing

3.4   Reset

The **Reset** pin can go high with **VCC**, but must at no time exceed the maximum specified voltage for **VIH**. After **VCC** is valid **ClockIn** should be running for a minimum period **TDCVRL** before the end of **Reset**.

Reset initialises the IMS C004 to a state where all link outputs from the switch are disconnected and held low; the control link is then ready to receive a configuration message.

Table 3.2 Reset

SYMBOL	PARAMETER	MIN	NOM	MAX	UNITS	NOTE
TPVRH	Power valid before Reset	10			ms	
TRHRL	Reset pulse width high	8			ClockIn	1
TDCVRL	ClockIn running before Reset end	10			ms	2

Notes

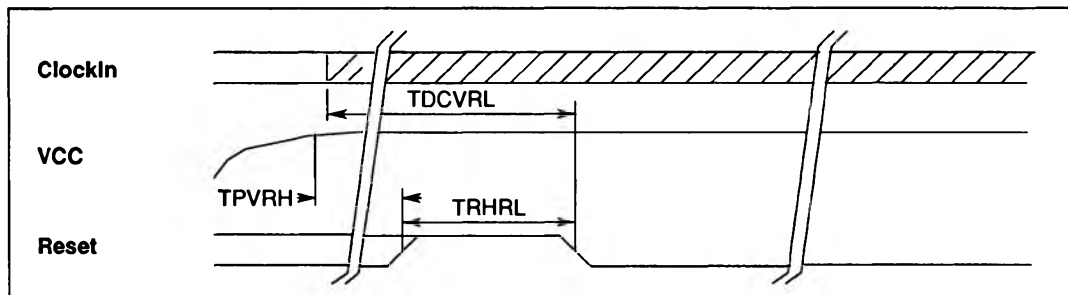1 Full periods of **ClockIn TDCLDCL** required.

2 At power-on reset.

Figure 3.3 Reset Timing

4 Links

INMOS bi-directional serial links provide synchronized communication between INMOS products and with the outside world. Each link comprises an input channel and output channel. A link between two devices is implemented by connecting a link interface on one device to a link interface on the other device. Every byte of data sent on a link is acknowledged on the input of the same link, thus each signal line carries both data and control information.

A receiver can transmit an acknowledge as soon as it starts to receive a data byte. In this way the transmission of an acknowledge can be overlapped with receipt of a data byte to provide continuous transmission of data. This technique is fully compatible with all other INMOS transputer family links.

The quiescent state of a link output is low. Each data byte is transmitted as a high start bit followed by a one bit followed by eight data bits followed by a low stop bit. The least significant bit of data is transmitted first. After transmitting a data byte the sender waits for the acknowledge, which consists of a high start bit followed by a zero bit. The acknowledge signifies that the receiving link is able to receive another byte.

Links are not synchronised with **ClockIn** and are insensitive to its phase. Thus links from independently clocked systems may communicate, providing only that the clocks are nominally identical and within specification.

Links are TTL compatible and intended to be used in electrically quiet environments, between devices on a single printed circuit board or between two boards via a backplane. Direct connection may be made between devices separated by a distance of less than 300 millimetres. For longer distances a matched 100 ohm transmission line should be used with series matching resistors **RM**. When this is done the line delay should be less than 0.4 bit time to ensure that the reflection returns before the next data bit is sent.

Buffers may be used for very long transmissions. If so, their overall propagation delay should be stable within the skew tolerance of the link, although the absolute value of the delay is immaterial.

The IMS C004 links support the standard INMOS communication speed of 10 Mbits/sec. In addition they can be used at 20 Mbits/sec. When the **LinkSpeed** pin is low, all links operate at the standard 10 Mbits/sec; when high they operate at 20 Mbits/sec.

A single IMS C004 inserted between two transputers which fully implement overlapped acknowledges will cause some reduction in data bandwidth, see table 4.2 and figure 4.7.
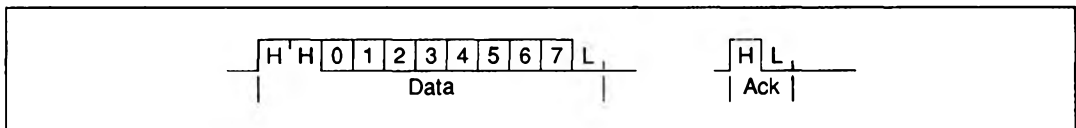

Figure 4.1 IMS C004 link data and acknowledge packets

Table 4.1 Link

SYMBOL	PARAMETER		MIN	NOM	MAX	UNITS	NOTE
TJQr	LinkOut rise time				20	ns	1
TJQf	LinkOut fall time				10	ns	1
TJDr	LinkIn rise time				20	ns	1
TJDf	LinkIn fall time				20	ns	1
TJQJD	Buffered edge delay		0			ns	
TJBskew	Variation in TJQJD	20 Mbits/s			3	ns	2
		10 Mbits/s			10	ns	2
CLIZ	LinkIn capacitance	@ f=1MHz			7	pF	1
CLL	LinkOut load capacitance				50	pF	
RM	Series resistor for 100Ω transmission line			56		ohms	

Notes

1 These paramters are sampled, but are not 100% tested.

2 This is the variation in the total delay through buffers, transmission lines, differential receivers etc., caused by such things as short term variation in supply voltages and differences in delays for rising and falling edges.
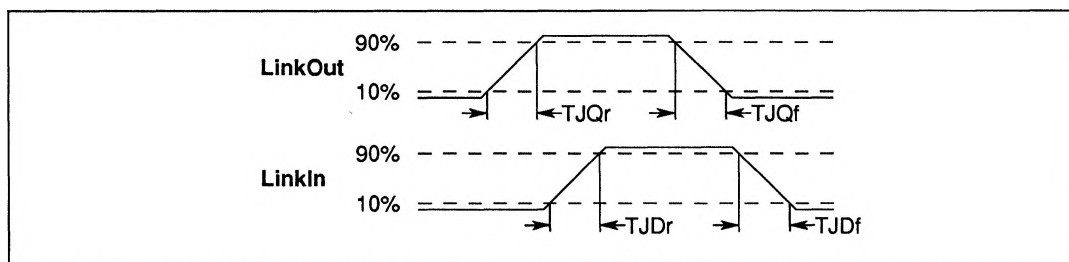

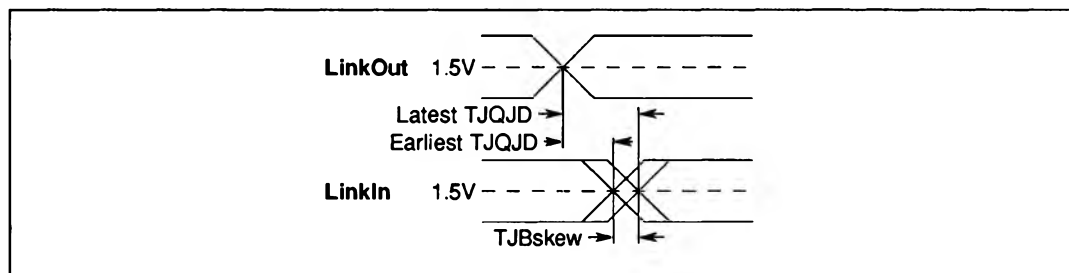Figure 4.2 IMS C004 link timing

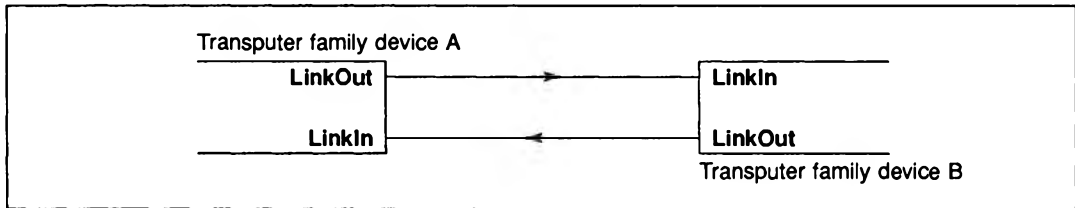Figure 4.3 IMS C004 buffered link timing
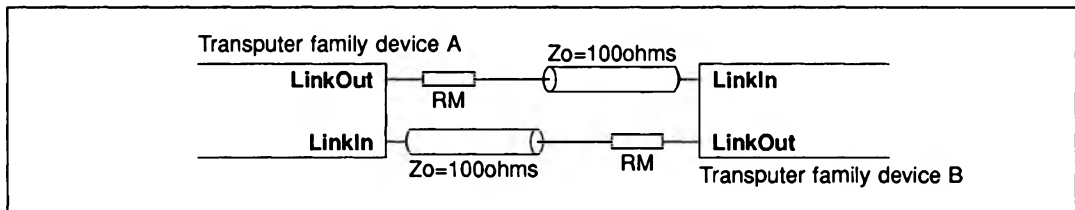
Figure 4.4 IMS C004 Links directly connected

Figure 4.5 IMS C004 Links connected by transmission line

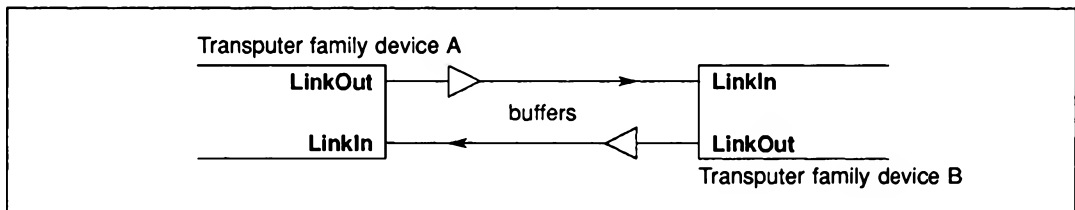

Figure 4.6 IMS C004 Links connected by buffers

Table 4.2 T800 links data transfer rate at 20 Mbits/sec

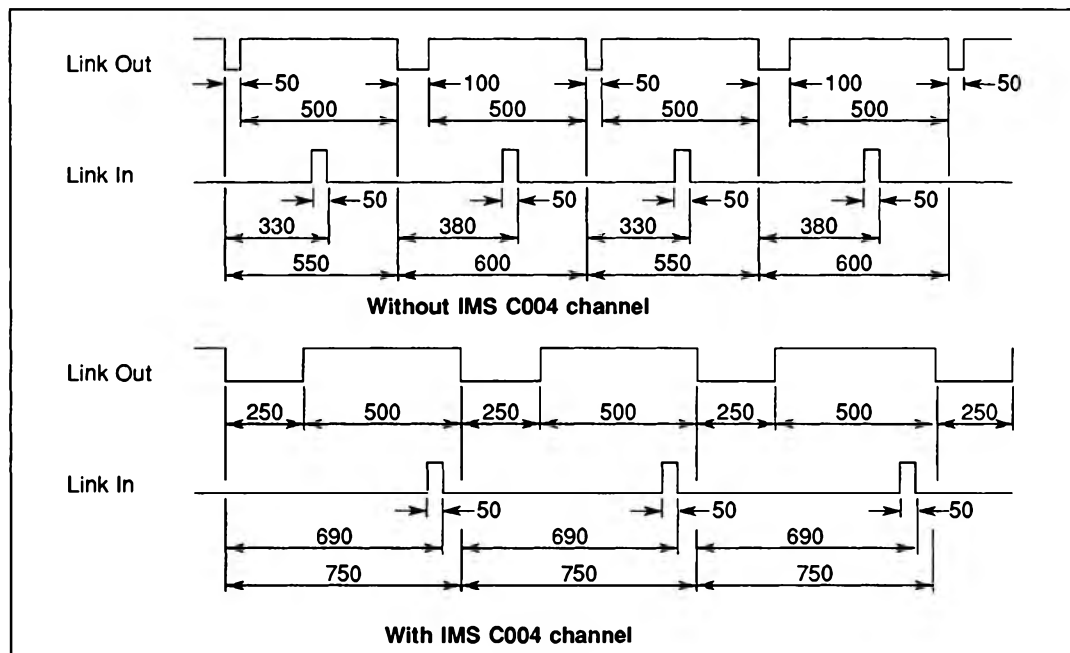|	Without C004	With C004	Degradation
Unidirectional	1.7	1.3	25%
Bidirectional	2.3	2.1	10%

Figure 4.7 IMS C004 link timing

Notes

1 All values are in ns.

2 Timing values shown are for links at 20 Mbits/sec.

5   Switch implementation

The IMS C004 is internally organised as a set of thirtytwo 32-to-1 multiplexors. Each multiplexor has associated with it a six bit latch, five bits of which select one input as the source of data for the corresponding output. The sixth bit is used to connect and disconnect the output. These latches can be read and written by messages sent on the configuration link via **ConfigLinkIn** and **ConfigLinkOut**.

The output of each multiplexor is synchronised with an internal high speed clock and regenerated at the output pad. This synchronisation introduces, on average, a 1.75 bit time delay on the signal. As the signal is not electrically degraded in passing through the switch, it is possible to form links through an arbitrary number of link switches.

Each input and output is identified by a number in the range 0 to 31. A configuration message consisting of one, two or three bytes is transmitted on the configuration link. The configuration messages sent to the switch on this link are shown in table 5.1. If an unspecified configuration message is used, the effect of it is undefined.

Table 5.1 IMS C004 configuration messages

Configuration Message	Function
[0] [input] [output]	Connects **input** to **output**.
[1] [link1] [link2]	Connects **link1** to **link2** by connecting the input of **link1** to the output of **link2** and the input of **link2** to the output of **link1**.
[2] [output]	Enquires which input the **output** is connected to. The IMS C004 responds with the input. The most signifigant bit of this byte indicates whether the output is connected (bit set high) or disconnected (bit set low).
[3]	This command byte must be sent at the end of every configuration sequence which sets up a connection. The IMS C004 is then ready to accept data on the connected inputs.
[4]	Resets the switch. All outputs are disconnected and held low. This also happens when **Reset** is applied to the IMS C004.
[5] [output]	Output **output** is disconnected and held low.
[6] [link1] [link2]	Disconnects the output of **link1** and the output of **link2**.

6 Applications

6.1 Link switching

The IMS C004 provides full switching capabilities between 32 INMOS links. It can also be used as a component of a larger link switch. For example, three IMS C004's can be connected together to produce a 48 way switch, as shown in figure 6.1. This technique can be extended to the switch shown in figure 6.2.

A fully connected network of 32 INMOS transputers (one in which all four links are used on every transputer) can be completely configured using just four IMS C004's. Figure 6.5 shows the connected transputer network.

In these diagrams each link line shown represents a unidirectional link; i.e. one output to one input. Where a number is also given, that denotes the number of lines.

6.2 Multiple IMS C004 control

Many systems require a number of IMS C004's, each configured via its own configuration link. A simple method of implementing this uses a master IMS C004, as shown in figure 6.3. One of the transputer links is used to configure the master link switch, whilst another transputer link is multiplexed via the master to send configuration messages to any of the other 31 IMS C004 links.

6.3 Bidirectional exchange

Use of the IMS C004 is not restricted to computer configuration applications. The ability to change the switch setting dynamically enables it to be used as a general purpose message router. This may, of course, also find applications in computing with the emergence of the new generation of supercomputers, but a more widespread use may be found as a communication exchange.

In the application shown in figure 6.4, a message into the exchange must be preceded by a destination token *dest*. When this message is passed, the destination token is replaced with a source token so that the receiver knows where the message has come from. The **in.out** device in the diagram and the controller can be implemented easily with a transputer, and the link protocol for establishing communication with these devices can be interfaced with INMOS link adaptors. All messages from **rx[i]** are preceded by the destination output *dest*. On receipt of such a message the **in.out** device requests the controller to connect a bidirectional link path to *dest*. The controller determines what is currently connected to each end of the proposed link. When both ends are free it sets up the IMS C004 and informs both ends of the new link. Note that in this network two channels are placed on each IMS C004 link, one for each direction.

6.4 Bus systems

The IMS C004 can be used in conjunction with the INMOS IMS C011/C012 link adaptors to provide a flexible means of connecting conventional bus based microprocessor systems.
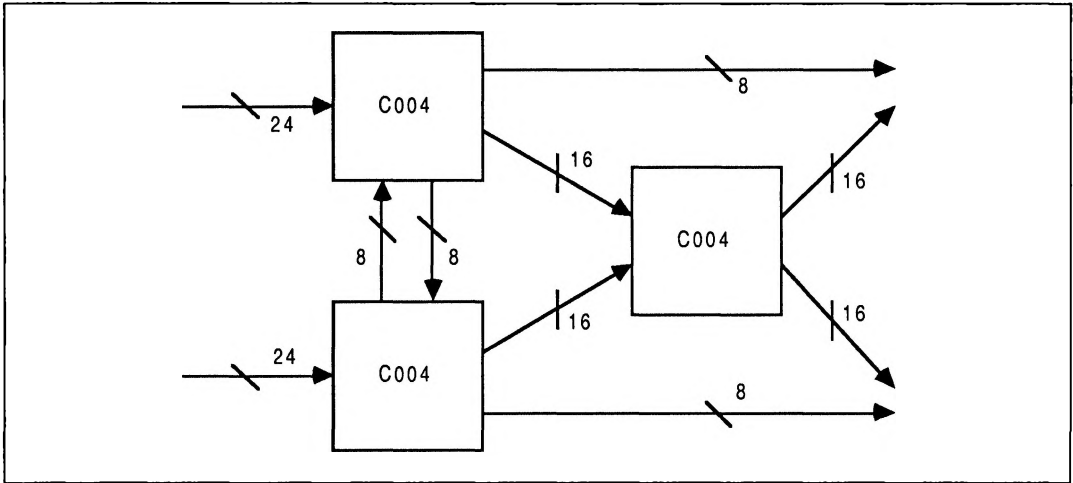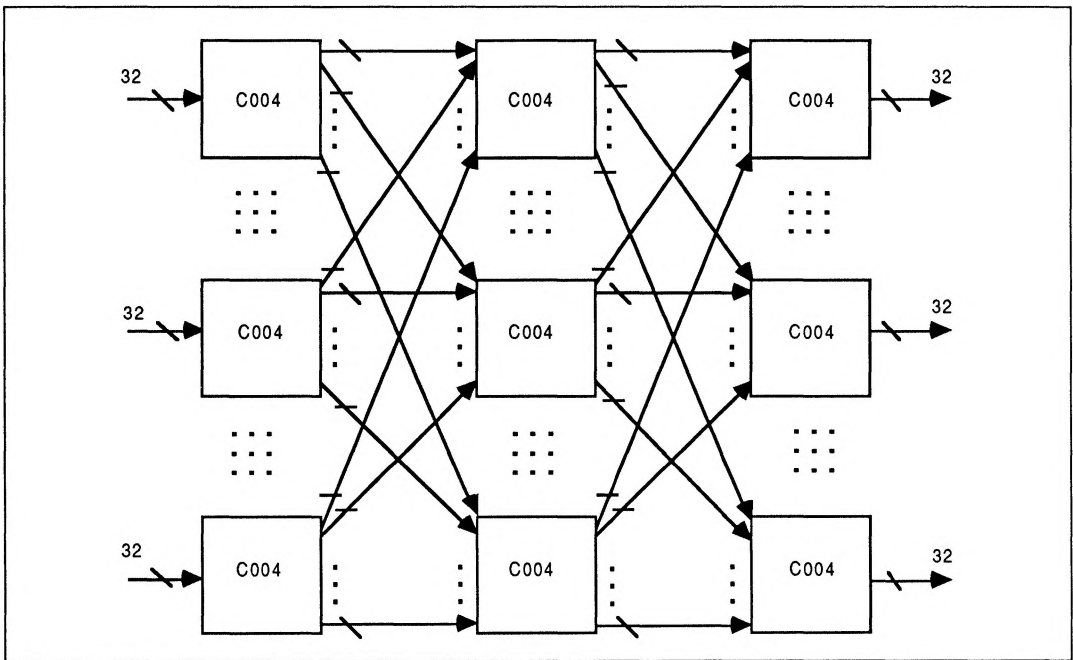
Figure 6.1 48 way link switch
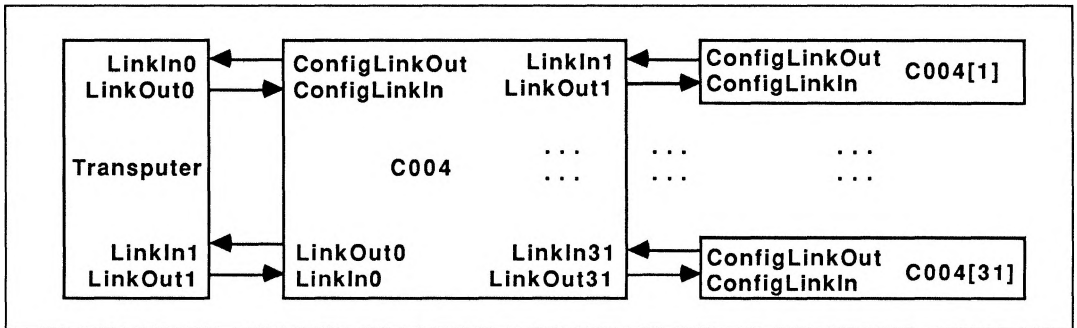

Figure 6.2 Generalised link switch

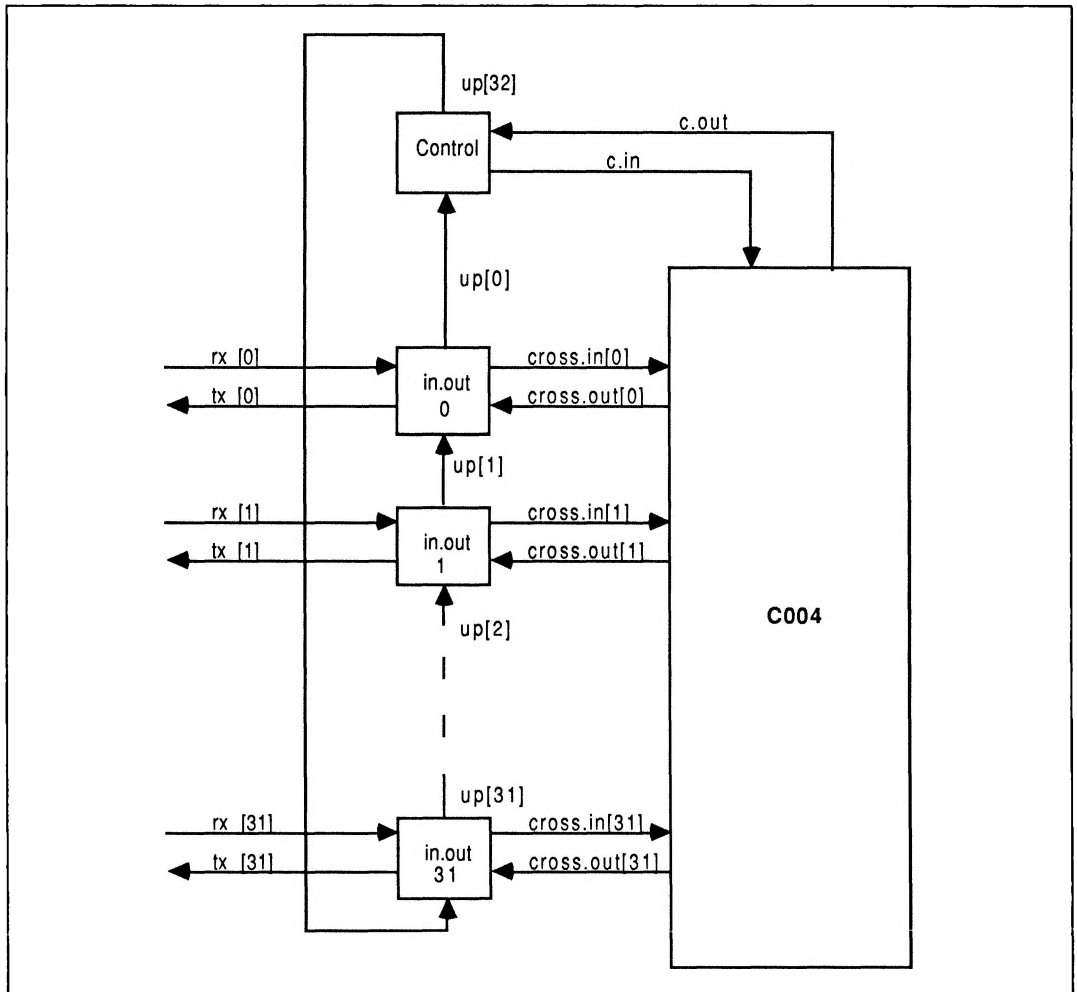Figure 6.3 Multiple IMS C004 controller
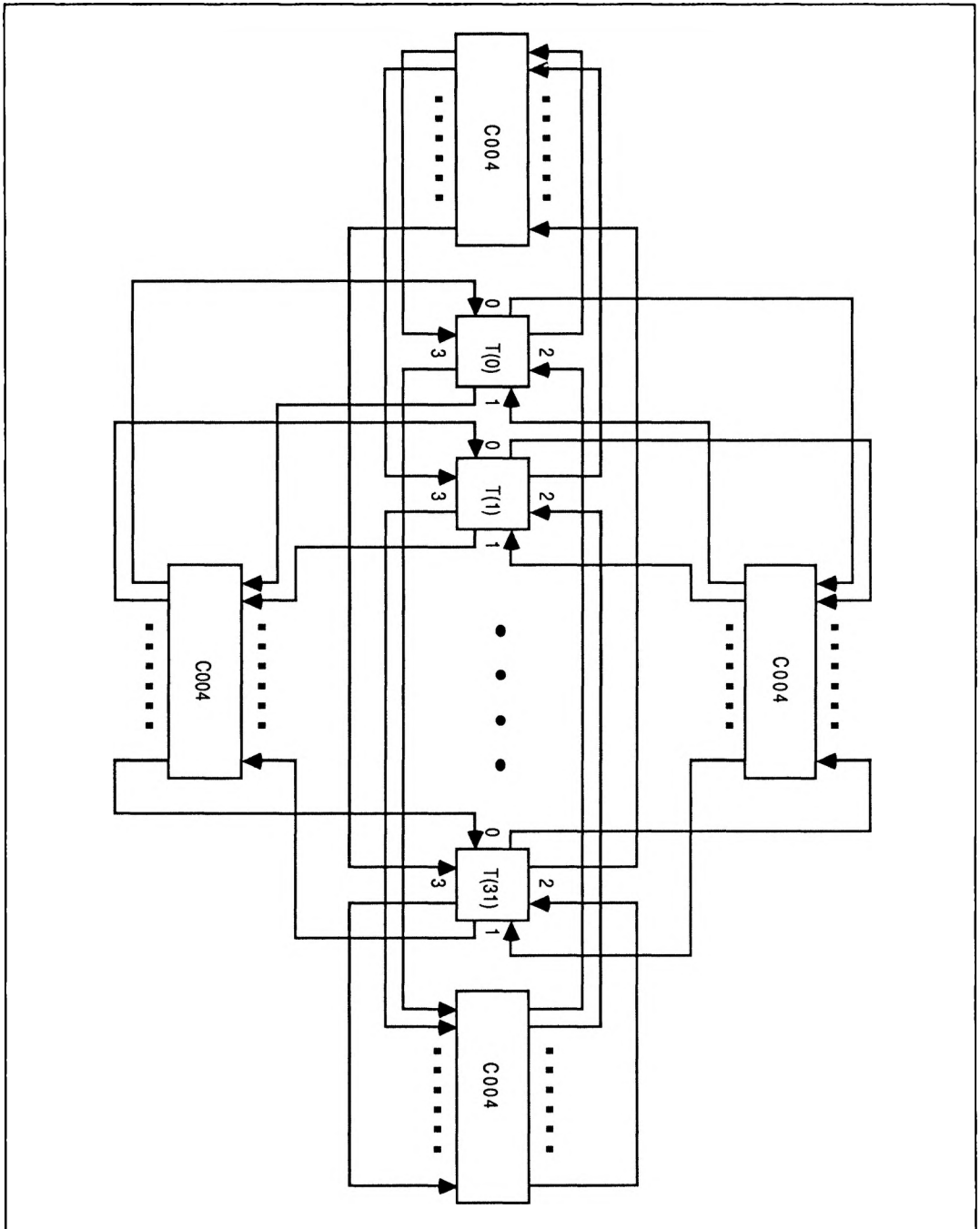

Figure 6.4 32 way bidirectional exchange

Figure 6.5 Complete connectivity of a transputer network using four IMS C004's

7 Electrical specifications

7.1 DC electrical characteristics

Table 7.1 Absolute maximum ratings

SYMBOL	PARAMETER	MIN	MAX	UNITS	NOTE
VCC	DC supply voltage	0	7.0	V	1,2,3
VI, VO	Voltage on input and output pins	-0.5	VCC+0.5	V	1,2,3
II	Input current		±25	mA	4
OSCT	Output short circuit time (one pin)		1	s	2
TS	Storage temperature	-65	150	°C	2
TA	Ambient temperature under bias	-55	125	°C	2
PDmax	Maximum allowable dissipation		2	W	

Notes

1 All voltages are with respect to **GND**.

2 This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operating sections of this specification is not implied. Stresses greater than those listed may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

3 This device contains circuitry to protect the inputs against damage caused by high static voltages or electrical fields. However, it is advised that normal precautions be taken to avoid application of any voltage higher than the absolute maximum rated voltages to this high impedance circuit. Unused inputs should be tied to an appropriate logic level such as **VCC** or **GND**.

4 The input current applies to any input or output pin and applies when the voltage on the pin is between **GND** and **VCC**.

Table 7.2 Operating conditions

SYMBOL	PARAMETER	MIN	MAX	UNITS	NOTE
VCC	DC supply voltage	4.75	5.25	V	1
VI, VO	Input or output voltage	0	VCC	V	1,2
CL	Load capacitance on any pin		60	pF	
TA	Operating temperature range IMS C004-S	0	70	°C	3
TA	Operating temperature range IMS C004-M	-55	125	°C	3

Notes

1 All voltages are with respect to **GND**.

2 Excursions beyond the supplies are permitted but not recommended; see DC characteristics.

3 Air flow rate 400 linear ft/min transverse air flow.

Table 7.3 DC characteristics

SYMBOL	PARAMETER		MIN	MAX	UNITS	NOTE
VIH	High level input voltage		2.0	VCC+0.5	V	1,2
VIL	Low level input voltage'		-0.5	0.8	V	1,2
II	Input current	@ GND<VI<VCC		±10	μA	1,2
VOH	Output high voltage	@ IOH=2mA	VCC-1		V	1,2
VOL	Output low voltage	@ IOL=4mA		0.4	V	1,2
IOS	Output short circuit current @ GND<VO<VCC		36	65	mA	1,2,3,6
			65	100	mA	1,2,4,6
PD	Power dissipation			1.5	W	2,5
CIN	Input capacitance	@ f=1MHz		7	pF	6
COZ	Output capacitance	@ f=1MHz		10	pF	6

Notes

1 All voltages are with respect to **GND**.

2 Parameters for IMS C004-S measured at 4.75V<**VCC**<5.25V and 0°C<**TA**<70°C.
Input clock frequency = 5 MHz.

3 Current sourced from non-link outputs.

4 Current sourced from link outputs.

5 Power dissipation varies with output loading and with the number of links active.

6 This parameter is sampled and not 100% tested.

7.2 Equivalent circuits

Load for:	R1	R2	Equivalent load:
Link outputs	1K96	47K	1 Schottky TTL input
Other outputs	970R	24K	2 Schottky TTL inputs

Diodes are 1N916
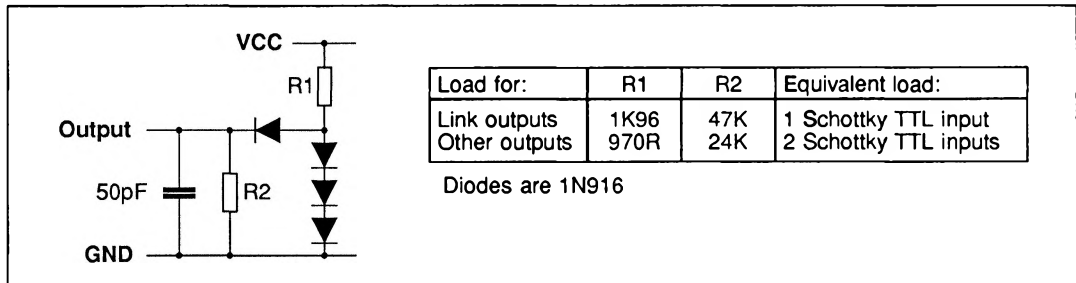
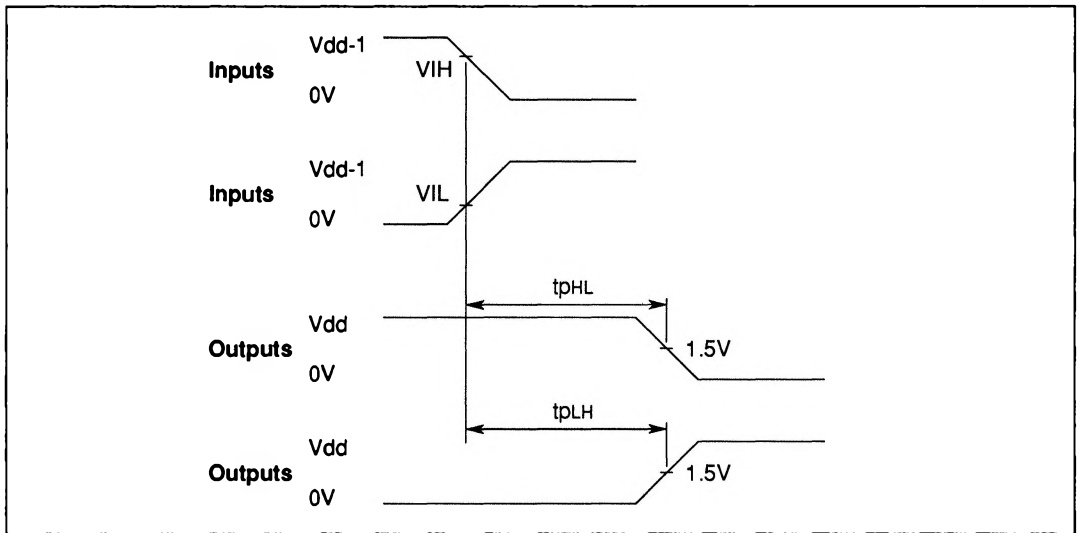Figure 7.1 Load circuit for AC measurements

Figure 7.2 AC measurements timing waveforms

7.3   AC timing characteristics
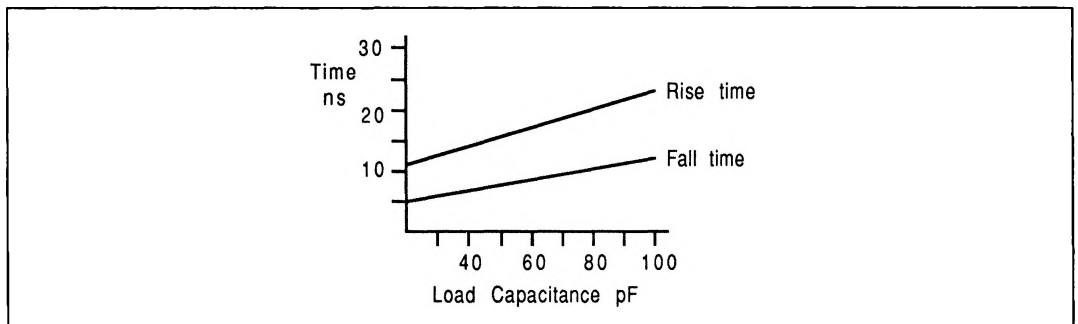
Figure 7.3 Typical link rise/fall times

7.4   Power rating

Internal power dissipation P_{INT} of transputer and peripheral chips depends on **VCC**, as shown in figure 7.4. P_{INT} is substantially independent of temperature.

Total power dissipation P_D of the chip is

$$P_D = P_{INT} + P_{IO}$$

where P_{IO} is the power dissipation in the input and output pins; this is application dependent.

Internal working temperature T_J of the chip is

$$T_J = T_A + \theta J_A * P_D$$

where T_A is the external ambient temperature in °C and θJ_A is the junction-to-ambient thermal resistance in °C/W. θJ_A for each package is given in the Packaging Specifications section.

Figure 7.4 IMS C004 internal power dissipation vs VCC

8 Package specifications

8.1 84 pin grid array package
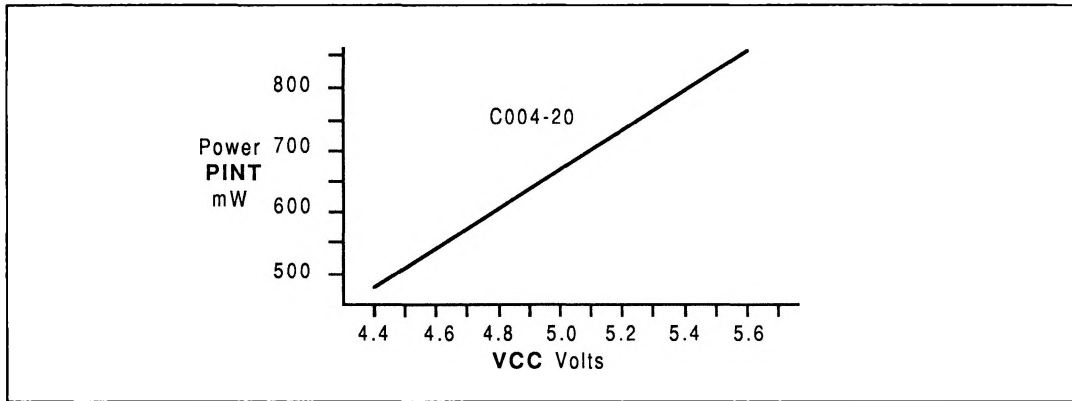
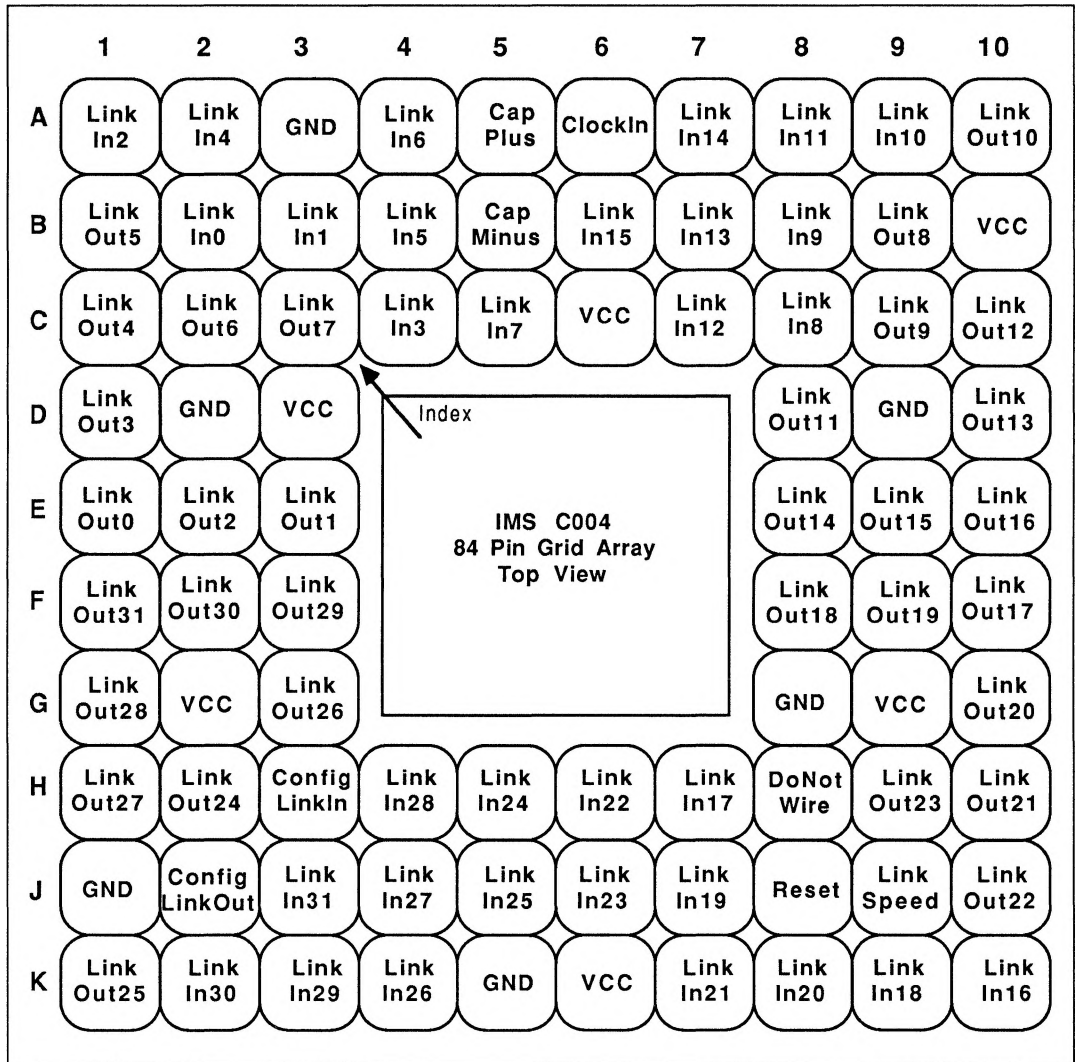|	1	2	3	4	5	6	7	8	9	10
A	Link In2	Link In4	GND	Link In6	Cap Plus	ClockIn	Link In14	Link In11	Link In10	Link Out10
B	Link Out5	Link In0	Link In1	Link In5	Cap Minus	Link In15	Link In13	Link In9	Link Out8	VCC
C	Link Out4	Link Out6	Link Out7	Link In3	Link In7	VCC	Link In12	Link In8	Link Out9	Link Out12
D	Link Out3	GND	VCC					Link Out11	GND	Link Out13
E	Link Out0	Link Out2	Link Out1		IMS C004 84 Pin Grid Array Top View			Link Out14	Link Out15	Link Out16
F	Link Out31	Link Out30	Link Out29					Link Out18	Link Out19	Link Out17
G	Link Out28	VCC	Link Out26					GND	VCC	Link Out20
H	Link Out27	Link Out24	Config LinkIn	Link In28	Link In24	Link In22	Link In17	DoNot Wire	Link Out23	Link Out21
J	GND	Config LinkOut	Link In31	Link In27	Link In25	Link In23	Link In19	Reset	Link Speed	Link Out22
K	Link Out25	Link In30	Link In29	Link In26	GND	VCC	Link In21	Link In20	Link In18	Link In16

Index

Figure 8.1 IMS C004 84 pin grid array package pinout
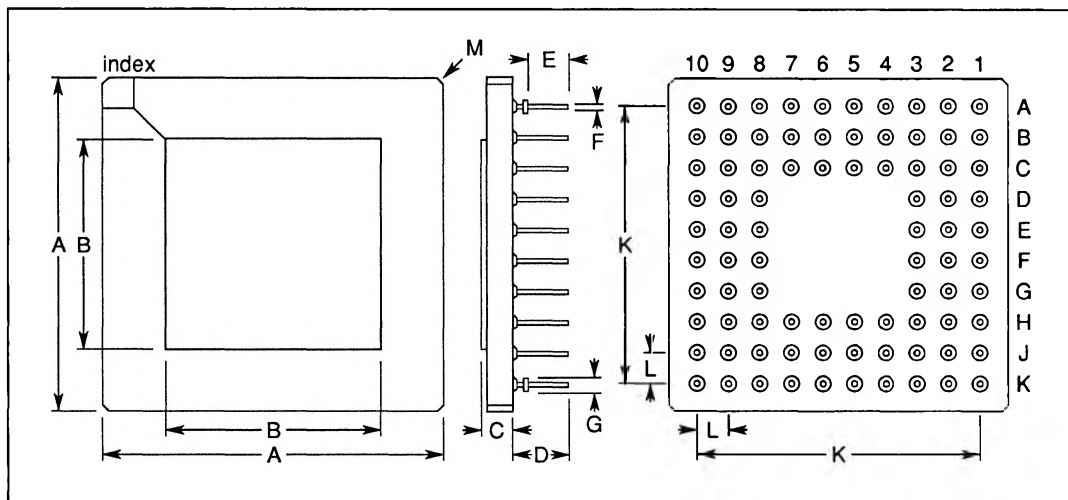
Figure 8.2 84 pin grid array package dimensions

Table 8.1 84 pin grid array package dimensions

	Millimetres		Inches		
DIM	NOM	TOL	NOM	TOL	Notes
A	26.924	±0.254	1.060	±0.010	
B	17.019	±0.127	0.670	±0.005	
C	2.456	±0.278	0.097	±0.011	
D	4.572	±0.127	0.180	±0.005	
E	3.302	±0.127	0.130	±0.005	
F	0.457	±0.025	0.018	±0.002	Pin diameter
G	1.143	±0.127	0.045	±0.005	Flange diameter
K	22.860	±0.127	0.900	±0.005	
L	2.540	±0.127	0.100	±0.005	
M	0.508		0.020		Chamfer

Package weight is approximately 7.2 grams

Table 8.2 84 pin grid array package junction to ambient thermal resistance

SYMBOL	PARAMETER	MIN	NOM	MAX	UNITS	NOTE
θJA	At 400 linear ft/min transverse air flow			35	°C/W	

8.2   84 lead quad cerpack package

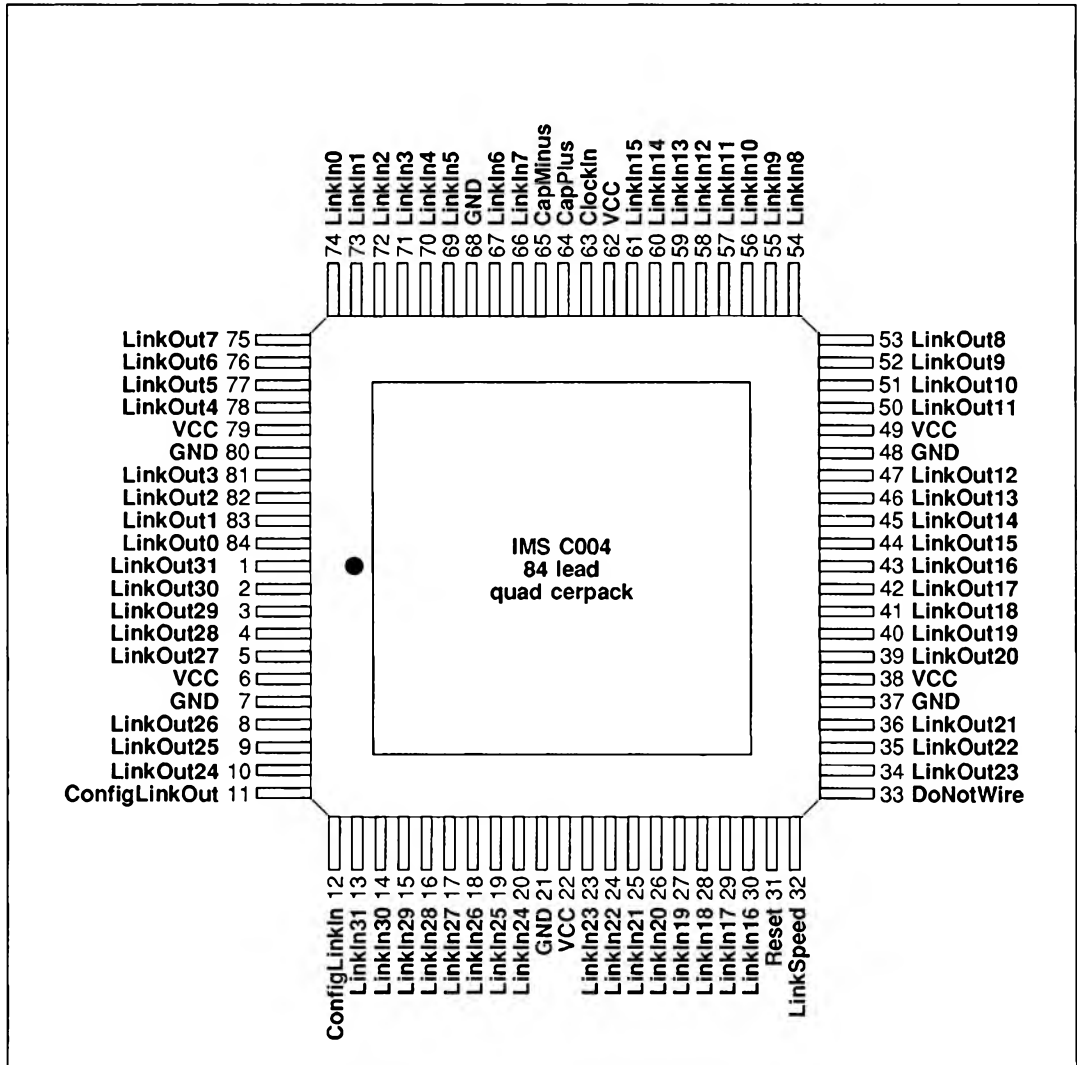The leads are unformed to allow the user to form them to specific requirements.

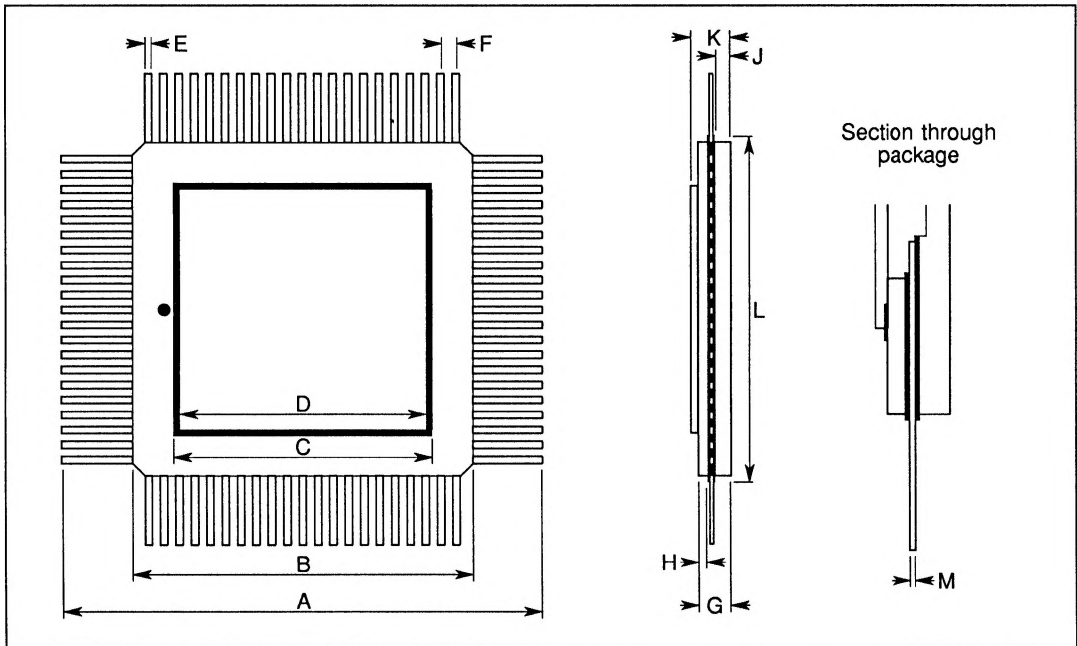Figure 8.3 IMS C004 84 lead quad cerpack package pinout

Figure 8.4 84 lead quad cerpack package dimensions

DIM	Millimetres		Inches		Notes
	NOM	TOL	NOM	TOL	
A	38.100	±0.508	1.500	±0.020	
B	26.924	±0.305	1.060	±0.012	
C	20.574	±0.203	0.810	±0.008	
D	19.558	±0.254	0.770	±0.010	
E	0.508		0.020		
F	1.270	±0.051	0.050	±0.002	
G	2.489	±0.305	0.098	±0.012	
H	0.635	±0.076	0.025	±0.003	
J	1.143	±0.102	0.045	±0.004	
K	3.099		0.122		Max.
L	27.940		1.100		Max.
M	0.178	±0.025	0.007	±0.001	

Table 8.3 84 lead quad cerpack package dimensions

9 Ordering

This section indicates the designation of package selections for the IMS C004. Speed of **ClockIn** is 5 MHz for all parts.

For availability contact local INMOS sales office or authorised distributor.

Table 9.1 IMS C004 ordering details

INMOS designation	Package
IMS C004-G20S	Ceramic Pin Grid Array
IMS C004-G20M	Ceramic Pin Grid Array MIL Spec
IMS C004-Q20M	Quad Cerpack MIL Spec